

## MAT 705, Calculus on Manifolds, Fall 2017

TR 9:30-10:50, Carnegie 109

**Instructor:** Loredana Lanzani, 313G Carnegie, phone 443-1496, e-mail: llanzani@syr.edu  
**Office hours:** W 1:00-2:00pm, R 4:00-5:00pm or by appointment.

**Topics:** differentiable manifolds, differential forms, exterior calculus, integration over manifolds, Stokes' theorem, other topics.

**Prerequisites:** MAT 602, MAT 632, MAT 661.

**Textbook:** Instructor's notes based upon material taken from (but not limited to): *Analysis on Manifolds*, by James R. Munkres, Westview Press 1991; *An introduction to differentiable manifolds and Riemannian Geometry*, by William M. Boothby, Academic Press 1986; *Holomorphic functions and integral representations in several complex variables* by R. Michael Range, Springer 1998.

**Grading:** Students will be expected to make short presentations on topics assigned by the instructor.

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in MySlice under Student Services>Enrollment>My Religious Observances, from the first day of class until the end of the second week of classes.

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## **MAT705 Fall 2017 Final assignments and presentations schedule**

### **• *Instructions:***

- Each enrolled student will write a paper (up to 10 pages for a single paper or up to 20 pages for a joint paper by two persons) and make a 35-40min presentation to the class and/or to the professor.
- **All papers are due Monday Nov. 28** (e-mail an e-scan to professor who will post on BlackBoard for everyone to access) (pdf)
- Topics and assignments listed below. Study material for Topics 1, 2 and 3 from J. R. Munkres *Analysis on Manifolds* (sections and pages indicated below).
- You may borrow a copy of the book from Prof. Lanzani and make photocopies of relevant pages.
- Feel free to exchange your assignment with another student's (who will agree to do so) based on interest and availability. **Let me know asap if you have switched assignment with another student's.**
- **Presentations calendar:**
  - Tuesday Nov. 28 (2 persons; 35-40min each);
  - Thursday Nov. 30 (2 persons; 35-40min each)
  - Thursday Dec. 7 (2 persons; 35-40min each);
  - **Tuesday Dec. 12 1:00pm in CARN 109** (1 person; 35-40min).

**Note: Class cancelled Tuesday Dec. 5 (we meet Dec. 12 instead).**



• **Presentation topics and assignments:**

- **Topic 1: Wedge product. Assigned to: Erin and Stephen** (write joint paper, up to 20pp total; split presentation 35-40min each).

Content:

Thm on existence; uniqueness and properties of wedge product: Munkres Thm. 28.1 pp. 237-243, plus exercises #1, 2, 5

(include pb. 5 in the proof of Thm 28.1) and 6, pp. 243-244.

**Presentation schedule: Tuesday Nov. 28.**

- **Topic 2: Exterior derivative and pull-back. Assigned to: Fabian and Paula** (write joint paper, up to 20pp total; split presentation 35-40min each).

Content:

Theorem on exterior derivative (existence; uniqueness and properties): Munkres Thm. 30.4 pp. 256-259 and exercise #2 p. 260, plus correlation with div-curl-grad (Thm. 31.1 and Thm. 31.2 pp. 263-265: fill-in missing details).

Theorem on pull-back representation: Munkres Thm. 32.2 pp. 269-270 and exercise #4 p. 273.

pp. 256-273

Theorem on invariance of exterior derivative: Munkres Thm. 32.3 pp. 270-272 and exercises #5.

If you have time, also try exercise #6, p. 273.

**Presentation schedule: Thursday Nov. 30.**

Paper due:

Monday Nov. 27

- **Topic 3: The classical theorems of vector integral calculus re-interpreted via differential forms.**



**Assigned to: Erin and Felix** (write joint paper, up to 20pp total; split presentation 35-40min each).

Content:

Gradient thm for 1-manifolds: Munkres Lemma 38.1 pp. 310-311 (proof 2 only). Thm 38.2 p. 312.

Divergence thm for  $(n-1)$  manifolds: Munkres pp. 312-319 (in Lemma 38.6 do proof 2 only)

Stokes' thm for 2-manifolds in 3D: Thm 38.9 pp.319-320.

**Presentation schedule: Thursday Dec. 7.**

- **Topic 4: Applications of manifolds to Physics. Assigned to Arthur** (write a paper up to 10pp; give presentation 35-40min)

**Presentation schedule: Thursday Dec. 12.**





# MAT 705 - Calculus on Manifolds

Aug 29

HW: send e-mail with available time-slots on Mondays

A quick review of Multivariable Calc. (Cal III)

$D \subset \mathbb{R}^3$  domain (open & connected),  $\vec{F}(x,y,z) = P(x,y,z)\vec{i} + Q(x,y,z)\vec{j} + R(x,y,z)\vec{k}$  a given vector field (assume as much differentiability as we need)

•  $\text{div } \vec{F} := P_x + Q_y + R_z$  (a scalar fct)

•  $\text{Curl } \vec{F} := \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \partial_x & \partial_y & \partial_z \\ P & Q & R \end{vmatrix} = \vec{i} \partial_y (R_z - Q_z) - \vec{j} (R_x - P_x) + \vec{k} (Q_x - P_y)$   
(= rot  $\vec{F}$ )

• Special Case:  $D \subset \mathbb{R}^2$  &  $\vec{F}(x,y) = P(x,y)\vec{i} + Q(x,y)\vec{j}$ . Then:

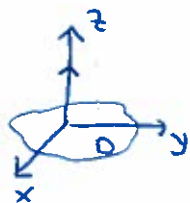


• We may think of  $\vec{F}$  as a vector field in  $\mathbb{R}^3$  by setting  $R(x,y,z) \equiv 0$ .

•  $\text{div } \vec{F} = P_x + Q_y$

•  $\text{Curl } \vec{F} = (Q_x - P_y)\vec{k}$

$\begin{cases} R_y, R_x = 0 & (R=0) \\ Q_z, P_z = 0 & (P, Q \text{ indep of } z) \end{cases}$



## (A) Divergence Thm

$n=k=3$  (see (D) later)

Hypothesis

(H)  $D \subset \mathbb{R}^3$  domain;  $\vec{F} = P(x,y,z)\vec{i} + Q(x,y,z)\vec{j} + R(x,y,z)\vec{k}$

Conclusion

(C)  $\iint_{\text{bd}} \vec{F} \cdot \vec{n} \, dS = \iiint_D \text{div } \vec{F} \, dV$   
outer unit normal vector    surface area element     $dV$  vol. el.  $dx dy dz$

Ex.:

$D = B_1(0) = \{x^2 + y^2 + z^2 < 1\}$

$\text{bd} = S_1^2(0) = \{x^2 + y^2 + z^2 = 1\}$



(B) Stokes' Thm

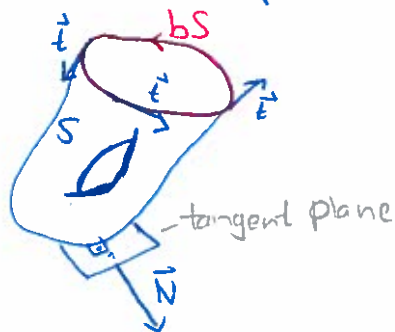
$n=3; k=2$

(H)  $S \subset \mathbb{R}^3$  a given surface with boundary  $bS$ ,  $\vec{F} = P\vec{i} + Q\vec{j} + R\vec{k}$

(C)  $\int_{bS} \vec{F} \cdot \vec{t} ds = \iint_S (\text{Curl } \vec{F}) \cdot \vec{N} dS$

unit tangent vector to  $bS$   
 arc length el. for  $bS$   
 surface area el. for  $S$   
 outer unit normal vector to  $S$   
 $d\omega$

Ex:

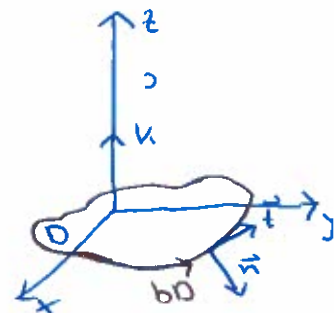


(C) Green's Thm

(H)  $D \subset \mathbb{R}^2$  a given domain,  $\vec{F} = P(x,y)\vec{i} + Q(x,y)\vec{j}$

(C)  $\int_{bD} P(x,y) dx + Q(x,y) dy = \iint_D (Q_x - P_y) dA$

area element  $dx dy$



Alternate formulations of (C)

(a)  $\int_{bD} \vec{F} \cdot \vec{n} ds = \iint_D \text{div } \vec{F} dA$

outer arc length el. for  $bD$  with normal vector to  $bD$   
 area element

(b)  $\int_{bD} \vec{F} \cdot \vec{t} ds = \iint_D (\text{Curl } \vec{F}) \cdot \vec{k} dA$

unit tangent vector to  $bD$   
 area el.  $dx dy$

Connections between (A), (B) and (C)

- Green (formulation (b)) is a special case of Stokes with  $S=D$  so that  $\vec{N} = \vec{k}$  ("flat" case)
- Green (formulation (a)) is a 2-dim analog of Divergence Thm:
  - $dV$  in  $\mathbb{R}^3$  is analog to  $dA$  in  $\mathbb{R}^2$  ("Lebesgue measure")
  - $dS$  for surface in  $\mathbb{R}^3$  is analog of  $ds$  for curve in  $\mathbb{R}^2$  ("Induced Leb. measure")

As we shall see sometime ~ Nov, each of (A), (B), (C) is a special case of:

(10) Generalized Stokes' Thm:

(H)  $M \subset \mathbb{R}^n$  is a  $k$ -dim. manifold (any  $n \geq 2, 1 \leq k \leq n$ ; integers) with boundary  $bM$

• given a differential form  $w$  in  $\mathbb{R}^n$  of degree  $k-1$  (a " $k-1$ -form", for short)

(C)  $\int_{bM} w = \iint_M dw$ , where  $dw =$  the differential of  $w$ .

Manifolds in  $\mathbb{R}^n$

• Manifolds without boundary

Assumptions: •  $n, k \in \mathbb{Z}^+$ ;  $1 \leq k \leq n$ ;  $r \in \mathbb{Z}^+$   
(Given)

•  $M \subset \mathbb{R}^n$  (a subset)

Def.: We say that  $M$  is a (differentiable)  $k$ -manifold of Class  $C^r$  without boundary in  $\mathbb{R}^n$  if  $\forall p \in M$ :

- $\exists$  set  $p \in V_p \subset M$  that is open in  $M$  (i.e.  $V_p = \tilde{V} \cap M, \exists \tilde{V}$  open set in  $\mathbb{R}^n$ )
- $\exists$  open set  $U_p \subset \mathbb{R}^k$
- $\exists$  map  $d: U_p \rightarrow V_p$

$x = (x_1, \dots, x_k) \mapsto d(x) = (d_1(x), \dots, d_n(x))$  s.t.

(0)  $d$  is one-to-one & onto :  $U_p \rightarrow V_p$

(1)  $d$  is of class  $C^r$  ( i.e.  $\frac{\partial^L d_j}{\partial x_1^{l_1} \dots \partial x_k^{l_k}}$  ( $0 \leq L \leq r$ ,  $l_1 + \dots + l_k = L$ )  $\forall j=1, \dots, n$ ) are all continuous

(2)  $d^{-1}: V_p \rightarrow U_p$  is continuous

(3)  $Dd(x) = \begin{pmatrix} \frac{\partial d_1}{\partial x_1} & \dots & \frac{\partial d_1}{\partial x_k} \\ \frac{\partial d_2}{\partial x_1} & \dots & \frac{\partial d_2}{\partial x_k} \\ \vdots & & \vdots \\ \frac{\partial d_n}{\partial x_1} & \dots & \frac{\partial d_n}{\partial x_k} \end{pmatrix}$   $n \times k$  matrix

has maximal rank  $\forall x \in U_p$ . max. rank =  $k$

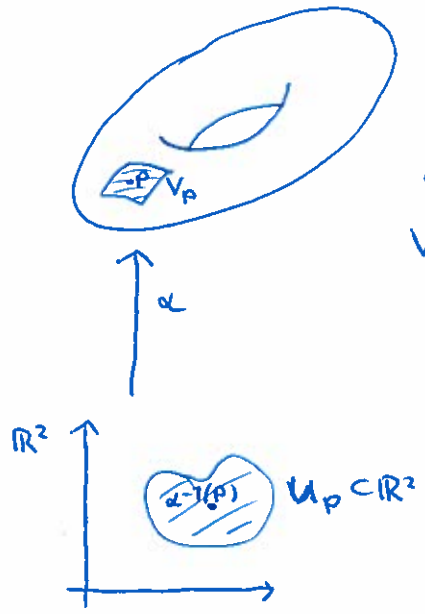
ie.  $\exists$   $k \times k$  minor of  $D\alpha(x)$  whose determinant is  $\neq 0$ .

We call such map  $\alpha$  a coordinate chart for  $M$ .

HW: reading assignment (next week: no classes)  $\rightarrow$  BB

$\alpha$  is a coordinate patch.

Ex:  $M = \text{torus in } \mathbb{R}^3$



$$V = \mathbb{R}^2 \cap B_r(p)$$

$$V = V(p, \alpha) \quad \text{Ball in } \mathbb{R}^2$$

$$\{(x_1 - p_1)^2 + (x_2 - p_2)^2 + (x_3 - p_3)^2 < r^2\}$$

Significance of "Maximal Rank" condition for  $D\alpha$

Example

(i)  $k=1$ ; any  $n$  Then  $U_p = (a, b) \subset \mathbb{R} \ni t$

$$\alpha(t) = (\alpha_1(t), \dots, \alpha_n(t))$$

$$D\alpha(t) = \begin{pmatrix} \alpha_1'(t) \\ \vdots \\ \alpha_n'(t) \end{pmatrix} \quad n \times 1$$

maximal rank = rank = 1  $\forall t \exists j \in \{1, \dots, n\}$  s.t.  $\alpha_j'(t) \neq 0$

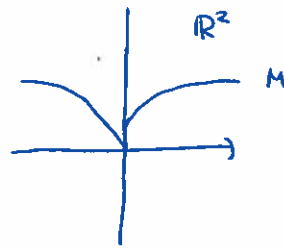
Ex:  $k=1, n=2. \alpha: \mathbb{R} \rightarrow \mathbb{R}^2, \alpha(t) = (t^3, t^2); M = \alpha(\mathbb{R})$ .

- $\alpha$  class  $C^\infty$  (polynomial)
- 1-1; onto (check!)
- $\alpha^{-1}$  is continuous (check!)

onto of map  $\mathbb{R} \rightarrow \alpha(\mathbb{R}) = M$

But  $D\alpha(t)$  does not have rank = 1 at every  $t \in \mathbb{R}$   
 $D\alpha(t) = (3t^2, 2t)$  so  $D\alpha(0) = (0, 0) \therefore$

it turns out that  $M$  has a cusp



Ex:  $k=1, n=2; M=\beta(\mathbb{R})$

$$\beta(t) = (t^3, |t^3|)$$

- $\beta$  of class  $C^2$  (check!)
- $\beta^{-1}$  is continuous (check!)
- $D\beta(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  again, rank not maximal.



$$\frac{D\beta(t)}{|D\beta(t)|} = \vec{e}(t) \quad \text{so if rank not maximal at } t_0, \vec{e}(t_0) \text{ "discontinuous"}$$

Comparing "discontinuity" of  $\vec{e}(0)$ : Cusp vs Corner:

• Cusp:  $\alpha(t) = (t^2, 2t) = t(3t, 2)$

$$|D\alpha(t)| = |t| \sqrt{9t^2 + 4} \quad \text{note: } \sqrt{9t^2 + 4} \approx 2$$

$$\tau(t) \approx \frac{t}{|t|} (3t, 2) = \text{sign}(t) (3t, 2)$$

$$\rightarrow \tau(t) \approx (\underbrace{3t \text{ sign}(t)}, \underbrace{2 \text{ sign}(t)})$$

continuous at  $t=0$ , discontinuous at  $t=0$  not of class  $C^1$

• Corner:  $\beta(t) = (t^3, |t^3|)$

$$D\beta(t) = (3t^2, 3t^2 \text{ sign}(t)) = 3t^2 (1, \text{sign}(t))$$

$$|D\beta(t)| = 3t^2 \sqrt{2}; \quad \vec{e}(t) = \frac{1}{\sqrt{2}} (1, \text{sign}(t))$$

$C^\infty$ !! discant. at 0

Failure of maximal rank

$k=2$ , any  $n$

$$D\alpha(x) = \begin{pmatrix} \frac{\partial \alpha_1}{\partial x_1} & \frac{\partial \alpha_1}{\partial x_2} \\ \vdots & \vdots \\ \frac{\partial \alpha_n}{\partial x_1} & \frac{\partial \alpha_n}{\partial x_2} \end{pmatrix} \quad n \times 2 \text{ matrix}$$

Maximal rank =  $k=2$

Note:  $\vec{v}_i(y) := \left( \frac{\partial \alpha_1}{\partial x_1}(y), \dots, \frac{\partial \alpha_n}{\partial x_2}(y) \right) = \text{velocity vector of}$

Curve:

$$t \mapsto (\alpha_1(y_1 + t\vec{v}_1, y_2), \dots, \alpha_n(y_1 + t\vec{v}_1, y_2)) = f_1(t) \in M$$

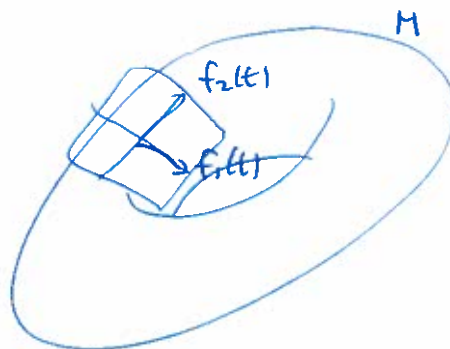
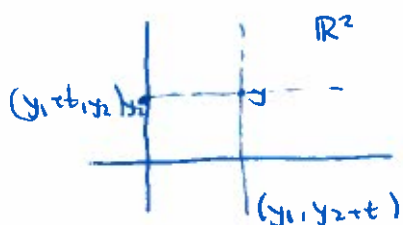
$\Rightarrow \vec{v}_1(y)$  is tangent to  $f_1(t) \Rightarrow$  tangent to  $M$  at  $pt \alpha(y)$

Similarly:  $\vec{v}_2(y) = (\frac{\partial \alpha_1}{\partial x_2}(y), \dots, \frac{\partial \alpha_n}{\partial x_2}(y))$  tangent to

$$t \mapsto f_2(t) = (\alpha_1(y_1, y_2 + t), \dots, \alpha_n(y_1, y_2 + t)) \in M$$

Rank=2  $\Rightarrow \vec{v}_1$  &  $\vec{v}_2$  are  $\left\{ \begin{array}{l} \text{linearly indep.} \\ \text{tangent} \end{array} \right\} \Rightarrow \text{rank } D\alpha(t) \neq 0$

then  $\frac{\partial \alpha}{\partial x_1}(y)$  &  $\frac{\partial \alpha}{\partial x_2}(y)$  span the tangent plane



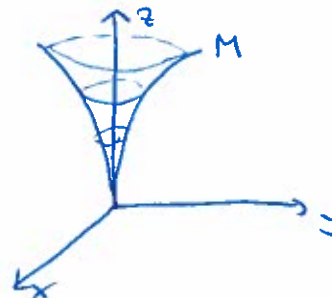
What happens if  $D\alpha$  fails max rank at some pt  $x_0$ ?

Ex:  $k=2; n=3; \alpha: \mathbb{R}^2 \rightarrow \mathbb{R}^3$   
 $(x,y) \mapsto (\underbrace{x}_{\alpha_1} / \underbrace{(x^2+y^2)}_{\alpha_2}, \underbrace{y}_{\alpha_2} / \underbrace{(x^2+y^2)}_{\alpha_2}, \underbrace{x^2+y^2}_{\alpha_3})$

Check:  $D\alpha$  ( $3 \times 2$ -matrix)  
 $D\alpha(0,0) = \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{pmatrix}$  (check!)

failure of max rank

$M = \alpha(\mathbb{R}^2)$  has a cusp at  $(0,0)$



Ex: try on your own to study:  $M = \text{cone}$   
 find:  $\beta: (x,y) \rightarrow (\beta_1(x,y), \beta_2(x,y), \beta_3(x,y))$



Significance of condition that  $\alpha^{-1}$  be continuous

Ex:  $n=2; k=1; \alpha: (0, \pi) \xrightarrow{C^1 \mathbb{R}} \mathbb{R}^2$   
 $t \mapsto \alpha(t) := \sin(2t) (\cos t, \sin t)$

$M = \alpha(0, \pi)$  is "figure 8 in  $\mathbb{R}^2$ ":



$\alpha$  class  $C^1$  (check!)

$\alpha: (0, \pi) \rightarrow M$  one-to-one (check!)

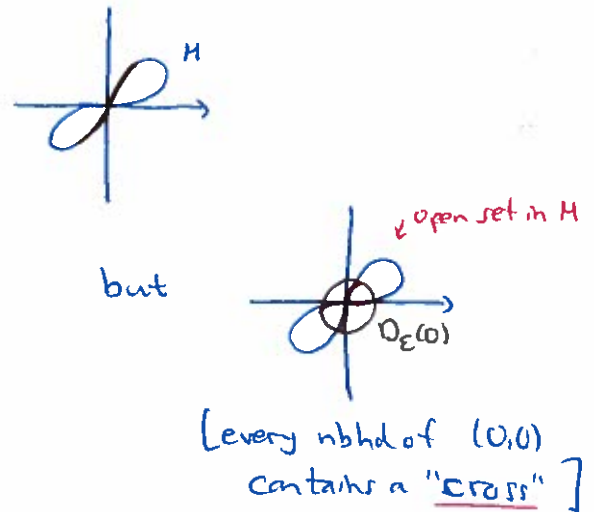
D $\alpha$  has rank 1 Check!!  
 $2 \times 1$

$\alpha^{-1}$  not continuous at  $\frac{\pi}{2} = t_0$ .

for continuity:  $\underbrace{(\alpha^{-1})^{-1}(V_0)}_{\alpha(V_0)}$  open  $\forall V_0$  open in  $\mathbb{R}^2$

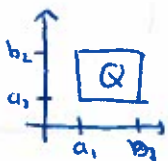


$t_0 = \frac{\pi}{2}, V_0 = (\frac{\pi}{4}, \frac{3}{4}\pi)$   
 $\alpha(V_0)$  not open  
 [ $\alpha^{-1}$  not cts  $\rightarrow$  double-crossing]



Partitions of unity

Lemma: (H)  $Q = [a_1, b_1] \times [a_2, b_2] \times \dots \times [a_n, b_n]$   
 "rectangle" in  $\mathbb{R}^n$



(C)  $\exists \varphi: \mathbb{R}^n \rightarrow \mathbb{R}$  of class  $C^\infty(\mathbb{R}^n)$  such that  
 $\varphi(x) > 0$  if  $x \in \text{int } Q = (a_1, b_1) \times \dots \times (a_n, b_n)$   
 and  $\varphi(x) = 0$  if  $x \in \mathbb{R}^n \setminus \text{int } Q$ .

Proof: read notes. → BB

Lemma 2: (H)  $A = \{A_\lambda\}_\lambda$  collection of open sets in  $\mathbb{R}^n$

$$A = \bigcup_\lambda A_\lambda$$

(C)  $\exists$  countable collection of rectangles  $\{Q_i\}_{i \in \mathbb{N}}$  s.t.  $Q_i \subset A \forall i=1, \dots, \infty$

(1)  $A \subset \bigcup_{i=1}^{\infty} Q_i$

(2)  $\forall i: \exists \lambda = \lambda(i)$  s.t.  $Q_i \subset A_{\lambda(i)}$

(3)  $\forall x \in A \exists U(x)$  open nbhd of  $x$  s.t.  $U(x) \cap Q_i \neq \emptyset$   
for only finitely many  $i$ 's ("local finiteness cond.")

Partitions of unity

Sep 12

Thm ( $\exists$  of partitions of unity)

(H)  $A = \{A_\alpha\}_\alpha$  collection of open sets in  $\mathbb{R}^n$ ,  $A = \bigcup_\alpha A_\alpha$

(C)  $\exists \{\varphi_i\}_{i \in \mathbb{N}}$  a sequence of functs:  $\varphi_i: \mathbb{R}^n \rightarrow \mathbb{R}$  s.t.

(1)  $\varphi_i(x) \geq 0 \quad \forall x \in \mathbb{R}^n, i=1, 2, 3, \dots$

(2)  $\text{Supp } \varphi_i \subset A_{\alpha(i)} \quad \exists \alpha(i)$  ( $\text{supp } \varphi_i = \{x \in \mathbb{R}^n \mid \varphi_i(x) \neq 0\}$ , so  $y \in \text{supp } \varphi_i$  then  $\exists B_r(y)$  s.t.  $\varphi_i(x) = 0 \quad \forall x \in B_r(y)$ )

(3)  $\forall x \in A, \exists U(x)$  open nbhd s.t.  $U(x) \cap \text{Supp } \varphi_i \neq \emptyset$  for only finitely many  $i$ 's

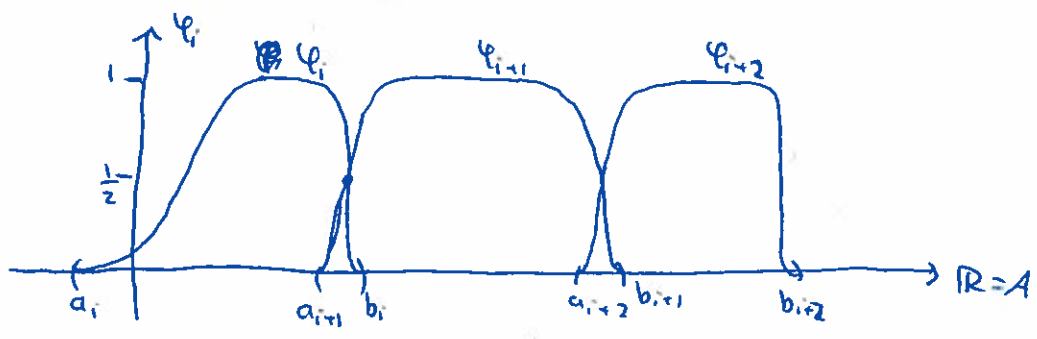
(4)  $\sum_{i \in \mathbb{N}} \varphi_i(x) = 1 \quad \forall x \in A$   
 $\uparrow$   
finite for each  $x \in A$

(5)  $\varphi_i \in C^\infty(A)$

Def:  $\{\varphi_i\}_{i \in \mathbb{N}}$  as above are called a partition of unity for  $A$  dominated by  $\{A_\alpha\}_\alpha$ .



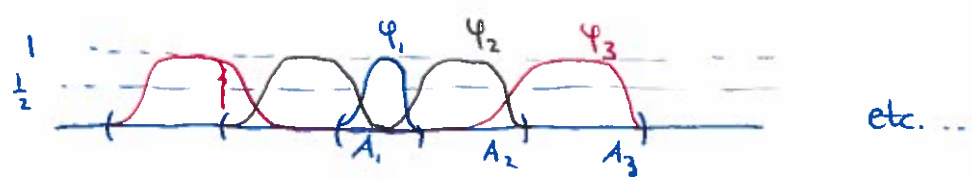
Ex: a partition of unity for  $A = \mathbb{R}$  dominated by  $\{A_i\}$



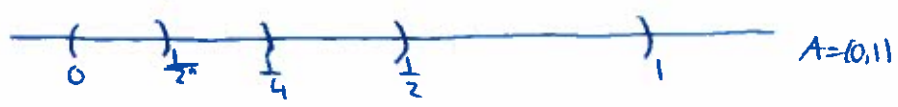
$A_i = (a_i, b_i)$  s.t.  $a_i < b_i$  &  $a_{i+1} < b_i < a_{i+2}$

In this ex,  $\sum \psi_i(x)$  consists of at most two terms  $\forall x \in \mathbb{R}$

More interesting configurations ( $A = \mathbb{R}$ ):  $A_{i_1} \subset A_{i_2+1} \subset A_{i_3} \dots$



Question: How about

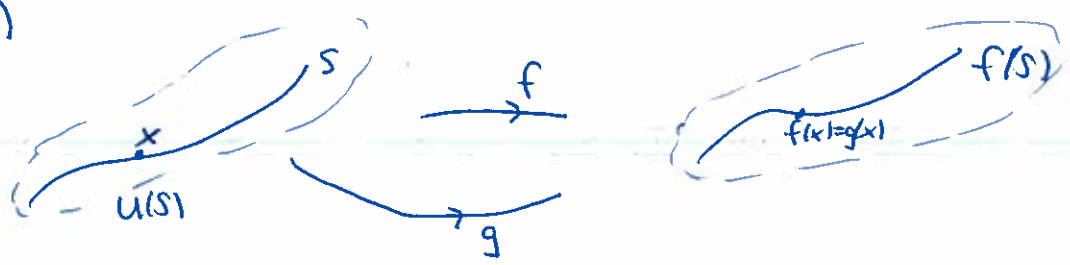


Def: (Differentiability on arbitrary sets in  $\mathbb{R}^k$ )

Let  $S \subset \mathbb{R}^k$  be (any) subset; Let  $f: S \rightarrow \mathbb{R}^n$ . We say that

"f is of class  $C^r$  on S" ( $\exists r \in \mathbb{N}$ ) if  $\exists U(S)$  open set in  $\mathbb{R}^k$  that contains S,  $\exists g: U(S) \rightarrow \mathbb{R}^n$  of class  $C^r$  s.t.  $g|_S = f$  i.e.  $g(x) = f(x) \forall x \in S$  (g is "a  $C^r$ -extension of f").

ie. ( $n=k=2$ )



fact: given  $f_1: S \subseteq \mathbb{R}^k \rightarrow \mathbb{R}^n, f_1(S) \subset T \subseteq \mathbb{R}^n$   
 -"-  $f_2: T \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^p$  }  $f_1, f_2$  of class  $C^r$

then :  $f := f_2 \circ f_1: S \subseteq \mathbb{R}^k \rightarrow \mathbb{R}^p$  is also of class  $C^r$ .  
check!

Lemma (being of class  $C^r$  is a local property)

(H) Suppose  $S \subseteq \mathbb{R}^k$ , a subset,  $f: S \rightarrow \mathbb{R}^n$

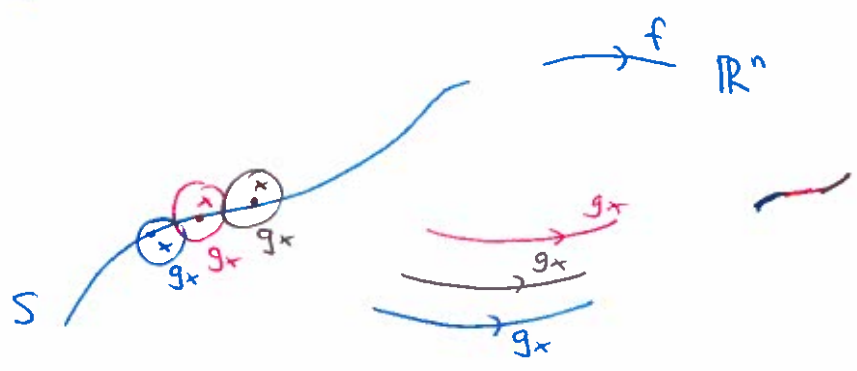
$\forall x \in S \exists U_x$  an open set in  $\mathbb{R}^k$  containing  $x$  &  $\exists g_x: U_x \rightarrow \mathbb{R}^n$  of class  $C^r$

s.t.  $g_x(y) = f(y) \quad \forall y \in S \cap U_x$ .

(C)  $f$  is of class  $C^r$ .

Proof: Need to find  $U = U(S)$  and  $g: U \rightarrow \mathbb{R}^n$  of class  $C^r$  s.t.

$g(y) = f(y) \quad \forall y \in S$ .

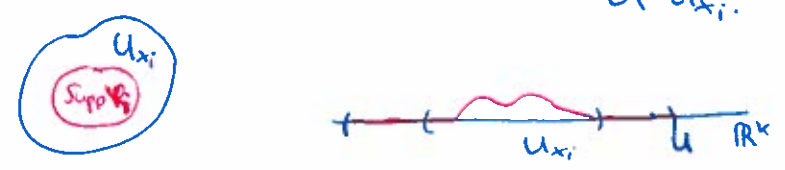


Let  $U = \bigcup_x U_x$ ; let  $A = \{A_x\} = \{U_x\}_{x \in S}$ . Let  $\{\varphi_i\}_{i \in I}$  be a partition of unity dominated by  $\{U_x\}_{x \in S}$  of class  $C^\infty$ .

$\forall i = 1, 2, 3, \dots$  pick  $U_{x_i}$  s.t.  $\text{Supp } \varphi_i \subset U_{x_i}$ , and call:  $g_i := g_{x_i}$ .

Note that:  $\varphi_i \cdot g_i: U_{x_i} \rightarrow \mathbb{R}^n$  is zero outside  $\text{Supp } \varphi_i =$  a cpct subset of  $U_{x_i}$ .  
 ptwise product

Thus we may extend  $\varphi_i \cdot g_i$  to a fct  $h_i$  on  $U$  by setting it = 0 on  $U \setminus U_{x_i}$ .  
 of class  $C^r$



Def  $g(x) := \sum_{i=1}^{\infty} h_i(x) = \sum_{i=1}^{\infty} \varphi_i(x) g_i(x)$ .

Note:  $\forall x \in U \exists U_x \exists N(x) \in \mathbb{Z}^+$  s.t.  $g(y) = \sum_{i=1}^{N(x)} \varphi_i(y) g_i(y) \forall y \in U_x$

So  $g$  of class  $C^r$  on  $U_x \forall x \in U \Rightarrow g$  of class  $C^r$

( $g =$  finite sum of  $C^r$ -fcts)

Finally, now let  $x \in S, g(x) = \sum \varphi_i(x) \underbrace{g_i(x)}_{=f(x)} \stackrel{(H)}{=} \underbrace{\left(\sum_i \varphi_i(x)\right)}_{=1 \forall x \in U} f(x) = f(x)$

So,  $g|_S = f$ , indeed. □

Def: •  $\mathbb{H}^k := \{x \in \mathbb{R}^k, x = (x_1, \dots, x_k) \text{ s.t. } x_k \geq 0\}$  is the upper half space in  $\mathbb{R}^k$ .

ex: ( $k=2$ )



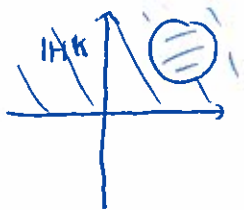
•  $\mathbb{H}_+^k := \{x \in \mathbb{R}^k \mid x = (x_1, \dots, x_k), x_k > 0\}$

i.e. the open upper half space in  $\mathbb{R}^k$

ex: ( $k=2$ )

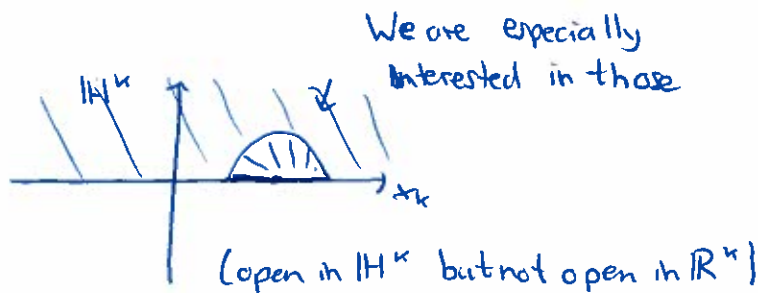


Open sets in  $\mathbb{H}^k$ :



(same as open sets in  $\mathbb{R}^k$ )

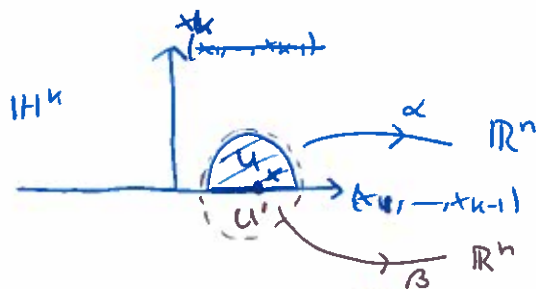
or



(open in  $\mathbb{H}^k$  but not open in  $\mathbb{R}^k$ )

Lemma: (H) Let  $U$  be open in  $\mathbb{H}^k$  but not in  $\mathbb{R}^k$ .

Let  $\alpha: U \rightarrow \mathbb{R}^n$  be of class  $C^r$ . Let  $U' \subset \mathbb{R}^k$  be open in  $\mathbb{R}^k$  that contains  $U$  & let  $\beta: U' \rightarrow \mathbb{R}^n$  be a  $C^r$ -extension of  $\alpha$ .



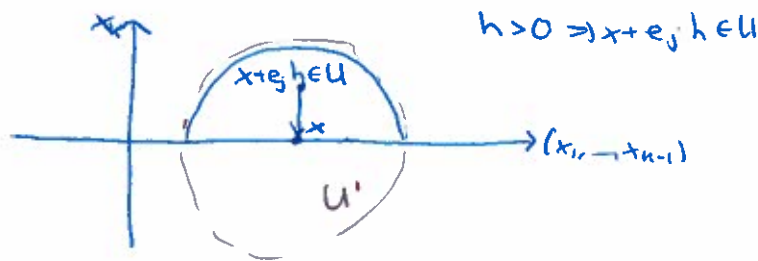
©  $\forall x \in U$ , we have that  $D_\beta(x) = \left( \frac{\partial \beta_i(x)}{\partial x_j} \right)_{\substack{i=1, \dots, n \\ j=1, \dots, k}}$

depends only on  $\alpha$  and is independent of the choice of extension  $\beta$ .

It follows that we may write  $D_\alpha(x)$  without ambiguity,  $x \in U$ .

Proof: Fix  $i \in \{1, \dots, n\}$ . For ease of notation, write  $\frac{\partial \beta(x)}{\partial x_j}$  for  $\frac{\partial \beta_i(x)}{\partial x_j}$

Recall:  $\frac{\partial \beta(x)}{\partial x_j} = \lim_{h \rightarrow 0} \frac{\beta(x + h e_j) - \beta(x)}{h}$ ,  $e_j = (0, \dots, 0, \underset{j}{1}, 0, \dots, 0)$



Now, we do now that  $\beta \in C^r(U')$  & this means that above limit exists

$\forall j=1, \dots, k \quad \forall x \in U'$ , (so in particular for  $x \in U$ ) & takes same value no

matter how you let  $h \rightarrow 0$ . Pick  $h \geq 0$ : for such  $h$ , we have that

$x + h e_j \in U$ . But  $\beta$  is an extension of  $\alpha$ , so:  $x \in U \Rightarrow \beta(x) = \alpha(x)$

&  $x + h e_j \in U \Rightarrow \beta(x + h e_j) = \alpha(x + h e_j)$

Thus for  $0 < h \ll 1$   $\frac{\beta(x + h e_j) - \beta(x)}{h} = \frac{\alpha(x + h e_j) - \alpha(x)}{h}$

ie. diff. quotient of  $\alpha$  is independent of choice of extension  $\beta$ .  $\square$

Def: Let  $k, n \in \mathbb{Z}^+$ ,  $k \leq n$ . A "k-manifold in  $\mathbb{R}^n$  of class  $C^r$ "

is a subset  $M \subseteq \mathbb{R}^n$  with the following properties:

$\forall p \in M \exists V(p) \subset \mathbb{R}^n$  (open nbhd of  $p$  in  $\mathbb{R}^n$ ),

$\exists U_p \ni p$  open either in  $\mathbb{R}^k$  or in  $\mathbb{H}^k$

$\exists$  continuous,  $H$ , onto map  $\alpha: U_p \rightarrow V(p)$  s.t.

(1)  $\alpha$  is of class  $C^r$  (i.e.  $\exists U_p' \subset \mathbb{R}^k$  open  $\exists g_\alpha: U_p' \rightarrow \mathbb{R}^n$  of class  $C^r$  s.t.  $g|_{U_p} = \alpha$ )

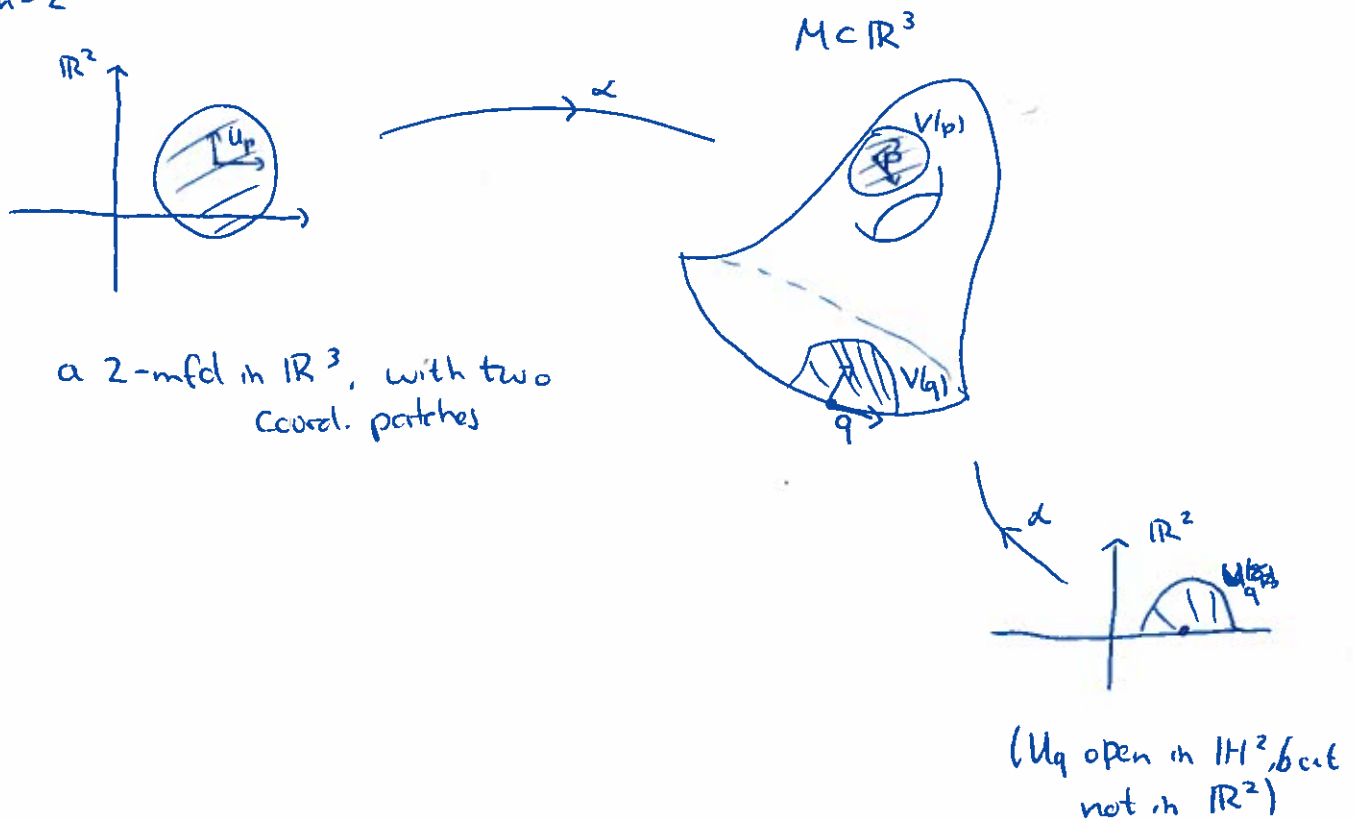
(2)  $\alpha^{-1}: V(p) \rightarrow U_p$  is continuous

(3)  $D\alpha(x)$  has (maximal) rank  $k \forall x \in U_p$ .

The map  $\alpha$  is called a coordinate patch on  $M$  about  $p$ .

Def. A discrete collection of points in  $\mathbb{R}^n$  is called a zero manifold in  $\mathbb{R}^n$ .

ex.  $n=3, k=2$



Lemma: (H)  $M$  is a  $k$ -mfd in  $\mathbb{R}^n$ ,  $\alpha: U \rightarrow V$  is a coord. patch on  $M$ .

$U_0 \subset U$  open in  $U$  ( $U_0 = U \cap \underline{B}_r(z_0)$ )

(C)  $\alpha|_{U_0}: U_0 \rightarrow \alpha(U_0) = V_0$  is also a coord. patch

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Pf:  $U_0$  open in  $U$  means  $U_0$  is open in  $\mathbb{R}^k$  or  $\mathbb{H}^k$

$\alpha^{-1}$  continuous  $\Rightarrow \alpha(U_0) =: V_0$  is open in  $\mathbb{R}^n$

$(\alpha^{-1})^{-1}(U_0)$  open but:  $(\alpha^{-1})^{-1}(U_0) = \alpha(U_0)$

It follows that  $\alpha|_{U_0}$  is a coord. patch.

- 1-1, onto
- class  $C^r$
- inverse continuous
- $D(\alpha|_{U_0})$  maximal

} immediate from properties of  $\alpha$  &  $V_0$  open

The boundary of a manifold

Fact: coordinates patches of a  $k$ -mfd "overlap differentiability"

Thm: (H)  $M$  is a  $k$ -mfd in  $\mathbb{R}^n$  of class  $C^r$

$\alpha_0: U_0 \subset \mathbb{R}^k$  (or  $\mathbb{H}^k$ )  $\rightarrow V_0 \subset M$

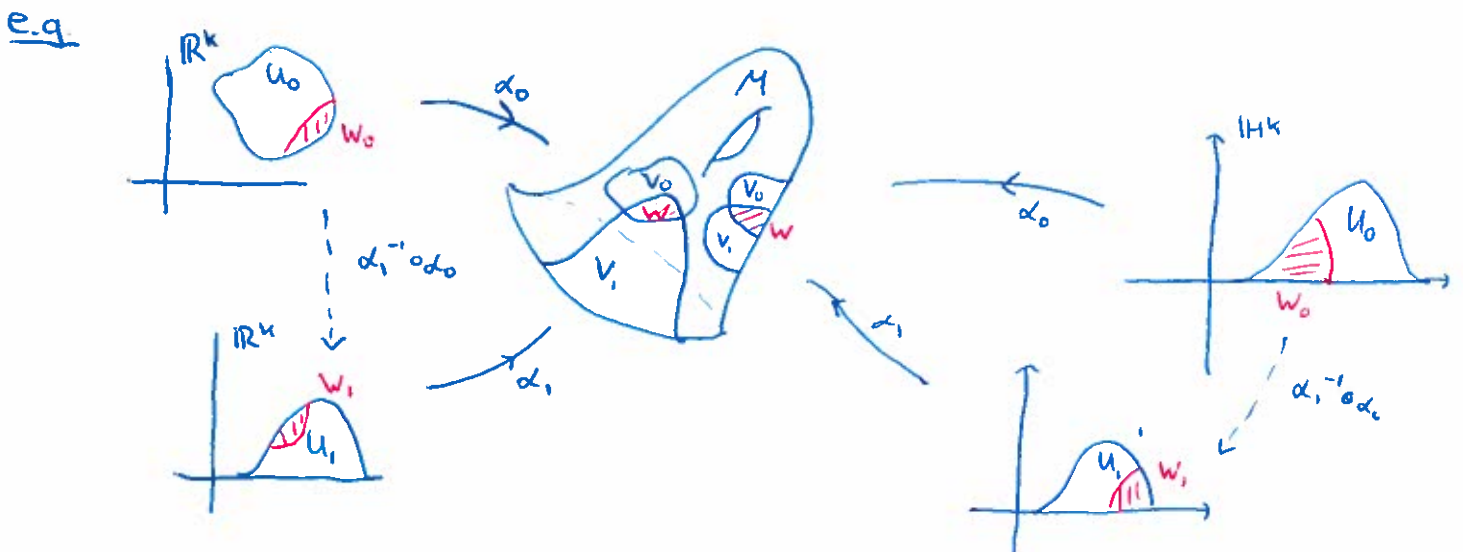
$\alpha_1: U_1 \subset \mathbb{R}^k$  (or  $\mathbb{H}^k$ )  $\rightarrow V_1 \subset M$

are two coordinate patches such that  $V_0 \cap V_1 = W \neq \emptyset$

Let  $W_i = \alpha_i^{-1}(W) \subset U_i, i=0,1$

(C)  $\alpha_1^{-1} \circ \alpha_0: W_0 \rightarrow W_1$  is of class  $C^r$  and the matrix

$D(\alpha_1^{-1} \circ \alpha_0)(x)$  is non-singular  $\forall x \in W_0$



So:  $D(\alpha_1^{-1} \circ \alpha_0)$  is a  $k \times k$ -matrix  $\forall x \in W_0 = \alpha^{-1}(W)$   
 $\cap V_0 \cap V_1$

& thm claims:  $\alpha_1^{-1} \circ \alpha_0$  is of class  $C^r$  and

$$\det(D(\alpha_1^{-1} \circ \alpha_0)(x)) \neq 0 \quad \forall x \in W_0.$$

We call  $\alpha_1^{-1} \circ \alpha_0$  a transition fct for the patches  $\alpha_0, \alpha_1$ .

Pf. Claim: enough to show that if  $\alpha: U \rightarrow V$  is a coord. patch on  $M$ , then  $\alpha^{-1}: V \rightarrow U$  is of class  $C^r$ .

Assuming that claim is true, let's see why (c) follows:

if  $\alpha_1^{-1}$  is of class  $C^r$  then so is  $\alpha_1^{-1} \circ \alpha_0$  ✓

Also:

$$\text{Id} = (\alpha_0^{-1} \circ \alpha_1) \circ (\alpha_1^{-1} \circ \alpha_0) : W_0 \rightarrow W_0$$

$$\det D(\text{Id})(x) = \det \left( \underbrace{D(\alpha_0^{-1} \circ \alpha_1)}_{B(x)} \cdot \underbrace{D(\alpha_1^{-1} \circ \alpha_0)(x)}_{\text{matrix product}} \right), x \in W_0$$

$\nearrow$  chain rule  
 $\nwarrow$

$\alpha_0^{-1} \circ \alpha_1$   
&  $\alpha_1^{-1} \circ \alpha_0$   
are of class  $C^r$

$$1 = \det B(x) \cdot \det(D(\alpha_1^{-1} \circ \alpha_0)(x))$$

$$\Rightarrow \det B(x) \neq 0 \text{ and } \det(D(\alpha_1^{-1} \circ \alpha_0)(x)) \neq 0$$

$$\Rightarrow D(\alpha_1^{-1} \circ \alpha_0)(x) \text{ non-singular!}$$

We are left to prove the claim, that is to show that if  $\alpha: U \rightarrow V$

is a coord. patch, then  $\alpha^{-1}$  is of class  $C^r$ .

$\alpha^{-1}: V \rightarrow U$  & we would need to show that  $\exists \tilde{V} \subset \mathbb{R}^n$  open

in  $\mathbb{R}^n$   $\exists G: \tilde{V} \rightarrow \mathbb{R}^k$  of class  $C^r$  s.t.  $V \subset \tilde{V}$  &  $G(p) = \alpha^{-1}(p)$

$\forall p \in V \cap \tilde{V}$ . But we know that the property of being of class  $C^r$

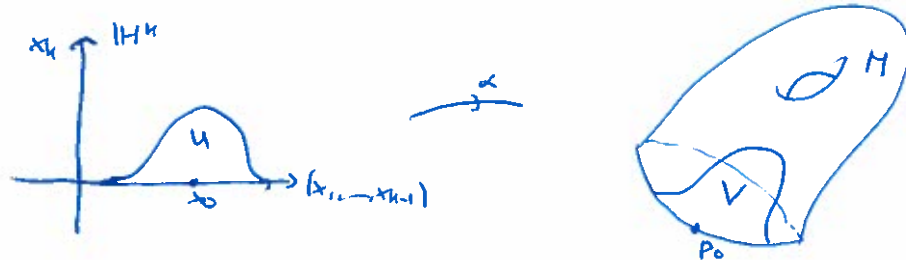
is local (lemma we proved last time), so, enough to show that

$\alpha^{-1}$  is locally of class  $C^r$  that is:  $\forall p_0 \in V \exists V'(p_0)$  open in  $\mathbb{R}^n$   
 (containing  $p_0$ ) and  $\exists g: V'(p_0) \rightarrow \mathbb{R}^k$  of class  $C^r$  s.t.

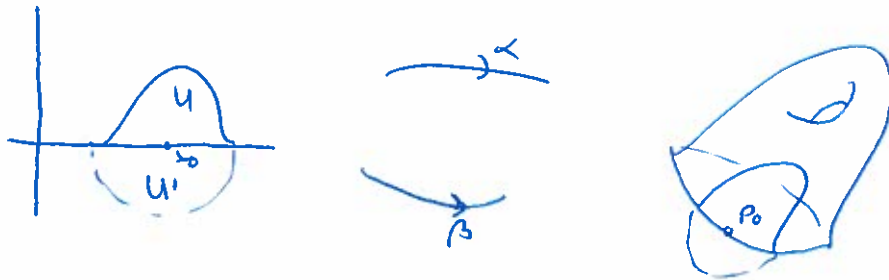
$$g(p) = \alpha^{-1}(p) \quad \forall p \in V^{-1}(p_0) \cap V.$$

recall:  $\alpha^{-1}: V \rightarrow U$  where  $U$  is either open in  $\mathbb{H}^k$  (but not in  $\mathbb{R}^k$ ), or open in  $\mathbb{R}^k$ . Set:  $x_0 := \alpha^{-1}(p_0) \in U$ .

Case 1:  $U$  open in  $\mathbb{H}^k$  but not in  $\mathbb{R}^k$ :



(H)  $\Rightarrow$  we may extend  $\alpha$  to a  $C^r$ -map  $\beta$  on an open set  $U' \subseteq \mathbb{R}^n$ .



Also (H)  $\Rightarrow D\alpha(x_0)$  has rank  $k$ , so there are  $k$ -many lin. independent rows in  $D\alpha(x_0)$  & we may assume that these are the first  $k$  rows.

let  $\pi: \mathbb{R}^n \rightarrow \mathbb{R}^k$ ,  $\pi(x_1, \dots, x_n) = (x_1, \dots, x_k)$ .

Then  $h := \pi \circ \beta: U' \rightarrow \mathbb{R}^k$  is of class  $C^r$  (check!)

&  $\det(Dh)(x_0) \neq 0$  (check!!!)

Aside: Recall from Advanced Calculus

Inverse Function Thm:

(H)  $U' \subseteq \mathbb{R}^n$  open set,  $h: U' \rightarrow \mathbb{R}^k$  of class  $C^r$

$\det Dh(x_0) \neq 0 \quad \exists x_0 \in U'$

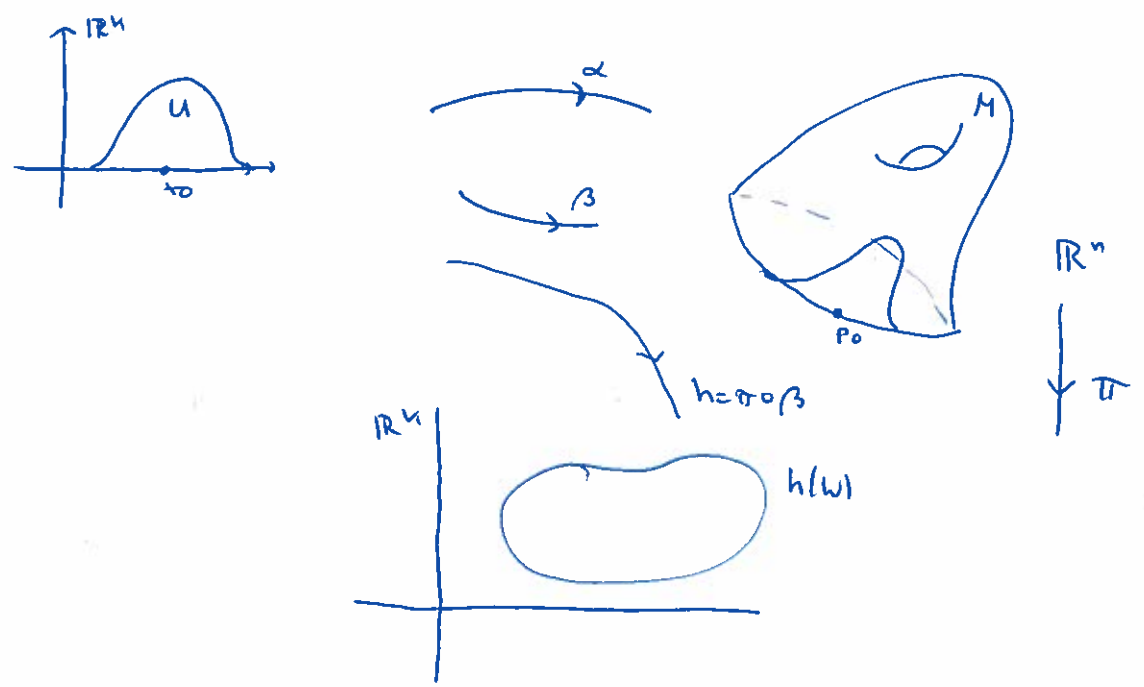
(C)  $\exists W = W(x_0)$  open nbhd of  $x_0$  in  $\mathbb{R}^n$  st.  $h(W)$  is open in  $\mathbb{R}^k$



$h: W \rightarrow h(W)$  1-1 & onto. Furthermore,  $h^{-1}$  is of class  $C^r$ .

We call such  $h$  a diffeomorphism of class  $C^r$   
also "change of variables of class  $C^r$ "

By Inverse fct Thm,  $\exists W = W(w_0) \subset \mathbb{R}^k$  open set s.t.  $h: W \rightarrow h(W) \subset \mathbb{R}^k$   
is diffeom. of class  $C^r$ , i.e.  $h$  invertible and  $h^{-1}$  of class  $C^r$ , &  
 $h(W)$  open set in  $\mathbb{R}^k$ :



Def:  $g = h^{-1} \circ \pi$ , Note that  $g$  is of class  $C^r$ .

Claim:  $\exists V' = V'(p_0)$  open in  $\mathbb{R}^n$  such that  $g(p) = \alpha^{-1}(p) \forall p \in V'$ .

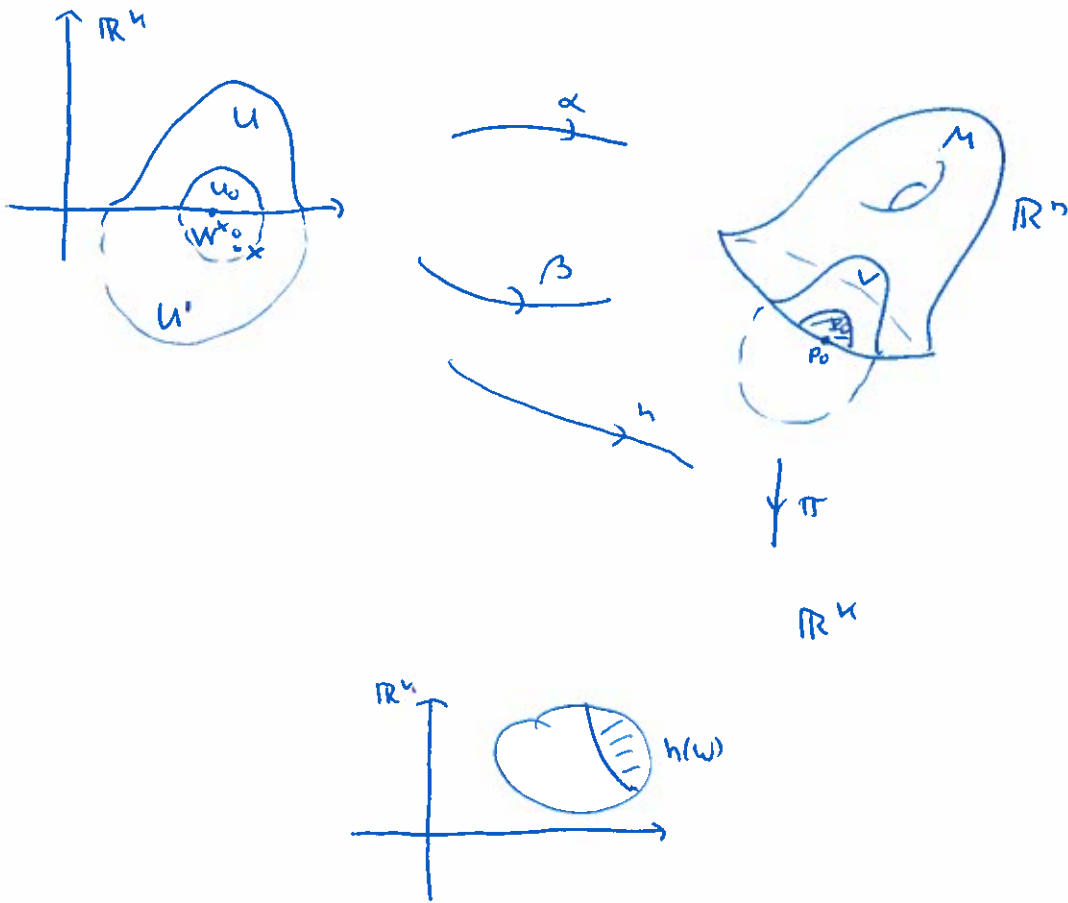
Pf of claim: first note that  $U_0 := U \cap W$  is open in  $U$ .

(b/c  $W$  is open in  $\mathbb{R}^k$ ). Thus  $\alpha(U_0) =: V_0$  is open in  $V$

(b/c  $\alpha^{-1}$  continuous since  $\alpha$  is coord. chart)

So  $\exists V'$  open in  $\mathbb{R}^n$  s.t.  $V_0 = V' \cap V$  & we may choose  $V'$

so that  $V' \subset \text{domain of } g$  (intersect  $V'$  with  $\pi^{-1}(h(W))$ )



$\forall p \in V_0 = V \cap V'$  let  $x = \alpha^{-1}(p) \in U_0$  & compute

$$g(p) = g(\alpha(x)) = \underset{\substack{x \in U_0 \cap U' \\ \beta \text{ is an extension of } \alpha}}{h^{-1}(\pi(\beta(x)))} = h^{-1}(h(x)) = x$$

So:  $g(p) = x = \alpha^{-1}(p)$ .

Case 2:  $U$  (domain of chart  $\alpha$ ) is open in  $\mathbb{R}^k$ .

proof is similar (same steps) but much easier.

We may pick  $U' = U$  &  $\beta = \alpha$ . □

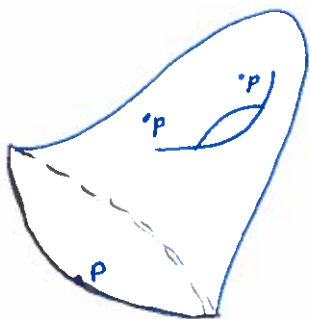
Def: (interior points & boundary pts of  $k$ -mfd in  $\mathbb{R}^n$ ).

Let  $M$  be a  $k$ -mfd in  $\mathbb{R}^n$ , <sup>cr</sup>clsd. Let  $p \in M$ .

• If there is a coord. patch  $\alpha: U \rightarrow V$  on  $M$  about  $p$  such that  $U$  is open in  $\mathbb{R}^k$ , then we say that  $p$  is an interior point of  $M$ .

- Otherwise (i.e. if all coord. <sup>patches</sup> about  $p$  are defined on sets that are open in  $\mathbb{H}^k$  but not open in  $\mathbb{R}^k$ ) we say that  $p$  is a boundary pt of  $M$  [computationally hard to check]

Notation:  $\{ \text{boundary pts of } M \} = bM$  "boundary of  $M$ "  
 $M \setminus bM = \text{Int } M$  "interior of  $M$ "



Lemma 2: (Criteria to identify boundary pts on a  $k$ -mfd in  $\mathbb{R}^n$ )

(H)  $M \subset \mathbb{R}^n$  is a  $k$ -mfd in  $\mathbb{R}^n$ ,  $p \in M$ ,  $\alpha: U \rightarrow V$  chart about  $p$ .

(C) (a) if  $U$  is open in  $\mathbb{R}^k$  then  $p \in \text{Int } M$

(b) if  $U$  is open in  $\mathbb{H}^k$  <sub>(not in  $\mathbb{R}^k$ )</sub> and  $p = \alpha(x_0) \exists x_0 \in \mathbb{H}_+^k$   
 then  $p \in \text{Int } M$

(c) if  ~~$U$  is open in  $\mathbb{H}^k$~~  and  $p = \alpha(x_0) \exists x_0 \in \mathbb{R}^{k-1} \times \{0\}$   
 then  $p \in bM$

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Lemma 1: (H)  $p \in bM$

(C)  $\forall$  charts  $\alpha: U \rightarrow V$  about  $p$ ,  $\exists x \in U \cap (\mathbb{R}^{k-1} \times \{0\})$  s.t.  $p = \alpha(x)$

PF: By def. we know that  $U \cap (\mathbb{R}^{k-1} \times \{0\}) \neq \emptyset$ .

By contradiction:  $\exists \beta: U \rightarrow V$  a chart s.t.  $p = \beta(x_1) \exists x_1 \in U \setminus (\mathbb{R}^{k-1} \times \{0\})$

This means that  $x_1 \in \mathbb{H}_+^k$  which is open in  $\mathbb{R}^k \Rightarrow \exists B_\epsilon^k(x_1) \subset U \setminus (\mathbb{R}^{k-1} \times \{0\})$

$\Rightarrow \beta|_{B_\epsilon^k(x_1)}$  is also a chart about  $p$  ~~is~~ (b/c  $p \in bM$ : every chart has domain not open in  $\mathbb{R}^k$ , but  $B_\epsilon^k(x_1)$  is!)

So  $p \in bM \Rightarrow \forall \text{ chart about } p, p = \alpha(x_0) \Rightarrow x_0 \in \mathbb{R}^{k-1} \times \{0\}$ .

Proof of Lemma 2:

- (i) trivial (def of Int M!)
- (ii) semi-trivial:  $x_1 \in \text{Int } M \Rightarrow \exists B_\epsilon^k(x_1)$  open in  $\mathbb{R}^k$  &  $\alpha|_{B_\epsilon^k(x_1)}$  is also a chart.
- (iii) By contradiction: Say  $p \notin bM$ . Then  $p \in \text{Int } M$  i.e.  $\exists \alpha_1: U_1 \rightarrow V_1$  about  $p$  with  $U_1$  open in  $\mathbb{R}^k$ .

Set  $V = V_0 \cap V_1$  open in  $M$  &  $p \in V$ . Set  $W_0 := \alpha_0^{-1}(V)$ : open in  $\mathbb{H}^k$  and  $x_0 \in W_0$ . Set  $W_1 := \alpha_1^{-1}(V)$ : open in  $\mathbb{R}^k$ .

Consider transition fct:  $\alpha_0^{-1} \circ \alpha_1: W_1 \rightarrow W_0$ . By previous Thm,

$\alpha_0^{-1} \circ \alpha_1$  is class  $C^r$ ; 1-1; onto;  $\det(D(\alpha_0^{-1} \circ \alpha_1)(x)) \neq 0 \forall x \in W_1$

By global inverse fct thm it follows that  ~~$W_0 = \alpha_0^{-1}(V)$~~

$W_0 = (\alpha_0^{-1} \circ \alpha_1)(W_1)$  is open in  $\mathbb{R}^k$ : impossible b/c  $x_0 \in W_0 \cap (\mathbb{R}^{k-1} \times \{0\})$

&  $W_0 \subseteq \mathbb{H}^k$  so  $\exists B_\epsilon^k(x_0) \subset W_0$ , so  $W_0$  not open in  $\mathbb{R}^k$ . □

Summary:

Lemma 1:  $p \in bM \Rightarrow \forall \text{ chart about } p \exists x \in \mathbb{R}^{k-1} \times \{0\}$  s.t.  $p = \alpha(x)$

Lemma 2: if  $p = \alpha(x_0) \mid \exists x_0 \in \mathbb{R}^{k-1} \times \{0\} \exists \text{ chart} \Rightarrow p \in bM$ .

Ex:  $M = \mathbb{H}^k$  is a  $k$ -mfd in  $\mathbb{R}^k$  of class  $C^\infty$ , &  $b\mathbb{H}^k = \mathbb{R}^{k-1} \times \{0\}$   
check!!

Thm: (H)  $M$  is a  $k$ -manifold in  $\mathbb{R}^n$  of class  $C^r$ .

(C)  $bM$  is a  $(k-1)$ -mfd in  $\mathbb{R}^n$  of class  $C^r$  and  $b(bM) = \emptyset$ .

Pf: To show:  $\forall p \in bM \exists \alpha': U' \rightarrow V'$  chart about  $p$  with  $U'$  open in  $\mathbb{R}^{k-1}$ .

Pick  $p \in bM$ .  $(H) \Rightarrow \exists \alpha: U \rightarrow V$  chart about  $p$  of class  $C^r$  with

$U$  open in  $\mathbb{H}^k$  (not in  $\mathbb{R}^k$ ) &  $p = \alpha(x_0) \exists x_0 \in U \cap (\mathbb{R}^{k-1} \times \{0\})$

Notation:  $\mathbb{R}^k = \{(x', x_k) \mid x' \in \mathbb{R}^{k-1}, x_k \in \mathbb{R}\}$ .

Claim:  $U \cap (\mathbb{R}^{k-1} \times \{0\}) = U' \times \{0\} \exists$  open set  $U'$  in  $\mathbb{R}^{k-1}$

Pf of claim: WLOG:  $U = B_E^k(x_0) \cap \mathbb{H}^k = \{(x', x_k) \mid |x' - x_0'|^2 + \frac{x_k^2}{E^2} < E^2\}$

$$\Rightarrow U \cap (\mathbb{R}^{k-1} \times \{0\}) = \{(x', x_k) \mid |x' - x_0'|^2 + 0 < E^2, x_k = 0\} \cap \{x_k \geq 0\}$$

$$= B_E^{k-1}(x_0') \times \{0\}$$

$$\Rightarrow U' = B_E^{k-1}(x_0') \quad \text{Let } x' \in U'$$

Def.  $\alpha'(x') := \alpha(x', 0)$  : class  $C^r$  b/c  $\alpha$  is so

$\bullet D\alpha'(x')$  has rank  $k-1 \checkmark$  ( $(n \times (k-1))$  submatrix of  $n \times k$  :

$$\frac{D\alpha(x', 0)}{\text{rank } k} )$$

Also: Lemmas 1 & 2:  $\alpha: \frac{U \cap \{x_k = 0\}}{U' \times \{0\}} \xrightarrow{\text{check!}} \frac{V \cap bM}{V' \cap bM}$   
 $= \frac{V' \cap bM}{\text{open in } bM}$

$$\alpha': U' \rightarrow U' \times \{0\} \xrightarrow{\alpha} V \cap bM =: V' \text{ open set in } bM$$

$\mathbb{R}^{k-1} \xleftarrow{\pi} \mathbb{R}^k$   $q$

$$\text{and } \forall q \in V \cap bM, (\alpha')^{-1}(q) = \underbrace{(\pi \circ \alpha^{-1})}_{\text{continuous}}(q) \text{ b/c } \alpha^{-1} \text{ is so}$$

All together:  $\forall p \in bM \exists U'$  open in  $\mathbb{R}^{k-1}$  &  $C^r$ -chart

$$\alpha': U' \rightarrow V' \text{ about } p$$

$\nwarrow$  open in  $bM$ . □

Recall:  $\alpha'(x') = \alpha(x', 0)$   
 $\downarrow$   
 chart for  $p \in bM$  chart for  $p \in bM \subset M$ .

We call  $\alpha'$  the restriction of the chart.

A procedure for constructing  $n$ -mfd in  $\mathbb{R}^n$  of class  $C^r$  and  $(n-1)$ -mfd's in  $\mathbb{R}^n$  (class  $C^r$ ).

Thm: (H)  $A \subseteq \mathbb{R}^n$  open,  $f: A \rightarrow \mathbb{R}$  of class  $C^r$ ,  $f \neq \text{const}$ .

Def.  $N := f^{-1}([0, +\infty)) = \{y \in A \mid f(y) \geq 0\}$

Def.  $M := f^{-1}(0) = \{x \in A \mid f(x) = 0\}$ .

Suppose that  $M \neq \emptyset$  &  $Df(x) \in \mathbb{R}^{n \times 1}$  has rank 1  $\forall x \in M$ .

(C)  $N$  is an  $n$ -mfd class  $C^r$  &  $\partial N = M$ .

(Note: if  $N = M$  i.e.  $f(y) \leq 0 \forall y \in A$ : replace  $f$  with  $g := -f$ ).

Proof:  $p \in N$ . Two cases:  $f(p) > 0$  or  $f(p) = 0$  (def  $N$ )

Case 1:  $f(p) > 0$ . Def.  $U := f^{-1}(0, \infty)$  open in  $\mathbb{R}^n$  (b/c  $f$  continuous)

&  $p \in \text{int } U$  &  $\alpha: U \rightarrow U$ ,  $\alpha(x) := x$  is trivially a coord. chart about  $p$ , & since  $U$  open in  $\mathbb{R}^n$ ,  $p \in \text{int } N$ .

Case 2:  $f(p) = 0 \Rightarrow p \in M$  (def  $M$ ) & (H)  $\rightarrow Df(p)$  has rank 1

$\Rightarrow \frac{\partial f(p)}{\partial x_j} \neq 0 \quad \exists j = 1, \dots, n$

WLOG. :  $j = n$  i.e.  $\frac{\partial f}{\partial x_n}(p) \neq 0$

Def.  $F: A \rightarrow \mathbb{R}^n$

$x = (x', x_n) \mapsto F(x) = (x', f(x))$

$DF(x) := \begin{pmatrix} I^{(n-1) \times (n-1)} & 0 \\ \vdots & \frac{\partial f}{\partial x_n}(x) \\ \frac{\partial f}{\partial x_j} & \# \\ \vdots & 0 \end{pmatrix}$

$\det DF(p) = 1 \cdot D_n f(p) \neq 0$

$DF(p)$  non-singular. By inverse Fct Thm  $\exists V(p), \exists U(F(p))$

Open sets in  $\mathbb{R}^n$  s.t.

$F: V(p) \rightarrow U(\mathbb{R}^n)$  is diffeo of class  $C^r$

&  $F: \underbrace{V(p) \cap N}_{\text{open in } N} \rightarrow \underbrace{U \cap \mathbb{H}^n}_{\text{open in } \mathbb{H}^n}$  (b/c  $x \in N \Leftrightarrow f(x) \geq 0$ )

Thus:  $\alpha := F^{-1} = \underbrace{U \cap \mathbb{H}^n}_{U'} \rightarrow \underbrace{V(p) \cap N}_{V'}$

is the required chart.

Also:  $F: V(p) \cap M \rightarrow U(p) \cap \mathbb{H}^n$

so  $bN = M$ . □

Thm: (H)  $A \subset \mathbb{R}^n$  open set,  $f: A \rightarrow \mathbb{R}$  class  $C^r$ ,  $f \neq \text{const}$ .

(C)  $f^{-1}([0, \infty))$  is  $n$ -mfld class  $C^r$ , call it  $N$ ,  $f^{-1}(0) = bN$ .

Ex:  $x \in \mathbb{R}^n$ ,  $x = (x', x_n)$ ,  $x' \in \mathbb{R}^{n-1}$

let  $g: \underbrace{A' \subset \mathbb{R}^{n-1}}_{\text{open}} \rightarrow \mathbb{R}$  class  $C^r$

Def.  $f(x) := g(x') - x_n$ .  $Df(x) = (Dg(x'), \underbrace{-1}_{\neq 0})$

has max'l rank.

Thm  $\Rightarrow N := \{(x', x_n) \mid x_n < g(x')\}$  &  $M = \{(x', x_n) \mid x_n = g(x')\}$   
 $n$  mfd  $n-1$  mfd

are class  $C^r$ -mfds

$\uparrow$

epigraph of  $g$

$\uparrow$

graph of  $g$

So epigraphs & graphs of fcts of class  $C^r$  always have mfld structure.

& can describe  $N$  &  $M$  with a single chart

$\alpha': \underbrace{\mathbb{R}^{n-1}}_{U'} \rightarrow M \cap \mathbb{R}^n$

$x' \mapsto \alpha'(x') := \alpha(x', 0) = (x', g(x'))$

$\alpha: \mathbb{R}^n \rightarrow N \cap \mathbb{R}^n$

$x \mapsto \alpha(x) = (x', g(x') - x_n)$ .

Ex:  $B_r^n(p) = \{ |x-p|^2 \leq r^2 \}$  is mfd with  $b: B_r^n(p) \rightarrow S^{n-1}(p)$   
 with  $f(x) := r^2 - |x-p|^2$  Check!

Def: For a  $k$ -mfd  $M \subset \mathbb{R}^n$  of class  $C^r$ , an atlas for  $M$  is  $\{ \alpha_i, U_i, V_i \}_{i \in J}$ , a collection of coord. charts s.t.  $M = \bigcup_{i \in J} V_i$  Sep 21

Next goal: "Integrals of scalar fcts over mfd" i.e.  $\int_M f dv = ?$

But first: quick detour of linear algebra

A quick review of (some) linear algebra & integration over  $\mathbb{R}^n$

Def: Let  $h: \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a linear transformation  
 $(h(ax+by) = ah(x) + bh(y) \quad \forall a, b \in \mathbb{R}, \forall x, y \in \mathbb{R}^n)$

Facts:

- $h(\vec{x}) = A \cdot \vec{x} \quad \exists A \in \mathbb{R}^{n \times n}$  (matrix),  $\vec{x} \in \mathbb{R}^n$  ("vector")
- $h$  is orthogonal if  $A$  is an orthogonal matrix i.e.  $A^{tr} \cdot A = I^{n \times n}$   
 where if  $A = (a_{ij}) \Rightarrow A^{tr} := (b_{ij}), b_{ij} := a_{ji}$ .
- $h$  is isometry if  $\|h(\vec{x}) - h(\vec{y})\|_{\mathbb{R}^n} = \|\vec{x} - \vec{y}\|_{\mathbb{R}^n}$  (distance preserving)

Def: Linear subspace of  $\mathbb{R}^n$  is  $W \subset \mathbb{R}^n$  s.t.  $\forall \vec{u}, \vec{v} \in W \Rightarrow a\vec{u} + b\vec{v} \in W \quad \forall a, b \in \mathbb{R}$

(ex: Line through origin is linear subspace  $\smile$ )

Lemma:  $\oplus W$  is linear subspace of  $\mathbb{R}^n$  with dimension  $n \leq k$ .

- © •  $\exists$  orthonormal basis for  $\mathbb{R}^n$  whose first  $k$  elements are a basis for  $W$
- $\exists h: \mathbb{R}^n \rightarrow \mathbb{R}^n$  orthogonal transf. s.t.  $h(W) = \mathbb{R}^k \times \underbrace{\{ (0, 0, \dots, 0) \}}_{(n-k) \text{ 1-times}} \subset \mathbb{R}^n$



Thm 1 ("Volume fct in  $\mathbb{R}^n$ ")

(M)  $k, n \in \mathbb{Z}^+, k \leq n$

(C) There ~~exists~~ a unique fct:  $V: \mathbb{R}^{n \times k} \rightarrow [0, \infty) \subset \mathbb{R}$

$$(\vec{x}_1, \dots, \vec{x}_k) \rightarrow V(\vec{x}_1, \dots, \vec{x}_k) \in [0, \infty) \text{ s.t.}$$

$\in \mathbb{R}^n, \dots, \in \mathbb{R}^n$

(1) if  $h: \mathbb{R}^n \rightarrow \mathbb{R}^n$  is orthog. transf. then  $V(h(\vec{x}_1), \dots, h(\vec{x}_k)) = V(\vec{x}_1, \dots, \vec{x}_k)$

(2) if  $\vec{y}_j \in \mathbb{R}^k \times \{\vec{0}\} \in \mathbb{R}^n \quad \forall j=1, \dots, k$ , so:  $\vec{y}_j = \begin{bmatrix} z_{1j} \\ z_{2j} \\ \vdots \\ z_{kj} \\ 0 \end{bmatrix} = \begin{bmatrix} z \\ 0 \end{bmatrix}$

then  $V(\vec{y}_1, \dots, \vec{y}_k) = |\det Z|$ ,  $Z = (z_{ij}) \in \mathbb{R}^{k \times k}$

(3) In general:  $V(\vec{x}_1, \dots, \vec{x}_k) = |\det(X^t \cdot X)|^{1/2}$  where  $X := [\vec{x}_1, \dots, \vec{x}_k] \in \mathbb{R}^{n \times k}$

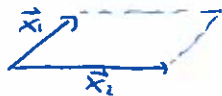
(so  $X^t \cdot X \in \mathbb{R}^{k \times k}$ )

It follows  $V(\vec{x}_1, \dots, \vec{x}_k) = 0 \Leftrightarrow \{\vec{x}_1, \dots, \vec{x}_k\}$  are linearly dependent vectors in  $\mathbb{R}^n$ .

Notation:  $V(\vec{x}_1, \dots, \vec{x}_k) = V(X)$  volume function

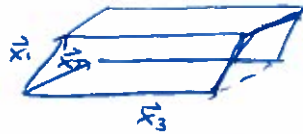
Ex: •  $k=2, n=3$  then  $V(\vec{x}_1, \vec{x}_2) = \text{area of parallelogram in } \mathbb{R}^3 \text{ with edges}$

$\vec{x}_1$  &  $\vec{x}_2$ :



•  $k=3, n=3$  then  $V(\vec{x}_1, \vec{x}_2, \vec{x}_3) = \text{volume of parallelepiped with edges}$

$\vec{x}_1, \vec{x}_2, \vec{x}_3$



Back:  $k=2, n=3$ : Recall from Calc III that Area(parallelogram) = magnitude of  $\vec{x}_1 \times \vec{x}_2$  (cross pr.)

So, two ways for computing area of a parallelogram:

via Thm 1 (formula 3) or via cross product.

Similarly, for  $X \in \mathbb{R}^{n \times k}$  we have:

Thm 2 (H)  $X \in \mathbb{R}^{n \times k}$ ,  $k \leq n$

$$(C) \quad V(X) = \left( \sum_{[I]} (\det X_I)^2 \right)^{1/2},$$

where  $\cdot [I]$  means that above summation is taken over all

"ascending  $k$ -tuples of  $\{1, \dots, n\}$ " i.e. over all  $I = (i_1, i_2, \dots, i_k)$

$\subset \{1, \dots, n\}$  s.t.  $i_1 < i_2 < \dots < i_k$

(ex: "ascending 2-plets of  $\{1, 2, 3\} = \{(1, 2), (1, 3), (2, 3)\}$ ")

$\cdot X_I$  is  $k \times k$  submatrix of  $X$  consisting of rows  $i_1, i_2, \dots, i_k \in I$ .

Ex:  $k=2; n=3$

$$X = \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \\ x_{31} & x_{32} \end{pmatrix} \begin{matrix} \left[ \begin{matrix} x_{12} \\ x_{23} \end{matrix} \right] \\ \left[ \begin{matrix} x_{12} \\ x_{23} \end{matrix} \right] \end{matrix} \begin{matrix} \cdot \\ \cdot \end{matrix} \begin{matrix} x_{13} \\ x_{23} \end{matrix}$$

So in this ex. by Thm 2,  $V(X) = \left( \det^2 \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \end{pmatrix} + \det^2 \begin{pmatrix} x_{11} & x_{12} \\ x_{31} & x_{32} \end{pmatrix} + \det^2 \begin{pmatrix} x_{21} & x_{22} \\ x_{31} & x_{32} \end{pmatrix} \right)^{1/2}$

$$\text{Thm 1: } \Rightarrow X^t \cdot X = \begin{pmatrix} x_{11} & x_{21} & x_{31} \\ x_{12} & x_{22} & x_{32} \end{pmatrix} \begin{pmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \\ x_{31} & x_{32} \end{pmatrix} = \begin{pmatrix} x_{11}^2 + x_{21}^2 + x_{31}^2 & x_{11}x_{12} + x_{21}x_{22} + x_{31}x_{32} \\ x_{12}x_{11} + x_{22}x_{21} + x_{32}x_{31} & x_{12}^2 + x_{22}^2 + x_{32}^2 \end{pmatrix}$$

$$V(X) = \det(X^t \cdot X)^{1/2} = \dots$$

depending on relative size of  $k$  and  $n$ , formula from Thm 1 may be easier or harder than formula from Thm 2.

Def: Given a set  $\{\vec{x}_1, \dots, \vec{x}_k\}$  of linearly independent vectors in  $\mathbb{R}^n$ ,

the  $k$ -parallelepiped  $P(\vec{x}_1, \dots, \vec{x}_k)$  in  $\mathbb{R}^n$  is

$$\left\{ \vec{y} \in \mathbb{R}^n \mid \vec{y} = \sum_{j=1}^k a_j \vec{x}_j, a_j \in [0, 1] \right\}$$

So: • 2-parallel piped in  $\mathbb{R}^n =$  parallelogram

• 3- " " " " in  $\mathbb{R}^3 =$  "parallelepiped"

Def: Given  $X \in \mathbb{R}^{n \times n}$ , Volume of  $\{\vec{x}_1, \dots, \vec{x}_n\} := V(X)$

Note: if  $\{\vec{x}_1, \dots, \vec{x}_n\}$  are linearly indep. then  $V(X) =$  volume of  $P(\vec{x}_1, \dots, \vec{x}_n)$

Integrating a continuous, scalar fct over a k-mfd in  $\mathbb{R}^n$

Just consider special case when  $M$  (mfd) is a cpct subset of  $\mathbb{R}^n$

(eg.  $M =$  ball in  $\mathbb{R}^n$  or  $M =$  sphere in  $\mathbb{R}^n$ )

Extension to general case ( $M$  unbounded) is analog to strategy dealing with "improper integrals".

Preliminaries: Let  $M$  be a cpct  $k$ -mfd in  $\mathbb{R}^n$ , class  $C^r$ .

Let  $f: M \rightarrow \mathbb{R}$  be a continuous funct.

Let  $K = \text{supp } f$ . Note that  $K$  is a cpct set in  $\mathbb{R}^n$ .

To begin with, suppose that  $\text{supp } f$  is contained in a single chart:

$\alpha: U \rightarrow V$ , so  $\text{supp } f \subset V$ .

Claim:  $\alpha^{-1}(\text{supp } f)$  is cpct subset of  $\mathbb{H}^k$ . (check!)

Thus, wlog we may assume that  $U$  is bounded.



So, wlog we may assume for

- $M$  cpct  $k$ -mfd in  $\mathbb{R}^n$ , class  $C^r$ , that
- $f: M \rightarrow \mathbb{R}$  continuous & let  $K = \text{supp } f$  (cpct)

•  $\alpha: U \rightarrow V$  a coord. chart s.t.  $U$  is bounded &  $\text{Supp } f \subset V$ .

Def.  $\int_M f dV := \int_{\text{Int } U} (f \circ \alpha) V(D\alpha)(x) dx_1 \dots dx_n$

$\leftarrow$  Volume form

an integral over an open & bounded subset of  $\mathbb{R}^n$ .

So:  $V^2(D\alpha)(x) = \sum_{[I]} \det^2(D\alpha)_I$

$$\det^2 \begin{pmatrix} \frac{\partial x_{i_1}}{\partial x_1} & \dots & \frac{\partial x_{i_1}}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial x_{i_n}}{\partial x_1} & \dots & \frac{\partial x_{i_n}}{\partial x_n} \end{pmatrix}$$

Remark:  $\int_M f dV$  exists as an ordinary integral:

•  $\int_{\text{Int } U}$  — bounded

•  $F(x_1, \dots, x_n) = f(\alpha(x_1, \dots, x_n)) \cdot V(D\alpha)(x_1, \dots, x_n) \in C_0(\mathbb{R}^n)$

Lemma: (" $\int_M f dV$  is well-defd")

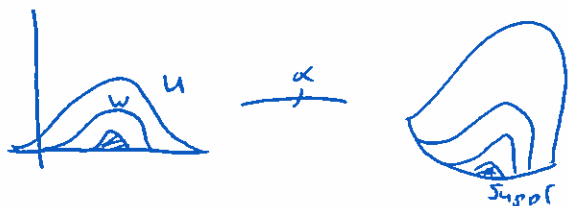
(-1)  $M$  is cpct  $k$ -mfd  $M$  of class  $C^r$

$f: M \rightarrow \mathbb{R}$  continuous;  $\text{Supp } f \subset V$  for a single chart  $\alpha: U \rightarrow V$ .

(0)  $\int_M f dV$  does not depend on choice of coord. chart.

Pf: Step 1: (Independence of range of  $\alpha$ ):

let  $W$  be open set in  $U$  s.t.  $\text{Supp } f \subset \alpha(W)$



$$\int_{\text{Int } U} (f \circ \alpha)(x) V(D\alpha)(x) dx = \int_{\text{Int } W} \text{same} + \int_{\text{Int } U \setminus \text{Int } W} \text{same} = \int_{\text{Int } W} (f \circ \alpha)(x) V(D\alpha)(x) dx$$

$f=0$

Step 2: (Independence of choice of  $\alpha$ ).

let  $\alpha_0: U_0 \rightarrow V_0$   
 $\alpha_1: U_1 \rightarrow V_1$  s.t.

$\text{Supp } f \cap V_0 \cap V_1 \neq \emptyset$ .

Sep 26

Recall from last time:

- $M$  cpt  $k$ -mfd in  $\mathbb{R}^n$ , class  $C^r$
- $f: M \rightarrow \mathbb{R}$ , continuous
- $\text{Supp } f$  contained in single chart  $\alpha: U \rightarrow V$  & w.l.o.g.  $U$  bounded open set in  $\mathbb{H}^k$  & sufficiently regular volume fact to support a notion of Riemann integral

Def:  $\int_M f dV = \int_{\text{Int } U} (f \circ \alpha) |V(D\alpha)| dx_1 \dots dx_k$   
 Riemann Integral over a bdd open set in  $\mathbb{R}^k$

Lemma: def. above does not depend on choice of coord. chart.

Pf: Step 1:  $\int_{\text{Int } U} f dV = \int_{\text{Int } W} f dV$  for any two open sets in  $\mathbb{R}^k$  w/  $\text{Supp } f \subset U, W$

Step 2: (Independence of  $\alpha$ ): Let  $\alpha_0: U_0 \rightarrow V_0$  &  $\alpha_1: U_1 \rightarrow V_1$  s.t.

$\text{Supp } f \subset V_0 \cap V_1$ .

Claim:  $\int_{\text{Int } U_0} (f \circ \alpha_0) |V(D\alpha_0)| dx_1 \dots dx_k = \int_{\text{Int } U_1} (f \circ \alpha_1) |V(D\alpha_1)| dy_1 \dots dy_k$

Pf of claim: Set  $V := V_0 \cap V_1$ ,  $W_i := \alpha_i^{-1}(V) \subset U_i$ ,  $i=0,1$

By Step 1: Enough to show that

$$\int_{\text{Int } U_0} f \circ \alpha_0 = \int_{\text{Int } \alpha_0^{-1}(V)} (f \circ \alpha_0) |V(D\alpha_0)| dx \stackrel{?}{=} \int_{\text{Int } \alpha_1^{-1}(V)} (f \circ \alpha_1) |V(D\alpha_1)| dy \stackrel{\text{Step 1}}{=} \int_{\text{Int } U_1} f \circ \alpha_1 = \int_{\text{Int } U_1} f dV$$

Pf is by Change of Var. Formula for integrals in  $\mathbb{R}^k$ , b/c we know

$g := \alpha_1^{-1} \circ \alpha_0 : \text{Int } W_0 \rightarrow \text{Int } W_1$  is a diffeom., so:

$$\int_{\text{Int } \alpha_1^{-1}(V)} (f \circ \alpha_1)(y) |V(D\alpha_1)(y)| dy = \int_{\text{Int } (\alpha_0^{-1}(V))} (f \circ \alpha_1)(\alpha_0(x)) \underbrace{|V(D\alpha_1)(g(x))|}_{= V(D\alpha_0)(x)} |\det Dg(x)| dx$$

$y = g(x) = \alpha_1^{-1} \circ \alpha_0(x)$

check!!

Def. of  $\int_M f dV$  for cpct  $k$ -mfd  $M$  in  $\mathbb{R}^n$  in case where

Supp  $f$  not contained in single chart

Need notion of partition of unity fitted to  $M$ .

Lemma: (H)  $M$  cpct,  $k$ -mfd in  $\mathbb{R}^n$ , class  $C^r$

$M \subseteq V_1 \cup \dots \cup V_N$  with  $\alpha_i : U_i \rightarrow V_i$  coord. charts

(C)  $\exists \{\varphi_1, \dots, \varphi_N\} \subset C_0^\infty(\mathbb{R}^n, \mathbb{R})$  i.e.  $\varphi_i : \mathbb{R}^n \rightarrow \mathbb{R}$ , s.t.

(1)  $\varphi_i(x) \geq 0 \quad \forall x \in \mathbb{R}^n \quad \forall i \in \{1, \dots, N\} = I$

(2)  $\forall i \in I \quad \exists \alpha_i : U_i \rightarrow V_i$  s.t.  $\text{Supp } \varphi_i \cap M \subset V_i$

(3)  $\sum_i \varphi_i(x) = 1 \quad \forall x \in M$

Pf.  $\varphi_i =$  partition of unity dominated by  $\tilde{V}_i$  where  $\tilde{V}_i$

open in  $\mathbb{R}^n$  s.t.  $V_i = \tilde{V}_i \cap M$ . □

Def. Let  $M$  be a cpct  $k$ -mfd in  $\mathbb{R}^n$ , class  $C^k$ , let  $f : M \rightarrow \mathbb{R}$

continuous.

(\*)  $\int_M f dV := \sum_{i=1}^N \int_M (f \circ \varphi_i) dV$  "new defn" ← pointwise mult.

where  $\{\varphi_1, \dots, \varphi_N\}$  is a part. of unity subordinated to an (same, any) atlas for  $M$ .

Remarks: (1) If Supp  $f$  lies indeed in single chart  $\alpha : U \rightarrow V$

then "new def" agrees with "original def":

Call  $A = \text{Int } U$  (open in  $\mathbb{R}^n$ )

$$\begin{aligned} \sum_{i=1}^N \int_M (\varphi_i f) dV &= \sum_{i=1}^N \int_{\text{Int } U} (\varphi_i \circ \alpha)(x) (f \circ \alpha)(x) V(D\alpha) dx \\ &= \int_{\text{Int } U} \underbrace{\left( \sum_{i=1}^N (\varphi_i \circ \alpha)(x) \right)}_{=1 \text{ } (\varphi_i \text{ are part. of unity})} (f \circ \alpha)(x) V(D\alpha) dx \\ &= \int_{\text{Int } U} (f \circ \alpha)(x) V(D\alpha)(x) dx \\ &\quad \text{"old def"} \end{aligned}$$

□

(2) New def (\*) is indep. of choice of part. of unity.

Let  $\{\varphi_i\}, \{\psi_j\}$  be two part. of unity.

By Remark (1) for  $\psi_j f$  ( $f$  &  $\psi_j$ )

$$\sum_i \int_M \varphi_i (\psi_j f) dV = \int_M \psi_j f dV \quad \underline{V_j}$$

$$\Rightarrow \sum_{i,j} \int_M (\varphi_i \psi_j f) dV = \sum_i \int_M \psi_j f dV \quad (a)$$

By same token (switch  $\psi_j$  &  $\varphi_i$ ):

$$\sum_i \int_M \psi_j (\varphi_i f) dV = \int_M \varphi_i f dV \quad \underline{V_i}$$

$$\sum_{i,j} \int_M (\psi_j \varphi_i f) dV = \sum_i \int_M \varphi_i f dV \quad (b)$$

Comparing (a) and (b) (which have same left hand sides) get

$$\sum_i \int_M \varphi_i f dV = \sum_j \int_M \psi_j f dV.$$

Thm: (linearity of  $\int_M$ ):

$$\int_M (af + bg) dV = a \int_M f dV + b \int_M g dV \quad \forall a, b \in \mathbb{C} \quad \forall f, g: M \rightarrow \mathbb{R} \text{ cont.} \quad \square$$

Note: Our current def of  $\int_M f dV$ , although rigorous & robust, is difficult to implement

(need to compute part of unity,  $\rho_i$ ; need to integrate product of  $\rho_i$  &  $f$ )

Need a more practical algorithm (method), which requires:

Def:  $M$  cpt mfd in  $\mathbb{R}^n$ , class  $C^\infty$ .  
 $D \subset M$  (a given subset of  $M$ ).

We say that  $D$  has zero measure in  $M$  if  $\exists$  atlas  $\{\alpha_i, U_i, V_i\}$  s.t.  $D$  covered by (countably many) charts  $\alpha_i: U_i \rightarrow V_i$ , lie.  $D \subset \cup_i V_i$ .

s.t.  $D_i := \alpha_i^{-1}(D \cap V_i) \subset \mathbb{R}^k$  has zero-Euclidean measure in  $\mathbb{R}^k$ ,  $\forall i$ .

Equivalently:  $\forall$  atlas,  $\forall$  chart in atlas,  $\alpha: U \rightarrow V$   $\alpha^{-1}(D \cap V)$  has zero meas. in  $\mathbb{R}^k$ . Check!  $\square$

Remark: if  $M$  has boundary  $\partial M$ , then  $\partial M$  has zero-measure in  $M$  b/c we know that  $\forall V$  s.t.  $\partial M \cap V \neq \emptyset$ , we have:

$$\alpha^{-1}(\partial M \cap V) \subset \underline{\mathbb{R}^{k-1} \times \{0\}}$$

a zero-meas. subset of  $\mathbb{R}^k$ .

Computationally friendly tool:

Thm:  $\textcircled{H}$   $M$  cpt  $k$ -mfd in  $\mathbb{R}^n$ ;  $f: M \rightarrow \mathbb{R}$  cont.

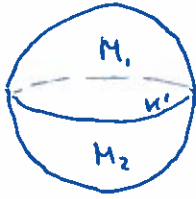
$\alpha_i: A_i \rightarrow M_i$  are charts ( $i=1, \dots, N$ ) s.t.

- $A_i$  is open in  $\mathbb{R}^k$ , &
- $M = M_1 \cup \dots \cup M_N \cup K$  with  $K \subset M$  a set of measure zero in  $M$ .

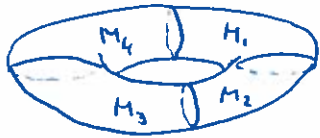


$$\textcircled{c} \int_M f dV = \sum_{i=1}^N \int_{A_i} (f \circ \alpha_i) V(D\alpha_i) \quad (**)$$

ex:  $M = S^2 \subseteq \mathbb{R}^3$



$M_i$  = upper & lower hemispheres  
 $K$  = equator  
 $A_1 = A_2 = D_1(0) \subset \mathbb{R}^2$ .



$K$  = union of four circles.

Def:  $M_i$  called a parametrized mfd (atlas is single chart)

Thm says that  $\int_M f dV$  can be computed by cutting up  $M$  into parametrized mfds ("pieces") and integrating on each piece separately.

Think of  $\{M_i\}_{i=1, \dots, r}$  as a "tiling" of  $M$  & think of  $K$  as the "grout" between your tiles.

Note: if  $\partial M \neq \emptyset$  then  $\partial M \subset K$  (b/c the  $A_i$  are open in  $\mathbb{R}^k$ ).

Pf of Thm: since both sides of (\*\*\*) are linear in  $f$ , wlog

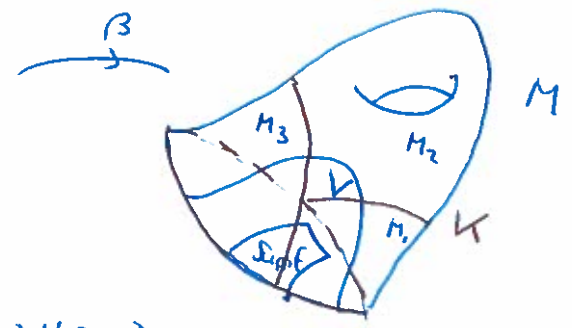
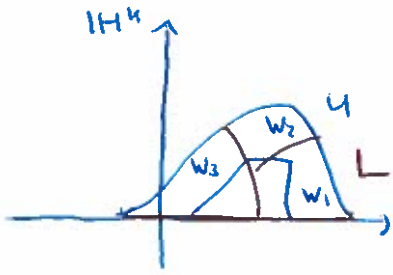
may assume that  $\text{Supp } f$  is contained in single chart:  
 (use part. of unity)

$\beta: U \rightarrow V$  &  $U$  is bounded. Thus:

$$\int_M f dV = \int_{\text{Int } U} (f \circ \beta) V(D\beta).$$

Step 1: Set  $W_i := \beta^{-1}(M_i \cap V)$  &  $L := \beta^{-1}(K \cap V)$ .

Then  $W_i$  open in  $\mathbb{R}^k$  (b/c  $W_i \subset A_i$  open in  $\mathbb{R}^k$  by (H))  
 &  $L$  has zero measure in  $\mathbb{R}^k$  (by (F))



Claim:  $\int_M f dV = \sum_{i=1}^N \int_{W_i} \underbrace{(f \circ \beta)}_{=: F} V(D\beta).$

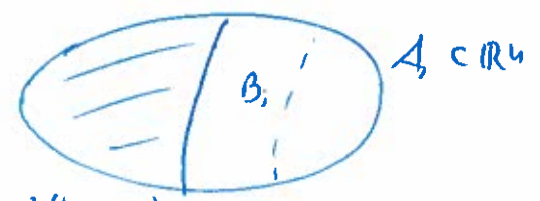
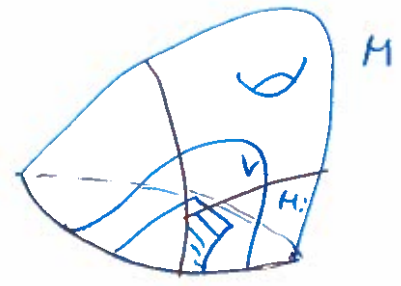
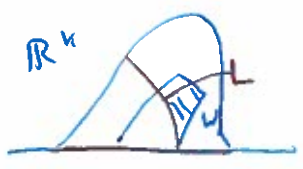
Then:  $\sum_{i=1}^N \int_{W_i} F = \int_{\text{ht } U \cup L} F$  (def of  $W_i$ ; def  $L$ ; additivity of integral)

$= \int_{\text{ht } U} F$  ( $L$  has 0-meas. in  $\mathbb{R}^k$  &  $F$  cont. on  $U$ )

$= \int_M f dV$  (def of  $\int_M$  &  $\oplus f$ )

Step 2: Claim:  $\int_{W_i} F = \int_{A_i} F_i, F_i = (f \circ \alpha_i) V(D\alpha_i)$

Consider:  $\alpha_i^{-1} \circ \beta$  (e.g. focus on  $W_i$ )



Then:  $\beta \circ \alpha_i^{-1}$  is a diffeom. :  $W_i \rightarrow \alpha_i^{-1}(M \cap V) =: B_i$

$H_i$  onto

Recall from last time:

$M$  cpct  $k$ -mfd in  $\mathbb{R}^n$  of class  $C^r$ ,  $f: M \rightarrow \mathbb{R}$  continuous

$\{\beta_i, U_i, V_i\}$  atlas for  $M$ ,  $\{\psi_i\}_{i=1, \dots, N}$  partition of unity on  $M$  dominated by atlas.

$$\int_M f dV := \int_V (f \circ \beta) V(D\beta) dx_1 \dots dx_k, \text{ if } \text{supp } f \subset V \text{ (one chart)}$$

$$\sum_{i=1}^N \int_{U_i} (f \circ \beta_i)(x) |\psi_i \circ \beta_i^{-1}(x)| V(D\beta_i) dx_1 \dots dx_k, \text{ otherwise}$$

Thm: (H)  $M$  cpct  $k$ -mfd in  $\mathbb{R}^n$ , class  $C^r$ ,  $f: M \rightarrow \mathbb{R}$  cont.

$\alpha_i: A_i \rightarrow M$  charts st.  $\cdot A_i$  open in  $\mathbb{R}^k$   
 $\cdot M = \bigcup_{i=1}^N M_i \cup K$ ,  $K$  zero meas. in  $M$

(C)  $\int_M f dV = \sum_{i=1}^N \int_{A_i} (f \circ \alpha_i) V(D\alpha_i)$

Pf of Thm: to show:  $\int_M f dV = \sum_i \int_{A_i} F_i$  (\*)

wlog: assume  $f \circ \beta: U \rightarrow \mathbb{R}$  (single chart; then invoke linearity of l.h.s. R of Rhs of (\*)).

to show:  $\int_{M \cap U} \underbrace{(f \circ \beta) V(D\beta)}_{=: F} dx = \sum_i \int_{A_i} F_i$   
 $\uparrow$   
given (def.)

Step 1: Show:  $\int_{M \cap U} F = \sum_i \int_{W_i} F dx$ , where:

$W_i = \beta^{-1}(M \cap V)$  (is open in  $\mathbb{R}^k$  b/c  $\subset A_i$  open by (H)).

Step 2:  $\int_{W_i} F dx = \int_{A_i} F_i$ ,  $F_i = (f \circ \alpha_i) V(D\alpha_i)$

Consider:  $g = \alpha_i^{-1} \circ \beta: W_i \rightarrow \alpha_i^{-1}(M \cap V) =: B_i$  diffeom. (see last picture from last time)  
 $\beta^{-1}(M \cap V)$

Then  $\int_{B_i} F_i(x) dx = \int_{W_i} (f \circ \beta)(x) \underbrace{V(D\beta)(x)}_{\text{check!}} dx = \int_{W_i} F_i$   
 $y = g(x) = \alpha_i^{-1}(\beta(x))$

Thus:  $\int_{W_i} F = \int_{B_i} F$

Moreover, since  $\text{Supp } f$  closed in  $M$ , then  $\alpha_i^{-1}(\text{Supp } f)$  closed

in  $A_i$ , so:  $D_i := A_i \setminus \alpha_i^{-1}(\text{Supp } f)$  open in  $A_i$  ( $\therefore$  in  $\mathbb{R}^k$ )

So:  $\int_{A_i} F_i = \int_{B_i} F_i + \underbrace{\int_{D_i} F_i - \int_{B_i \cap D_i} F_i}_{=0-0 \text{ since } \text{Supp } F \subset B_i}$   
 $A_i = B_i \cup D_i \setminus (B_i \cap D_i)$

Summary:

$$\int_M f dV \stackrel{\text{Step 1}}{=} \sum_{i=1}^N \int_{W_i} F \stackrel{\text{Step 2}}{=} \sum_i \int_{A_i} F_i$$

Ex: Compute surface area of  $M = S^2(a) = \{(x,y,z) \mid x^2 + y^2 + z^2 = a^2\}$

$\text{Area}(S^2(a)) = \int_{S^2(a)} 1 dV$  ( $S^2 = \text{cpct 2-mfld in } \mathbb{R}^3$ ,  $f=1$ )

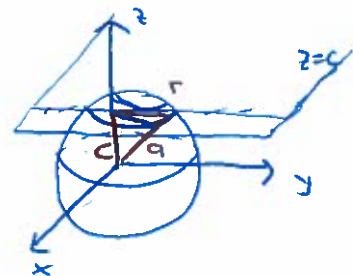
We may implement "Thm" in two different ways:

Method 1: use 2-tiling of  $S^2$  from last time ( $A_1, A_2$ : hemispheres,  $W$ =equator)

Method 2: use another tiling of  $S^2(a)$ , as follows:

note:  $S^2(a) \cap \{z=c\}$ ,  $|c| < a$ :  
 = circle, radius  $\rho^2 = a^2 - c^2$

$$= \begin{cases} x^2 + y^2 = a^2 - c^2 \\ z = c \end{cases}$$

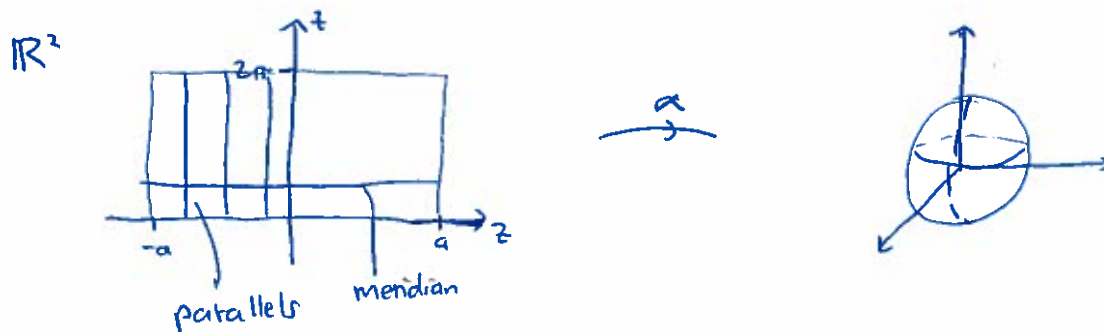


"Inspired" by this picture, we realize that  $S^2(a)$  may be tiled

as follows:  $\alpha(t, z) := ((a^2 - z^2)^{1/2} \cos t, (a^2 - z^2)^{1/2} \sin t, z)$

$(t, z) \in A_i = \{(t, z) \in \mathbb{R}^2 \mid 0 < t < 2\pi, |z| < a\}$  open in  $\mathbb{R}^2$

$\alpha = \left\{ \begin{matrix} ((a^2 - z^2)^{1/2} \cos t, (a^2 - z^2)^{1/2} \sin t, z) \\ t=0 \text{ \& } t=2\pi \end{matrix} \right\}$



$$\text{Surf} (S^2(a)) = \int_A V(D\alpha) dx$$

• Compute  $D\alpha$

• Compute  $V(D\alpha)$  check:  $V(D\alpha) = a$

$$\text{get: } \text{Surf} (S^2(a)) = \int_{(0, 2\pi) \times (-a, a)} a dz dt = a \cdot 2\pi \cdot (2a) = 4\pi^2 a^2 \quad \text{!}$$

Check: that 2-tile thing (hemispheres) gives same answer.

[Check: torus, area]

### Differential forms

Goal: extend "vector integral calculus" (Green's thm, div thm, Stokes thm)

from: Surfaces in  $\mathbb{R}^3$ ; to: cpct  $k$ -mflds in  $\mathbb{R}^n$

Tool for vector calculus in  $\mathbb{R}^3$ :

linear algebra: (vector fields acting on flds;  $\nabla$ ,  $\text{Curl}$ )

Tool for vector calculus on  $k$ -mfld in  $\mathbb{R}^n$ :

Multi-linear Algebra:  $k$ -tensors acting on differential forms

Multi-linear Algebra: a survey.

Given any two positive integers,  $k$  &  $n$ :

Def. ( $k$ -tensor) : Let  $V$  be an  $n$ -dim. v.s. over  $\mathbb{R}$ .

$$\text{Let } V^k = \underbrace{V \times \dots \times V}_{k\text{-many}} = \{ (\vec{v}_1, \dots, \vec{v}_k) \mid \vec{v}_j \in V, j=1, \dots, k \}$$

Given :  $f: V^k \rightarrow \mathbb{R}$  we say that  $f$  is a  $k$ -tensor on  $V$

if  $\forall i \in \{1, \dots, k\}, \forall \vec{a}_j \in V, j=1, \dots, i-1, i+1, \dots, k,$

we have that

$$\vec{v} \in V \rightarrow f(\vec{a}_1, \dots, \vec{a}_{i-1}, \vec{v}, \vec{a}_{i+1}, \dots, \vec{a}_k)$$

is a linear transformation :  $V \rightarrow \mathbb{R} \quad \forall i, \forall \vec{a}_j$

( $k$ -tensors also called multilinear transf.)

Notation:  $\mathcal{L}^k(V) = \{ \text{all } k\text{-tensors on } V \}$

Remarks:

- $k=1 \Rightarrow \mathcal{L}^1(V) = \{ \text{all linear transf. } V \rightarrow \mathbb{R} \} = V^*$  (dual space of  $V$ )
- $k=2 \Rightarrow \mathcal{L}^2(V) = \{ \text{bilinear transformations : } V \times V \rightarrow \mathbb{R} \}$
- check:  $k$ -tensor on  $V=\mathbb{R} = 1$ -tensor on  $V=\mathbb{R}^n$

Ex:  $\forall i \in \{1, \dots, k\}; \forall j \in \{1, \dots, n\} \quad \forall V$  (ndim.)

$$f_{ij}(\vec{v}_1, \dots, \vec{v}_k) := v_{ij} \quad (j\text{-th component of } \vec{v}_i)$$

Thm:  $\mathcal{L}^k(V)$  is a vector space over  $\mathbb{R}$  via:

$$(f+g)(\vec{v}_1, \dots, \vec{v}_k) := f(\vec{v}_1, \dots, \vec{v}_k) + g(\vec{v}_1, \dots, \vec{v}_k)$$

tensor sum " $+$ "

$$(cf)(\vec{v}_1, \dots, \vec{v}_k) = c f(\vec{v}_1, \dots, \vec{v}_k)$$

| prod. by scalar
| product in  $\mathbb{R}$

PF: Check!

Lemma: (H)  $\{\vec{a}_1, \dots, \vec{a}_n\}$  is a basis for  $V$ .

$f, g \in \mathcal{L}^k(V)$  s.t.  $\forall I := \{i_1, \dots, i_k\} \subset \{1, \dots, n\}$  we have

$$f(\vec{a}_{i_1}, \dots, \vec{a}_{i_k}) = g(\vec{a}_{i_1}, \dots, \vec{a}_{i_k})$$

$$\textcircled{C} \quad f(\vec{v}_1, \dots, \vec{v}_k) = g(\vec{v}_1, \dots, \vec{v}_k) \quad \forall \vec{v}_j \in V.$$

Note: no preassigned ordering of elts of  $\mathbb{R}^I$   
no requirements that elts of  $I$  be distinct.

Pf: Check!! □

Thm: (basis for  $\mathcal{L}^k(V)$ ):

$$\textcircled{H} \quad \{\vec{a}_1, \dots, \vec{a}_n\} \text{ basis for } V$$

$$I = \{i_1, \dots, i_k\} \subset \{1, \dots, n\}$$

(no preassigned order, repetitions allowed within  $I$ )

$$\textcircled{C} \quad \exists! \quad \varphi_I \in \mathcal{L}^k(V) \text{ s.t.}$$

$$\forall J = \{j_1, \dots, j_k\} \subset \{1, \dots, n\} \text{ we have:}$$

$$\textcircled{*} \quad \varphi_I(\vec{a}_{j_1}, \dots, \vec{a}_{j_k}) = \begin{cases} 1, & I=J \\ 0, & I \neq J \end{cases}$$

Furthermore,  $\{\varphi_I\}_I$  are a basis for  $\mathcal{L}^k(V)$

The  $\varphi_I$ 's are called: elementary  $k$ -tensors on  $V$

corresponding to basis  $\{\vec{a}_1, \dots, \vec{a}_n\}$  for  $V$ .

Note:  $|\{\text{distinct } k\text{-tuples from } \{1, \dots, n\}\}| = n^k$  (check!!)

eg.  $k=2, n=3$

12, 21  
13, 31  
23, 32

$$q = 3^2$$

$k=3, n=2$

112, 121, 211  
122, 212, 221  
222, 111

$$r = 2^3.$$

Also 11, 22, 33

Pf. Step 1: Prove uniqueness: follows from preceding lemma.

Step 2: prove  $\exists$  existence:

Case 1:  $k=1$   $\mathcal{L}^1(V) = V^*$ ;  $I = \{1\}; \{2\}; \dots; \{n\}$

Linear Algebra says we can determine any linear transf.

$f: V \rightarrow \mathbb{R}$  by specifying its values on (some) basis of  $V$ .

So we define  $\varphi_i(\vec{a}_j) = \begin{cases} 0, & i \neq j \\ 1, & i = j \end{cases} \quad \forall i, j = 1, \dots, n.$   
(\*\*) these are the clearest 1-tensors.

General case:  $k \geq 2$ .  $I = \{i_1, \dots, i_k\} \subset \{1, \dots, n\}$  (repetition allowed) etc.

Def.  $\varphi_I(\vec{v}_1, \dots, \vec{v}_k) := \varphi_{i_1}(\vec{v}_1) \cdot \varphi_{i_2}(\vec{v}_2) \cdot \dots \cdot \varphi_{i_k}(\vec{v}_k)$   
def. in Case 1 (k=1) ← product in  $\mathbb{R}$

Check: (1)  $\varphi_I$  satisfies (\*\*) immediate from (\*\*)

(2)  $\{\varphi_I\}_I$  are a basis for  $\mathcal{L}^k(V) \stackrel{\text{linearly indep}}{\text{generate}} \mathcal{L}^k(V)$

use lemma. □

Corollary: (H)  $\{\vec{a}_1, \dots, \vec{a}_n\}$  basis for  $V$

(C)  $\forall I = \{i_1, \dots, i_k\} \subset \{1, \dots, n\}$  (reps. allowed etc.)

$\forall d_I \in \mathbb{R} \quad \exists! f \in \mathcal{L}^k(V)$  s.t.  $f_I(\vec{a}_{i_1}, \dots, \vec{a}_{i_k}) = d_I.$

Thus: a  $k$ -tensor is determined by specifying its values on all  $k$ -tuples of elts from (any) basis of  $V$ .

Oct 3

Recall from last time:

- $k, n \in \mathbb{Z}^+$ ,  $V := n$ -dim vector-space over  $\mathbb{R}$
- $\mathcal{L}^k(V) = \{k\text{-tensors on } V\} = \{\text{tensors of order } k \text{ on } V\}$  (a vs. over  $\mathbb{R}$ )



k-tensors: multilin. transf.:  $\frac{V \times \dots \times V \rightarrow \mathbb{R}}{k\text{-linear}}$

•  $k=1 \rightarrow \mathcal{L}^1(V) = V^*$

•  $k=2 \rightarrow \mathcal{L}^2(V) = \{\text{bilinear transf. on } V\}$

• Basis for  $\mathcal{L}^k(V)$  (given by basis for  $V = \{\vec{a}_1, \dots, \vec{a}_n\}$ ) is the set

$$\left\{ \underbrace{\varphi_I}_{\text{elementary } k\text{-tensor, where:}} \mid I = \{i_1, \dots, i_k\} \subset \{1, \dots, n\} \right\}$$

elementary  
k-tensor, where:

↳ • repts allowed

• all possible orderings allowed

$$\varphi_I(\vec{a}_j, \dots, \vec{a}_{j_k}) = \begin{cases} 1, & j=I \\ 0, & \text{otherwise} \end{cases}$$

$$\dim \mathcal{L}^k(V) = n^k$$

• fact:  $\varphi_I(\vec{v}_1, \dots, \vec{v}_k) = \varphi_{i_1}(\vec{v}_1) \cdots \varphi_{i_k}(\vec{v}_k)$ , where  $\varphi_{i_j} \in \mathcal{L}^1(V)$ ,  $\varphi_{i_j}(\vec{a}_j) = \begin{cases} 1, & i_j=j \\ 0, & \text{otherwise} \end{cases}$

Corollary: (M)  $\{\vec{a}_1, \dots, \vec{a}_n\} = \text{basis for } V$

©  $\forall I = k\text{-subset of } \{1, \dots, n\} \quad \forall d_I \in \mathbb{R} \exists! f \in \mathcal{L}^k(V) \text{ s.t.}$

$$f(\vec{a}_{i_1}, \dots, \vec{a}_{i_k}) = d_I \quad (f := d_I \varphi_I)$$

Ex:  $V = \mathbb{R}^n$  with canonical basis  $\{\vec{e}_1, \dots, \vec{e}_n\}$

•  $k=1$  let  $\{\varphi_1, \dots, \varphi_n\}$  be dual basis of  $\mathcal{L}^1(V) = V^*$

(ie.  $\varphi_i(\vec{e}_j) = \delta_{ij}$ ). Writing  $\vec{x} = x_1 \vec{e}_1 + \dots + x_n \vec{e}_n$  get:  $\varphi_i(\vec{x}) = x_i$

( $\varphi_i = \text{projection onto } i\text{-th coord.}$ )

•  $k \geq 2$ :  $I = \{i_1, \dots, i_k\}$  Then:  $\varphi_I(\vec{x}_1, \dots, \vec{x}_k) = \underbrace{\varphi_{i_1}(\vec{x}_1)}_{x_{i_1,1}} \cdot \underbrace{\varphi_{i_2}(\vec{x}_2)}_{x_{i_2,2}} \cdots \underbrace{\varphi_{i_k}(\vec{x}_k)}_{x_{i_k,k}}$

where:  $\vec{x}_i = (x_{i1}, x_{i2}, \dots, x_{in})$  etc.

Thus: elementary k-tensor  $\varphi_I$  is monomial of degree k.

& general k-tensor on  $\mathbb{R}^n$  is linear comb. of such monomials.

eg. • 1-tensors in  $\mathbb{R}^n$ :  $f(\vec{x}) = d_1 x_1 + \dots + d_n x_n$ ,  $d_j \in \mathbb{R}$

- 2-tensors on  $\mathbb{R}^n$ :  $f(\vec{x}, \vec{y}) = \sum_{i,j=1}^n d_{ij} x_i x_j$ ,  $d_{ij} \in \mathbb{R}$
- $k$ -tensor on  $\mathbb{R}^n$ :  $f(\vec{x}_1, \dots, \vec{x}_k) = \sum_{i_1, \dots, i_k=1}^n \underbrace{d_{i_1, \dots, i_k}}_{\in \mathbb{R}} x_{i_1} \dots x_{i_k}$

Ex:  $k=2; n=4$  : 2 tensors in  $\mathbb{R}^4$

$$\begin{array}{ll} 11 & 21 \\ 12 & 22 \\ 13 & 23 \\ 14 & 24 \end{array} \quad \text{etc.}$$

Ex:  $\varphi_{11}(\vec{x}, \vec{y}) = x_1 y_1$ ,  $\varphi_{34}(\vec{x}, \vec{y}) = x_3 y_4$  etc.

• is  $h(\vec{x}, \vec{y}) = x_1 y_1 - 7 x_3 y_3 \in \mathcal{L}^2(\mathbb{R}^4)$ ?

$$= \varphi_{11} - 7 \varphi_{33} \quad \checkmark$$

is  $f(\vec{x}, \vec{y}) := 3 x_1 y_2 - 5 x_3 x_3 \in \mathcal{L}^2(\mathbb{R}^4)$ ?

$\varphi_{12}$   $\uparrow$   $\checkmark$   
not elementary 2-tensor!

## Tensor Product

Def: Let  $f \in \mathcal{L}^k(V)$  &  $g \in \mathcal{L}^l(V)$

$f \otimes g \in \mathcal{L}^{k+l}$  defined as follows:

$$f \otimes g(\vec{v}_1, \dots, \vec{v}_k, \vec{v}_{k+1}, \dots, \vec{v}_{k+l}) = f(\vec{v}_1, \dots, \vec{v}_k) \cdot \underbrace{g(\vec{v}_{k+1}, \dots, \vec{v}_{k+l})}_{\text{product in } \mathbb{R}}$$

Tensor product of  $f$  &  $g$

Thm: (properties of  $\otimes$ ): (H)  $f, g, h$  given tensors on  $V$

(1) (Associativity)  $f \otimes (g \otimes h) = (f \otimes g) \otimes h$

(2) (Homogeneity)  $(cf) \otimes g = f \otimes cg \quad \forall c \in \mathbb{R}$

(3) (Distributivity) Assume that  $f, g$  have same order

$$(f+g) \otimes h = f \otimes h + g \otimes h$$

$\uparrow$   $\uparrow$   $\uparrow$   
 Sum of  $k$ -tensors Sum of  $k+l$ -tensors (if order of  $h = l$ )

$$h \otimes (f+g) = h \otimes f + h \otimes g$$

$\uparrow$   
 Sum of  $k$ -tensors

(4) Let  $\{\vec{a}_1, \dots, \vec{a}_n\}$  be a basis for  $V$  & let  $\varphi_I$  elem. tensor.  
 $I = \{i_1, \dots, i_n\}$ , then  $\varphi_I = \varphi_{i_1} \otimes \dots \otimes \varphi_{i_n}$ .

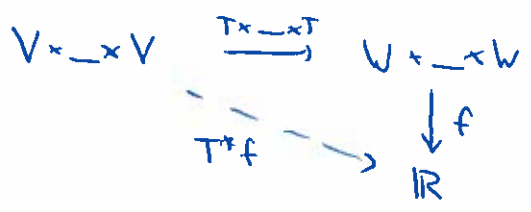
Addition of linear transformations

Let  $V, W$  be two vector spaces on  $\mathbb{R}$ ;  $k \in \mathbb{Z}^+$ .

Let  $T: V \rightarrow W$  be a linear transf.

Def: dual transformation:  $T^*: \mathcal{L}^k(W) \rightarrow \mathcal{L}^k(V)$   
 $f \mapsto T^*f$

where  $(T^*f)(\vec{v}_1, \dots, \vec{v}_k) = f(T\vec{v}_1, \dots, T\vec{v}_k)$  i.e.



Remarks:

•  $\forall f \in \mathcal{L}^k(W)$ ,  $T^*f$  is indeed multi lin.:  $V \times \dots \times V \rightarrow \mathbb{R}$

thw  $T^*f \in \mathcal{L}^k(V)$

•  $T^*: \mathcal{L}^k(W) \rightarrow \mathcal{L}^k(V)$  is multi linear, more precisely:

Thm (linearity of  $T^*$ ),

(H)  $V, W$  any two vector spaces on  $\mathbb{R}$ ,  $T: V \rightarrow W$  lin. transf., dual:  $T^*: \mathcal{L}^k(W) \rightarrow \mathcal{L}^k(V)$ .

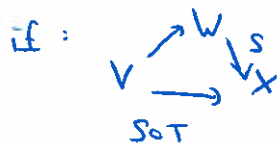
(C)  $T^*$  is linear:  $T^*(af + bg) = aT^*(f) + bT^*(g)$   $\forall a, b \in \mathbb{R}, f, g \in \mathcal{L}^k(W)$   
 $\uparrow$   $\uparrow$   
 lin. comb. of  $k$ -tensors on  $W$  Sum of  $k$ -tensors on  $V$

$$(2) \quad T^*(f \otimes g) = \underbrace{T^*f}_{2k\text{-tensor on } W} \otimes \underbrace{T^*g}_{2k\text{-tensor on } V}$$

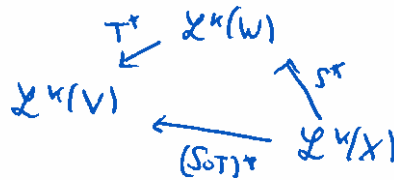
(3) Let  $X$  be a v.s. on  $\mathbb{R}$  &  $S: W \rightarrow X$  be a linear transf. Then:

$$(S \circ T)^* = T^* \circ S^* \quad \text{i.e.} \quad (S \circ T)^*(h) \in \mathcal{L}^k(X) = T^*(\underbrace{S^*h}_{\in \mathcal{L}^k(W)}) \in \mathcal{L}^k(V)$$

That is:



then



Pf. check !!

### A quick review of permutations

Let  $k \in \mathbb{Z}^+, k \geq 2$ . Permutation of  $\{1, \dots, k\}$  is a 1-1 onto fct:

$\sigma: \{1, \dots, k\} \rightarrow \{1, \dots, k\}$  (a rearrangement of the set)

$S_k = \{\text{all permutations of } \{1, \dots, k\}\}$  is a group under composition of functions (Id:  $1 \rightarrow 1, \dots, k \rightarrow k$ )

Note:  $\sigma$  is 1-1  $\Rightarrow$  repetitions not allowed in output

$$i \neq j \Rightarrow \sigma(i) \neq \sigma(j) \quad \Rightarrow \quad |S_k| = k!$$

Def:  $1 \leq i < k$ . Def.  $e_i \in S_k$  as follows:

$$e_i(j) = \begin{cases} j, & j \neq i, i+1 \\ i+1, & j = i \\ i, & j = i+1 \end{cases} \quad \text{elementary (i-th) permutation}$$

Remarks: • Identity  $\neq$  elementary!

•  $k=2 \rightsquigarrow S_2 = \{12, 21\}$ ,  $e_1$  not:  $12 \stackrel{e_1}{\rightarrow} 21 \stackrel{e_1}{\rightarrow} 12$   
so: Id =  $e_1 \circ e_1$ .

Lemma:  $\forall \sigma \in S_k$  is a composition of elementary permutations.

Pf. Check! (Note: Id =  $e_i \circ e_i \quad \forall i \in \{1, \dots, k\}$ .)

Def. (sign of permutation):

Let  $\sigma \in S_k$ .

- Inversion in  $\sigma := \{\text{all pairs } i < j \in \{1, \dots, k\} \text{ s.t. } \sigma(i) > \sigma(j)\}$ .
- Sign of  $\sigma := \begin{cases} -1 & \text{if total \# of inversions of } \sigma \text{ is odd} \\ +1 & \text{--- "--- "--- even} \end{cases}$

Ex:  $k=2$ :  $\text{Id} = \{1, 2\} \rightarrow 12$  even  $\text{sign}(\text{Id}) = +1$

$\sigma_1: \{1, 2\} \rightarrow 21$  odd ( $\sigma(1) > \sigma(2) \therefore \text{sign } \sigma_1 = -1$ )

Ex:  $k=3$ :  $\sigma: \{1, 2, 3\} \rightarrow 213$

$1, 2 \rightarrow 21$  ← inversion  
 $1, 3 \rightarrow 31$  ← no inv.  
 $2, 3 \rightarrow 13$  ← " " " "

$\left. \begin{array}{l} \\ \\ \end{array} \right\} \text{sign}(\sigma) = -1$   
 note:  $\sigma$  is elementary

$\tau: \{1, 2, 3\} \rightarrow 312$

$1, 2 \rightarrow 31$  ← inv.  
 $1, 3 \rightarrow 32$  ← inv.  
 $2, 3 \rightarrow 12$  ← not inv.

$\left. \begin{array}{l} \\ \\ \end{array} \right\} \text{sign}(\tau) = +1$   
 note:  $\tau$  not elem.

but:  $123 \xrightarrow{\sigma_1} 131 \xrightarrow{\sigma_2} 312 : \tau = \sigma_1 \circ \sigma_2$

Ex:  $\sigma \in S_k$  is any elementary permutation check:  $\text{sign } \sigma = -1$

Lemma: (H)  $\sigma, \tau \in S_k$

(1) If  $\tau$  is a composition of  $m$  elementary permutations, then  $\text{sign}(\tau) = (-1)^m$ .

(2)  $\text{sign}(\sigma \circ \tau) = \text{sign}(\sigma) \cdot \text{sign}(\tau)$   
 $\uparrow$  product of signs.

(3) if  $p \neq q$  &  $\tau \in S_k$  s.t.  $\tau_j = \begin{cases} q & \text{if } j=p \\ p & \text{if } j=q \\ j & \text{if } j \neq p, q \end{cases}$

(e.g.  $k=3$ :  $1, 2, 3 \rightarrow 3, 2, 1$ )

then  $\text{sign } \tau = -1$ .

pf: Check! □

Back to  $\mathcal{L}^k(V)$

Alternating k-tensors

Def:  $f \in \mathcal{L}^k(V)$ . We say that

- $f$  is an alternating  $k$ -tensor ("f is alternating") if

$$f(\vec{v}_1, \dots, \vec{v}_{i+1}, \vec{v}_i, \dots, \vec{v}_k) = -f(\vec{v}_1, \dots, \vec{v}_i, \dots, \vec{v}_{i+1}) \quad \forall \vec{v}_j \in V, \forall i=1, \dots, k.$$

Alt. notation:  $f(\sigma_i(\vec{v}_1, \dots, \vec{v}_k)) = -f(\vec{v}_1, \dots, \vec{v}_k)$

$$f^{\sigma_i}(\vec{v}_1, \dots, \vec{v}_k) = -f(\vec{v}_1, \dots, \vec{v}_k) \quad (\text{note: here } \sigma_i := e_i)$$

- $f$  is a symmetric  $k$ -tensor ("f is symmetric") if

$$f^{\sigma_i} = f \quad \forall i=1, \dots, k-1$$

Focus on alternating  $k$ -~~vectors~~ tensors

Ex:  $k=2$ . Then  $S_2 = \{12, 21\}$   
 $\uparrow$   
 $e_1$  the only elem. perm.

so  $f \in \mathcal{L}^2(V)$  is alternating  $\Leftrightarrow f(\vec{v}_2, \vec{v}_1) = -f(\vec{v}_1, \vec{v}_2) \quad \forall \vec{v}_i \in V.$

Def:  $V = \text{v.s. over } \mathbb{R}, k \in \mathbb{Z}^+, k \geq 2.$

$$A^k(V) = \{\text{Alternating } k\text{-tensors on } V\}$$

Fact:  $A^k(V)$  is a vector subspace of  $\mathcal{L}^k(V)$ .

Def:  $V$  v.s. over  $\mathbb{R}, k=1. (S_1 = \{1\})$  identity so no elem. perm.

Define  $A^1(V) = \mathcal{L}^1(V) = V^*$ .

Ex:  $k \geq 2$  &  $f = \varphi_k$  (elem.  $k$ -tensor)

Show that  $\varphi_k \notin A^k(V)$ : check!

Ex: if  $k \geq 2$ : certain linear transf. combinations of elem.  $k$ -tensors

are in  $A^k(V)$ !

For instance:

$$\bullet k=2, V=\mathbb{R}^n, f := \underbrace{\varphi_{ij}}_{\vec{i}} - \underbrace{\varphi_{ji}}_{\vec{j}} \in A^2(V) \quad \forall i, j=1, \dots, n$$

$$\text{and: } f(\vec{x}, \vec{y}) = x_i y_j - x_j y_i = \det \begin{pmatrix} x_i & y_i \\ x_j & y_j \end{pmatrix};$$

from this interpretation of  $f(\vec{x}, \vec{y})$  it follows right away that  $f(\vec{y}, \vec{x}) = -f(\vec{x}, \vec{y})$

$$\bullet k=3, V=\mathbb{R}^n, g(\vec{x}, \vec{y}, \vec{z}) = \det \begin{pmatrix} x_i & y_i & z_i \\ x_j & y_j & z_j \\ x_k & y_k & z_k \end{pmatrix} \in A^3(\mathbb{R}^n) \text{ @}$$

$$g = \varphi_{ijk} + \varphi_{jki} + \varphi_{kij} - \varphi_{jik} - \varphi_{ins} - \varphi_{kji} \quad \cdot \quad \text{Check!!} \quad \square$$

Recall from last time

$$k \in \mathbb{Z}^+, k \geq 2$$

$V = n$ -dim v.s. over  $\mathbb{R}$

$A^k(V) = \{ \text{alternating } k\text{-tensors on } V \} \therefore \text{elements in } A^k(V)$

\* multilinear:  $\underbrace{V \times \dots \times V}_k \rightarrow \mathbb{R}$

(Def:  $f^\sigma(\vec{x}_1, \dots, \vec{x}_n) = f(\vec{x}_{\sigma(1)}, \dots, \vec{x}_{\sigma(n)})$ ,  $f \in \mathcal{L}^k(V)$ ,  $\sigma \in S_n$ )

\*  $f^{e_i} = -f$   $\forall e_i = \text{elementary in } S_n$   $i \leftrightarrow i+1$

$$A^k(V) := V^{\times k} = \mathcal{L}^k(V)$$

Ex:  $V = \mathbb{R}^3$ ,  $k=3$

$$f(\vec{x}_1, \vec{x}_2, \vec{x}_3) = \det[\vec{x}_1, \vec{x}_2, \vec{x}_3] \in A^3(\mathbb{R}^3)$$

Lemma 1: (H)  $V = n$ -dim v.s. over  $\mathbb{R}$ ,  $f \in \mathcal{L}^k(V)$ ,  $\sigma, \tau \in S_n$

(C) (1) The mapping:  $f \rightarrow f^\sigma$  is a linear transf.:  $\mathcal{L}^k(V) \rightarrow \mathcal{L}^k(V)$

$$(af^e + bg^e)^\sigma = af^{\sigma e} + bg^{\sigma e} \quad \forall f, g \in \mathcal{L}^k(V), \forall a, b \in \mathbb{R}$$

also:  $(f^\sigma)^\tau = f^{\tau \circ \sigma}$

(2)  $f \in A^k(V) \Leftrightarrow f^\sigma = (\text{sign } \sigma) f \quad \forall \sigma \in S_n$

Moreover, if  $f \in A^k(V)$  &  $(\vec{v}_1, \dots, \vec{v}_n)$  is s.t.  $\vec{v}_p = \vec{v}_q \exists p \neq q$

(\*)

$$\text{then } f(\vec{v}_1, \dots, \vec{v}_n) = 0$$

Proof of (\*): (only)

Let  $\sigma_{pq} : p \leftrightarrow q$  (fixes every thing else)

then:  $\text{sign } \sigma_{pq} = -1 \Rightarrow \underline{f^{\sigma_{pq}}(\vec{v}) \stackrel{(*)}{=} -f(\vec{v})}$  by (2)

But  $\sigma_{pq}(\vec{v}_1, \dots, \vec{v}_n) = (\vec{v}_{\sigma_{pq}(1)}, \dots, \vec{v}_{\sigma_{pq}(n)}) = (\vec{v}_1, \dots, \vec{v}_n)$   
 $\vec{v}_p = \vec{v}_q$

so  $\underline{f^{\sigma_{pq}}(\vec{v}_1, \dots, \vec{v}_n) = f(\vec{v}_1, \dots, \vec{v}_n)} \Rightarrow f(\vec{v}) = -f(\vec{v}) \Rightarrow f(\vec{v}) = 0$



Corollary: (H)  $V = n$ -dim v.s. over  $\mathbb{R}$ ,  $k \in \mathbb{Z}^+$ ,  $k \geq 2$ ,  $k > n$ .

$$\textcircled{C} A^k(V) = \{0\}$$

Pf. We know any  $f \in \mathcal{L}^k(V)$  is ! determined by its values on all  $k$ -subsets of vectors from  $\{\vec{a}_1, \dots, \vec{a}_n\}$  (basis for  $V$ )

(by specifying  $f(\vec{a}_{j_1}, \dots, \vec{a}_{j_k}) \quad \forall J = \{j_1, \dots, j_k\} \subset \{1, \dots, n\}$ )

Now:  $k > n \Rightarrow J$  must contain repeated labels i.e.  $\exists j_i = j_l$  for  $i \neq l$ .

$\Rightarrow$  by (K) previous lemma:  $f \in A^k(V) \Rightarrow f(\vec{a}_J) = 0 \quad \therefore f \equiv 0 \quad \square$

Notation: ascending  $k$ -tuple is  $J = \{j_1, \dots, j_k\} \subset \{1, \dots, n\}$  s.t.

$$j_i \neq j_l \quad \forall i \neq l \quad \& \quad j_1 < j_2 < \dots < j_k$$

Next:  $f \in A^k(V)$  is completely determined by its values on ascending  $k$ -tuples of  $\{1, \dots, n\}$ .

Lemma: (H)  $2 \leq k \leq n$ ;  $V = n$ -dim. v.s. over  $\mathbb{R}$ , Let  $\{\vec{a}_1, \dots, \vec{a}_n\}$  be a basis for

$f, g \in A^k(V)$  s.t.  $f(\vec{a}_I) = g(\vec{a}_I)$  for any ascending  $k$ -tuple

$I$  in  $\{1, \dots, n\}$

$$\textcircled{C} f = g$$

Pf. enough to show that  $f(\vec{a}_J) = g(\vec{a}_J) \quad \forall J = \text{any } k\text{-tuple of basis element of } V$ .

Case 1:  $j_l = j_m \quad \exists l \neq m \quad \Rightarrow \quad \begin{matrix} J = \{j_1, \dots, j_k\} \\ \text{Coroll.} \quad f(\vec{a}_J) = 0 = g(\vec{a}_J) \end{matrix}$

Case 2:  $j_l \neq j_m \quad \forall l \neq m$ . Let  $\sigma \in S_k$  be the permutation of  $\{j_1, \dots, j_k\}$

that rearranges the labels in increasing order. Call  $\sigma(J) =: I = \{i_1 < \dots < i_k\}$

$$\begin{aligned} f(\vec{a}_I) &= f^\circ(\vec{a}_J) \quad (\text{def } \sigma, \text{ def } f^\circ) \\ &= (\text{sign } \sigma) f(\vec{a}_J) \quad (\text{bc } f \in A^k) \end{aligned}$$

Likewise,  $g(\vec{a}_I) = (\text{sign } \sigma) g(\vec{a}_J)$ , by (H)  $g(\vec{a}_I) = f(\vec{a}_I)$

thus  $f(\vec{a}_J) = g(\vec{a}_J) \Rightarrow f = g$ .  $\square$

Thm: (Basis for  $A^k(V)$ ) ~~is~~

(H)  $2 \leq k \leq n$ ,  $V$   $n$ -dim. v.s. over  $\mathbb{R}$ ,  $\{\vec{a}_1, \dots, \vec{a}_n\}$  basis for  $V$

$I =$  ascending  $k$ -tuple in  $\{1, \dots, n\}$

(C)  $\exists!$   $\psi_I \in A^k$  s.t.  $\forall$  ascending  $k$ -tuple  $J$ :

(\*)  $\psi_I(\vec{a}_J) = \delta_{IJ}$  where in fact

(\*\*)  $\psi_I := \sum_{\sigma \in S_k} (\text{sign } \sigma) \varphi_I^\sigma$  where  $\varphi_I$  is the elementary  $k$ -tensor for  $A^k(V)$  corresponding to  $I$ .

Furthermore,  $\{\psi_I\}_{I \in \mathcal{I}_k}$  is a basis for  $A^k(V)$ .  
 $\leftarrow$  all ascending  $k$ -tuples, only

Def:  $\psi_I$  given by (\*\*) is called elementary alternating  $k$ -tensor on  $V$  corresponding to basis  $\{\vec{a}_1, \dots, \vec{a}_n\}$ .

Proof: ! immediate from Lemma 2 (check!)

$\cdot \exists!$  define  $\psi_I := \sum_{\sigma \in S_k} \text{sign } \sigma (\varphi_I^\sigma)$

Show:  $\psi_I \in A^k(V)$  & (\*)  $\psi_I(\vec{a}_J) = \delta_{IJ} \forall$  ascending  $k$ -tuple  $J$

(i)  $\psi_I \in A^k(V)$ :  $\stackrel{\text{Lemma 1}}{\Leftrightarrow} \psi_I^\tau \stackrel{?}{=} (\text{sign } \tau) \psi_I \forall \tau \in S_k$ .

$$\psi_I^\tau = \sum_{\sigma} (\text{sign } \sigma) (\varphi_I^\sigma)^\tau \quad (\text{linearity})$$

$$= \sum_{\sigma} (\text{sign } \sigma) \varphi_I^{\tau \circ \sigma}$$

$$= \text{sign } \tau \underbrace{\sum_{\sigma} \text{sign}(\tau \circ \sigma) \varphi_I^{\tau \circ \sigma}}_{\psi_I}$$

$$(\text{sign}(\tau \circ \sigma) = \text{sign } \tau \cdot \text{sign } \sigma)$$

$$= \text{sign } \tau \psi_I \quad (\text{def } \psi_I \text{ b/c } \sigma \text{ also spans } S_k).$$

So:  $\psi_I^\tau = \text{sign } \tau \psi_I$ , thus  $\psi_I \in A^k(V)$ .

(ii) Show  $\psi_I(\vec{a}_J) = \delta_{IJ} \quad \forall$  ascending  $k$ -tuples  $I \& J$ .

$$\psi_I(\vec{a}_J) = \sum_{\sigma} \text{sign } \sigma \underbrace{\psi_I(\vec{a}_{\sigma(J)})}_{\neq 0 \Leftrightarrow \exists \sigma \in S_n \text{ s.t. } \sigma(J) = I.}$$

$\neq 0 \Leftrightarrow \exists \sigma \in S_n \text{ s.t. } \sigma(J) = I.$

$\Leftrightarrow I = J \quad \& \quad \sigma = \text{identity}$

$\text{sign } \sigma = (-1)^0 = 1$



$$= 1 \quad (\text{def } \psi_I(\vec{a}_I))$$

$$\therefore \psi_I(\vec{a}_J) = \delta_{IJ}$$

□

(iii) Show:  $\{\psi_I\}_{[I]}$  are basis of  $A^k$ .

i.e. show: any  $f \in A^k(V)$  can be! expressed as a lin. combination

of  $\{\psi_I\}_{[I]}$ : Given  $f \in A^k$ . Def  $d_I := f(\vec{a}_I) \in \mathbb{R} \quad \forall I$  ascending.

$$\text{def: } g := \sum_{[J]} d_J \psi_J$$

Then:  $g(\vec{a}_I) = d_I = f(\vec{a}_I) \quad \forall$  ascending  $I$  (def  $\psi_J$ ; def  $d_J$ ).

So:  $g = f$  (they agree on all ascending  $k$ -tuples of basis vectors.)

Uniqueness follows from lemma. □

Thus:  $\forall f \in A^k(V) \exists!$   $\{d_I\}_{[I]} \subset \mathbb{R}$  s.t.  $f = \sum_{[I]} d_I \psi_I$ .

Def:  $d_I =$  components of  $f$  relative to  $\{\vec{a}_1, \dots, \vec{a}_n\}$ .

Dimension of  $A^k(V)$ :

$$\bullet k=1 \quad \rightarrow A^1(V) = V^n \Rightarrow \dim A^1 = n$$

$$\bullet 2 \leq k \leq n : \dim A^k = |\{\text{all ascending } k\text{-tuples from } \{1, \dots, n\}\}|$$

$\forall k$ -subset of  $\{1, \dots, n\} \exists!$   $k$ -ascending set with same content

as this subset

$$|\{\text{all ascending } k\text{-tuples in } \{1, \dots, n\}\}| = |\{\text{ } k\text{-subsets of } \{1, \dots, n\}\}|$$

$$= \binom{n}{k} = \frac{n!}{k!(n-k)!}$$

$$\dim A^k(V) = \binom{n}{k} \quad \text{if } \dim V = n.$$

Ex: Basis for  $\mathcal{L}^2(\mathbb{R}^4)$

11	21	31	41
(12)	22	32	42
(13)	(23)	33	43
(14)	(24)	(34)	44

Basis for  $A^2(\mathbb{R}^4)$

Most boring situation:  $k=n$

$$\dim \mathcal{L}^n(\mathbb{R}^n) = n^n$$

$$\text{vs. } \dim A^n(\mathbb{R}^n) = \binom{n}{n} = 1$$

Thm (Stability of  $A^k$ )

(H)  $T: V \rightarrow W$  linear transf. between v.s. over  $\mathbb{R}$

$$f \in A^k(W)$$

$$\textcircled{C} T^*f \in A^k(V)$$

$$\begin{array}{ccc} \underbrace{V \times \dots \times V}_k & \xrightarrow{T \times \dots \times T} & \underbrace{W \times \dots \times W}_k \\ & \searrow T^*f & \downarrow f \\ & & \mathbb{R} \end{array}$$

So:  $T^*: \mathcal{L}^k(W) \rightarrow \mathcal{L}^k(V)$   
and  $A^k(W) \rightarrow A^k(V)$

Determinants (def. for arbitrarily sized matrices)

Def:  $V = \mathbb{R}^n$ , basis  $\{\vec{e}_1, \dots, \vec{e}_n\}$ , canonical basis

$$\{\varphi_1, \dots, \varphi_n\} = \text{dual basis} \quad (\text{for } \mathcal{L}^1(\mathbb{R}^n) = A^1(\mathbb{R}^n))$$

$$k=n: \dim A^n(\mathbb{R}^n)^* = 1 = \binom{n}{n}$$

basis: a single alternating elementary  $n$ -tensor:  $\varphi_{(1, \dots, n)}$

Let  $X = [\vec{x}_1, \dots, \vec{x}_n]$  be any  $n \times n$  matrix.

Def:  $\det X := \varphi_{(1, \dots, n)}(\vec{x}_1, \dots, \vec{x}_n)$  (\*)

Fact: (\*) satisfies all axioms of determinant fct as we know them from lin. alg.

(1) linearity on rows / columns  $\Leftrightarrow \varphi_{(1, \dots, n)} \in \mathcal{L}^n(V)$ .

(2) changing sign by switching columns (rows)  $\Leftrightarrow \varphi_{(1, \dots, n)} \in A^n(V)$ .

(3)  $\det X = \sum_{\sigma \in S_n} (\text{sign } \sigma) \underbrace{\varphi_{(1, \dots, n)}(x_{\sigma(1)}, \dots, x_{\sigma(n)})}_{\varphi_{(1, \dots, n)}^\sigma}$  (\*\*)

$$= \sum_{\sigma \in S_n} (\text{sign } \sigma) x_{1\sigma(1)} \cdot x_{2\sigma(2)} \cdot \dots \cdot x_{n\sigma(n)} \quad (\text{def } \varphi_{(1, \dots, n)})$$

"determinant formula" from lin. algebra

Oct 10

Recall from last week

$V = n$ -dim v.s. over  $\mathbb{R}$ .  $\{\vec{a}_1, \dots, \vec{a}_n\} =$  basis for  $V$

$A^k(V) = \{\text{alternating } k\text{-tensors}\}$ ,  $k \geq 2$

$$A^1(V) = \mathcal{L}(V) = V^*$$

$$A^k(V) = \{0\}, k \geq n$$

$$\dim A^k(V) = \binom{n}{k}$$

Basis for  $A^k(V) = \{\varphi_I\}_{I \in \mathcal{I}_k} = \{\text{elem. alternating } k\text{-tensors}\}$   
 ascending  $k$ -tuples in  $\{1, \dots, n\}$ .

$$\psi_{\mathbb{I}}(\vec{v}_{(1, \dots, k)}) = \sum_{\sigma \in S_k} (\text{sign } \sigma) \Phi_{\mathbb{I}}^{\sigma}(\vec{v}_{(1, \dots, k)})$$

notation:  $\vec{v}_{(1, \dots, k)} = (\vec{v}_1, \dots, \vec{v}_k)$ ,  $\vec{v}_j \in \mathbb{R}^n$

where  $\Phi_{\mathbb{I}}$  = elementary  $k$ -tensor (i.e.  $\Phi_{\mathbb{I}}(\vec{a}_j) = \delta_{\mathbb{I}j}$ )

$$\& \Phi_{\mathbb{I}}^{\sigma}(\vec{v}_{(1, \dots, k)}) := \Phi_{\mathbb{I}}(\vec{v}_{(\sigma(1), \dots, \sigma(k))})$$

Recall that:  $\Phi_{\mathbb{I}} = \Phi_{i_1} \otimes \dots \otimes \Phi_{i_k}$ ,  $\Phi_{i_j} \in \mathcal{L}'(V)$ .  $\Phi_{\mathbb{I}}(\vec{v}_{(1, \dots, k)}) = \Phi_{i_1}(\vec{v}_1) \dots \Phi_{i_k}(\vec{v}_k)$

### Determinants

$V = \mathbb{R}^n$ , basis  $\{\vec{e}_1, \dots, \vec{e}_n\}$ ;  $k=n$ ;  $\dim A^n(\mathbb{R}^n) = 1 = \langle \psi_{(1, \dots, n)} \rangle$

$$\forall X \in \mathbb{R}^{n \times n}, \det X \stackrel{\text{def}}{=} \psi_{(1, \dots, n)}(\vec{x}_{(1, \dots, n)}) = \sum_{\sigma \in S_n} \text{sign } \sigma \psi_{(1, \dots, n)}(\vec{x}_{(\sigma(1), \dots, \sigma(n))})$$

$$= \sum_{\sigma \in S_n} \text{sign } \sigma \cdot \underbrace{x_{1, \sigma(1)}}_{\psi_1(\vec{x}_{\sigma(1)})} \cdot \underbrace{x_{2, \sigma(2)}}_{\psi_2(\vec{x}_{\sigma(2)})} \cdot \dots \cdot \underbrace{x_{n, \sigma(n)}}_{\psi_n(\vec{x}_{\sigma(n)})}$$

used as "def'n"  
of  $\det X$  in linear algebra

Now we can say that the  $n \times n$  determinant fct is the elementary alternating  $n$ -tensor on  $\mathbb{R}^n$  relative to canonical basis in  $\mathbb{R}^n$ .

"Conversely":

Thm: (H)  $V = \mathbb{R}^n$ ;  $\{\vec{e}_1, \dots, \vec{e}_n\}$  canonical basis,  $\psi_{\mathbb{I}}$  = elementary alternating  $k$ -tensor on  $\mathbb{R}^n$ .

(C)  $\psi_{\mathbb{I}}(\vec{x}_{(1, \dots, k)}) = \det X_{\mathbb{I}}$  where  $X_{\mathbb{I}}$  is the  $k \times k$  minor of  $n \times k$ -matrix  $X = (\vec{x}_1, \dots, \vec{x}_k) = \vec{x}_{(1, \dots, k)}$

obtained by selecting rows  $i_1, i_2, \dots, i_k$  (in given order)

from all  $n$ -rows of  $X$ .

Ex:  $\dim A^3(\mathbb{R}^4) = \binom{4}{3} = 4$

$$\psi_{\Sigma} \in \{ \psi_{123}, \psi_{124}, \psi_{134}, \psi_{234} \}$$

$$\begin{array}{cccc}
 & \psi_{124} & & \psi_{123} \\
 & \nearrow & \searrow & \\
 x: & x_{11} & \dots & x_{31} \\
 & \searrow & \nearrow & \\
 & x_{12} & & x_{32} \\
 & \nearrow & \searrow & \\
 & x_{13} & & x_{33} \\
 & \searrow & \nearrow & \\
 & x_{14} & \dots & x_{34} \\
 & \uparrow & \uparrow & \uparrow \\
 & x_1 & x_2 & x_3
 \end{array}
 \left. \begin{array}{l} \\ \\ \\ \\ \\ \end{array} \right\} \begin{array}{l} \psi_{123} \\ \psi_{234} \end{array}$$

"Every elem. alt.  $k$ -tensor in  $\mathbb{R}^n$  relative to canonical basis is a  $k \times k$  determinant fct"

The same can be said for elementary alternating  $k$ -tensors  $\psi_{\Sigma}$  on an arbitrary  $n$ -dim. v.s.  $V$  in the sense that  $T_{\psi_{\Sigma}}^{\psi} \in A^k(\mathbb{R}^n)$  is a  $k \times k$ -determinant fct

where  $T: \mathbb{R}^n \rightarrow V$

$\{\vec{e}_1, \dots, \vec{e}_n\} \rightarrow \{\vec{a}_1, \dots, \vec{a}_n\}$  (extended by linearity)

### The Wedge Product

Recall: if  $T: V \rightarrow W$  then

$$T^{\wedge}: \mathcal{L}^k(W) \rightarrow \mathcal{L}^k(V) \quad \text{and}$$

$$T^{\wedge}: A^k(W) \rightarrow A^k(V)$$

Recall:  $\otimes \quad \mathcal{L}^k(V) \times \mathcal{L}^l(V) \rightarrow \mathcal{L}^{k+l}(V)$

$$(f, g) \mapsto f \otimes g (\vec{v}_{1, \dots, k+l}) = f(\vec{v}_{1, \dots, k}) \cdot g(\vec{v}_{k+1, \dots, k+l})$$

However, in general:  $\otimes A^k(V) \times A^l(V) \not\rightarrow A^{k+l}(V) !!!$

Need: new "product" that preserves alternating tensors

& this is the notion of "wedge product"

We have the following:

Thm. (H)  $V = n$ -dim v.s.  $V$  over  $\mathbb{R}$

(C)  $\exists \wedge : A^k(V) \times A^l(V) \rightarrow A^{k+l}(V)$  s.t.  $\forall f \in A^k(V), g \in A^l(V),$

$h \in A^p(V)$  the following holds:

(1) Associativity:  $f \wedge (g \wedge h) = (f \wedge g) \wedge h$

(2) Homogeneity:  $(cf) \wedge g = f \wedge (cg) \quad \forall c \in \mathbb{R}$

(3) Distributivity: if  $k > l$  then  $(f \wedge g) \wedge h = f \wedge (g \wedge h)$   
(w.r.t. tensor sum)  $h \wedge (f+g) = h \wedge f + h \wedge g$

(4) Anti-commutativity:  $g \wedge f = (-1)^{kl} f \wedge g$

(5) Let  $\{\vec{a}_1, \dots, \vec{a}_n\}$  basis for  $V$ ;  $\{\varphi_1, \dots, \varphi_n\}$  dual basis for  $V^*$

Let  $\{\varphi_I\}_{I \in \mathbb{R}} =$  elementary  $k$ -tensors on  $V$

then for any ascending  $k$ -tuple  $I = (i_1, i_2, \dots, i_k)$  we have:

$$\varphi_I = \varphi_{i_1} \wedge \varphi_{i_2} \wedge \dots \wedge \varphi_{i_k} \quad [\text{vgl. } \varphi_I = \varphi_{i_1} \otimes \dots \otimes \varphi_{i_k}]$$

Properties (1)-(5) characterize  $\wedge$  uniquely

Moreover, if:  $T: V \rightarrow W$  (linear transformation of vector spaces)

$\forall f \in A^k(W), g \in A^l(W)$  we have that

$$A^{k+l}(W) \ni T^*(f \wedge g) = T^* f \wedge T^* g \quad \square$$

Corollary: (H)  $f \in A^{2k+1}(V)$  (odd order)

(C)  $f \wedge f = 0$

(Pf)  $f \wedge f \stackrel{(C)}{=} \underbrace{(-1)^{(2k+1)^2}}_{=-1} f \wedge f \Rightarrow 2(f \wedge f) = 0 \quad \square$

Def:  $A: \mathcal{L}^k(V) \rightarrow \mathcal{L}^k(V), f \mapsto Af := \sum_{\sigma \in S_k} (\text{sign } \sigma) f^\sigma$



• Then, in fact:  $A: \mathcal{L}^k(V) \rightarrow \mathcal{L}^k(V)$

i.e.  $(Af)^i = -Af$  all  $f \in \mathcal{L}^k(V)$

check!

• if  $f \in \mathcal{L}^k(V)$  then  $Af = k!f$

• if  $f \in \mathcal{L}^k(V)$  &  $g \in \mathcal{L}^l(V)$  then  $f \wedge g = \frac{1}{k!l!} A(f \otimes g)$

Pf of Thm: a final exam "assignment"



- last two weeks of classes (4 classes)

- 4 assignments: work in pairs; each member talks 40 minutes

- read, understand proof + understandable presentation

## Tangent vectors & differential forms

Recall from multivariable calculus in  $\mathbb{R}^3$ :

"Vector algebra in  $\mathbb{R}^3$ ":

- vector sum
- dot product
- cross product
- scalar fields ( $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ )
- vector fields ( $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ )
- $\vec{\nabla}: \{\text{scalar field}\} \rightarrow \{\text{vector fields}\}$
- $\text{Curl} = \vec{\nabla} \times \vec{F}: \{\text{vector fields}\} \rightarrow \{\text{vector fields}\}$
- $\text{div} = \vec{\nabla} \cdot \vec{F}: \{\text{vector fields}\} \rightarrow \{\text{scalar fields}\}$

Now: "Tensor algebra in  $\mathbb{R}^n$ ":

(in fact:  $p \in M \rightarrow \omega(p) \in \mathcal{A}^k(T_p M)$ )

$\uparrow$   
m-mfld in  $\mathbb{R}^n$

tangent space  
of  $M$  at  $p$  ←

- Tensor sum
- alternating tensors
- wedge product of alternating tensors
- "Alternating tensor field":  $\vec{v} \in V \rightarrow \omega(\vec{v}) \in \mathcal{A}^k$

Alternating tensor fields are also called differential forms

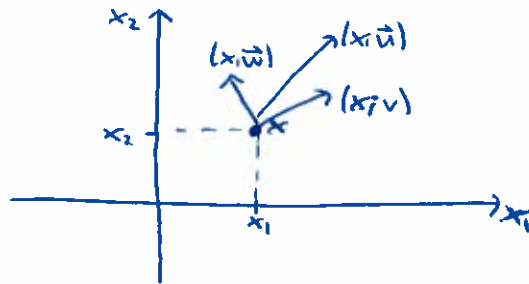
Later: "exterior derivative":  $d: \{\text{differential forms}\} \rightarrow \{\text{differential forms}\}$  ← generalize  
div, Curl,  $\vec{\nabla}$

## Tangent vectors & tangent vector fields

Def: Given  $x \in \mathbb{R}^n$  (a point in the metric space  $\mathbb{R}^n$ )

a "tangent vector to  $\mathbb{R}^n$  at  $x$ " is a pair  $(x, \vec{v})$  where  $\vec{v} \in \mathbb{R}^n$   
(a vector in the vector space  $\mathbb{R}^n$ )

ex:  $n=3$



We represent  $(x, \vec{v})$  as an arrow with same direction as  $\vec{v}$  and initial pt at  $x$

Def: Given  $x \in \mathbb{R}^n$  (a pt in metric space  $\mathbb{R}^n$ ),  $T_x(\mathbb{R}^n) = \{(x, \vec{v}) \mid \vec{v} \text{ any vector in v.s. } \mathbb{R}^n\}$  is the tangent space to  $\mathbb{R}^n$  at  $x$

Facts:  $T_x(\mathbb{R}^n)$  is a v.s.  $W$  over  $\mathbb{R}$  via:  $(x, \vec{v}) + (x, \vec{u}) := (x, \vec{v} + \vec{u})$

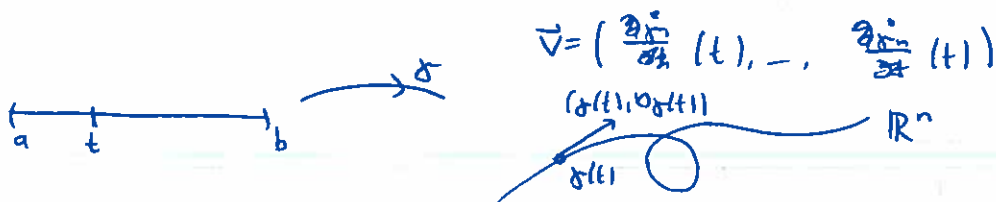
$$c(x, \vec{v}) = (x, c\vec{v}), c \in \mathbb{R}$$

Note:  $T_x: T_x(\mathbb{R}^n) \rightarrow \{x\} \times \mathbb{R}^n$   
 $(x, \vec{e}_j) \mapsto (x, \vec{e}_j)$  is 1-1, onto, linear

$$\dim T_x(\mathbb{R}^n) = n.$$

Def: Given  $(a, b) \subset \mathbb{R}$  (open interval) &  $\gamma: (a, b) \rightarrow \mathbb{R}^n$  (map of class  $C^1$ ),  $t \mapsto \gamma(t)$  (a point in  $\mathbb{R}^n$ )

Velocity vector of  $\gamma$ :  $(\gamma(t), D_t \gamma(t))$



More generally:

Def: given  $U$  open set in  $\mathbb{R}^k$  or  $\mathbb{H}^k$

given  $\alpha: U \rightarrow \mathbb{R}^n$  class  $C^r$

given  $x \in U$

def:  $\alpha_x: T_x(\mathbb{R}^k) \rightarrow T_{\alpha(x)}(\mathbb{R}^n)$  via

$$\alpha_x(x; \vec{v}) := (\alpha(x); \underbrace{D\alpha(x)}_{n \times k} \cdot \underbrace{\vec{v}}_{k \times 1})$$

$\alpha_x$  is called transformation of  <sup>$n \times 1$</sup>  tangent spaces induced by  $\alpha$

Tangent:

vectors  
spaces  
vector fields  
m-tensor fields  
m-forms

} for  $\mathbb{R}^n$  & for a  $k$ -mfd in  $\mathbb{R}^n$

Oct 12

For  $\mathbb{R}^n$ :

Def: Given  $x \in \mathbb{R}^n$  (pt in metric space  $\mathbb{R}^n$ )

"tangent vector to  $\mathbb{R}^n$  at  $x$ " is  $(x; \vec{v})$ , any  $\vec{v} \in \mathbb{R}^n$

(a vector in v.s.  $\mathbb{R}^n$ )

Ex:



$(x; \vec{v})$  represented as an arrow

- initial pt is at  $x$ , "base pt"
- direction = same as  $\vec{v}$

Def:  $T_x(\mathbb{R}^n) = \{(x; \vec{v}) \mid \vec{v} \in \mathbb{R}^n\}$

tangent space to  $\mathbb{R}^n$  at  $x$

Facts:

- $T_x(\mathbb{R}^n)$  v.s. (operations<sup>†</sup> inherited from  $\mathbb{R}^n$  as v.s. e.g.  $(x; \vec{v}) + (x; \vec{u}) = (x; \vec{v} + \vec{u})$  etc.
- $T_x(\mathbb{R}^n) \cong \{x\} \times \mathbb{R}^n$ , via  $T_x: \{x\} \times \mathbb{R}^n \rightarrow T_x(\mathbb{R}^n)$   
 $(x; \vec{e}_j) \mapsto (x; \vec{e}_j)$

$\dim J_x(\mathbb{R}^n) = n \forall x.$

•  $(x, \vec{v}) + (y, \vec{u})$  is undefined

• Interpretation of  $J_x(\mathbb{R}^n)$  as a space of "tangent vectors"

Given  $(a, b) \subset \mathbb{R}$  &  $f: (a, b) \rightarrow \mathbb{R}^n$  (class  $C^1$ )

Let  $x = f(t) \exists t \in (a, b)$ . Then:  $(f(t), (Df)(t)) = \vec{v} = (f_1(t), \dots, f_n(t))$

is tangent vector at  $f(t)$

to curve  $\{f(t)\}_{t \in \mathbb{R}} \subset \mathbb{R}^n$



More generally:

• transformation of tangent spaces:

Given  $U \subset \mathbb{R}^k$  on  $\mathbb{H}^k$ , open set

$\alpha: U \rightarrow \mathbb{R}^n$ , class  $C^1$  (before:  $\alpha = f, k=1$ )

$x \in U$

Def:  $d_x: J_x(\mathbb{R}^k) \rightarrow J_x(\mathbb{R}^n)$

$(x, \vec{v}) \mapsto d_x(x, \vec{v}) = (\alpha(x), \underbrace{D\alpha(x) \cdot \vec{v}}_{\in \mathbb{R}^n})$

...



Pf. Check! (chain rule) □

Lemma: (H)  $U$  open in  $\mathbb{R}^k$  or  $\mathbb{H}^k$ ,  $x \in U$

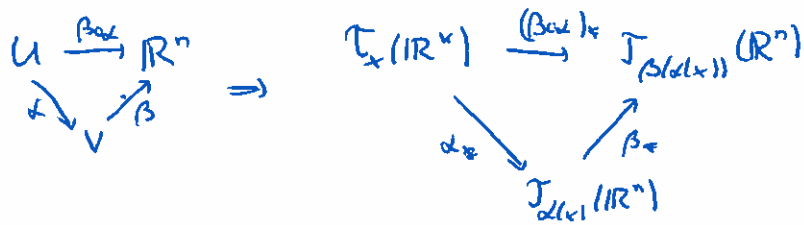
$\alpha: U \rightarrow \mathbb{R}^n$ , class  $C^r$

$V$  open in  $\mathbb{R}^n$ ,  $\alpha(U) \subset V$

$\beta: V \rightarrow \mathbb{R}^m$  (class  $C^r$ )

©  $(\beta \circ \alpha)_x = \beta_x \circ \alpha_x : T_x(\mathbb{R}^k) \rightarrow T_{(\beta \circ \alpha)(x)}(\mathbb{R}^m)$

Pf. Check!  $(\beta \circ \alpha)_x(x, \vec{v}) = \beta_x(\alpha_x(x, \vec{v}))$  i.e.



Tangent vector fields in  $\mathbb{R}^n$  (or  $U \subset \mathbb{R}^n$ , open)

Def: ↪ continuous fct  $F: U \rightarrow \mathbb{R}^n \times \mathbb{R}^n$  s.t.  
 $x \mapsto F(x) \in T_x(\mathbb{R}^n) \quad \forall x \in U$

i.e.,  $F(x) \in \{x\} \times \mathbb{R}^n \quad \forall x \in U$  &  $F(x) = (x, \vec{f}(x)) \quad \exists \vec{f}: U \rightarrow \mathbb{R}^n$

We say that  $F$  is of class  $C^r$  if  $\vec{f}$  so is.

Def: Let  $U \subseteq \mathbb{R}^n$ ; open;  $1 \leq m \leq n$ .

$m$ -tensor field on  $U$  is  $\omega: U \rightarrow \bigcup_{y \in U} \mathcal{L}^m(T_y(\mathbb{R}^n))$

s.t.  $\forall x \in U, \omega(x) \in \mathcal{L}^m(T_x(\mathbb{R}^n))$  ~~we require  $\omega$  to be~~

~~continuous:  $U \rightarrow \bigcup_{y \in U} \mathcal{L}^m$~~

Def: differential form order  $m$  ( $m$ -form;  $m$  co-vector) on  $U$

is an  $m$ -tensor field such that, in fact:

$\forall x \in U, \omega(x) \in \mathcal{A}^m(T_x(\mathbb{R}^n))$  which we require to be

continuous (recall  $A^n / \mathcal{J}_x(\mathbb{R}^n) = \mathbb{R}^{\binom{n}{m}}$ )

So:  $\forall x, \vec{v} \in \mathcal{J}_x(\mathbb{R}^n) \times \mathbb{R}^m \rightarrow \mathbb{R}$  with:

$$((x, \vec{v}_1), \dots, (x, \vec{v}_m)) \mapsto \omega(x) \left( (x, \vec{v}_1), \dots, (x, \vec{v}_m) \right) \in \mathbb{R}$$

s.t.  $(\omega(x))^{\circ} \left( (x, \vec{v}_1), \dots, (x, \vec{v}_m) \right) = \text{sign } \sigma(\omega(x)) \left( (x, \vec{v}_{\sigma(1)}), \dots, (x, \vec{v}_{\sigma(m)}) \right) \in \mathbb{R}$   
 $\forall \sigma \in \mathcal{S}_m$

Definitions for  $M = k\text{-mfd}$  in  $\mathbb{R}^n$

Given:  $M = a$   $k$ -mfd in  $\mathbb{R}^n$

$$p \in M$$

$\alpha: U \rightarrow V$  coord chart about  $p$ , ( $U$  open in  $\mathbb{R}^k$  or  $\mathbb{H}^k$ )

$$p = \alpha(x) \quad \exists x \in U$$

Def: Tangent vector for  $M$  at  $p$ : it's  $\alpha_x(x, \vec{v})$ , any  $\vec{v} \in \mathbb{R}^k$ .

Def: Tangent space to  $M$  at  $p$  is  $\mathcal{J}_p(M) := \alpha_x(\mathcal{J}_x(\mathbb{R}^k))$

$$= \left\{ \underbrace{(p; D\alpha(x) \cdot \vec{v})}_{\alpha(x)} \mid \vec{v} \in \mathbb{R}^k \right\}$$

Notes: (check!) • Def of  $\mathcal{J}_p(M)$  independent of choice of coord. chart about  $p$  (up to isomorphism)

- $\mathcal{J}_p(M) \subset \mathcal{J}_p(\mathbb{R}^n)$

- $\mathcal{J}_p(M)$  is a v.s. & a subspace of  $\mathcal{J}_p(\mathbb{R}^n)$

- If we choose  $\{\vec{e}_1, \dots, \vec{e}_k\}$ , canonical basis for  $\mathbb{R}^k$ , then:

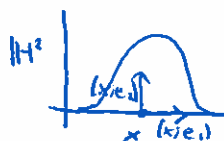
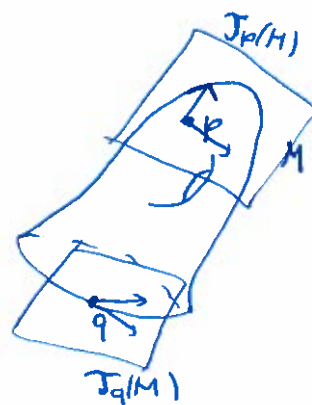
$\mathcal{J}_p(M)$  is spanned by  $\{(p; D\alpha(x) \cdot \vec{e}_j)\}_{j=1, \dots, k}$

$$\vec{u}_j(x) = \frac{\partial \alpha}{\partial x_j}(x) = \left( \frac{\partial \alpha_1}{\partial x_j}(x), \dots, \frac{\partial \alpha_m}{\partial x_j}(x) \right)$$

- $\{(x; \vec{u}_1(x)), \dots, (x; \vec{u}_k(x))\}$  linearly indep. b/c the  $n \times k$  matrix  $D\alpha(x)$  has max rank  $k$ .

So:  $\left\{ \left( x, \frac{\partial x_i}{\partial x_j}(x) \right) \right\}_{j=1 \rightarrow k}$  basis for  $T_p(M)$

e.g.  $k=2; n=3$



Def. Tangent bundle of  $M$  is:  $T(M) = \bigcup_{q \in M} T_q(M)$

Note:  $T_q(M) \cong \{q\} \times \mathbb{R}^k$  then:  $T(M) \cong M \times \mathbb{R}^k$ .

& endow with natural topology

Def. A tangent vector field to  $M$  is a continuous fcl

$$F: M \rightarrow T(M)$$

$$p \mapsto F(p) \in T_p(M), \forall p \in M.$$

Def.  $\forall 1 \leq m \leq k$ ,  $M = k$ -mfd in  $\mathbb{R}^n$ , an  $m$ -tensor field on  $M$

is a map  $\omega: M \rightarrow \bigcup_{q \in M} \mathcal{L}^m(T_q(M))$  s.t.

$$\forall p \in M, \omega(p) \in \mathcal{L}^m(T_p(M)).$$

• differential form of order  $m$  ( $m$ -form;  $m$  covectors) on  $M$ :

is an  $m$ -tensor field on  $M$  s.t.

$$\forall p \in M, \omega(p) \in \mathcal{A}^m(T_p(\mathbb{R}^n)).$$

↑ alternating  $m$ -tensors

s.t.  $\omega$ : continuous:  $M \rightarrow \bigcup_{q \in M} \mathcal{A}^m(T_q(M)) \cong M \times \mathbb{R}^{\binom{k}{m}}$

↑  
endowed w/  
natural topology from

Note:  $\omega(p): T_p(M) \times \dots \times T_p(M) \rightarrow \mathbb{R}$

Fact: if  $\Omega$  is an  $m$ -tensor field on  $U$  open in  $\mathbb{R}^n$

since  $T_p(M) \subset T_p(\mathbb{R}^n)$  (subspace) it follows that

$\Omega$  determines  $\omega$  an  $m$ -tensor field on  $M$  by setting

$$\omega(p) \left( (p; \vec{u}_1), \dots, (p; \vec{u}_m) \right) := \Omega(p) \left( (p; \vec{u}_1), \dots, (p; \vec{u}_m) \right)$$

$\omega$  is "restriction of  $\Omega$  to  $M$ ".

Converse also true (but non trivial!):

every  $m$ -tensor field  $\omega$  on  $M$  extends to  $m$ -tensor field on  $U \subset \mathbb{R}^n$ ,  $U \supset M$ .

From now on: we will only work with  $m$ -forms defined on open

sets in  $\mathbb{R}^n$ . Now precisely: we will only work with  $m$ -forms  $\omega$  over  $M$

that are restrictions to  $M$  of  $m$ -forms  $\Omega$  on open sets of  $\mathbb{R}^n$  (that contain  $M$ ).

Recall from last week

Oct 17

$$T_x(\mathbb{R}^k) = \left\{ (x; \vec{v}) \mid x \in \mathbb{R}^k, \vec{v} \in \mathbb{R}^k \right\}$$

$$T_p(M) = \alpha_* \left( T_{\alpha^{-1}(p)}(\mathbb{R}^k) \right) = \left\{ (p; (D\alpha)_*(x) \cdot \vec{v} \mid \vec{v} \in \mathbb{R}^k \right\}$$

$x = \alpha^{-1}(p), \alpha = \text{any coord. chart at } p$

$T_p(M)$  is a vector space with basis:

$$\left\{ \frac{\partial \vec{x}^i}{\partial x^1} \Big|_{\alpha^{-1}(p)} \in \mathbb{R}^k, \dots, \frac{\partial \vec{x}^i}{\partial x^k} \Big|_{\alpha^{-1}(p)} \in \mathbb{R}^k \right\}$$

$1 \leq i \leq k \leq n$ ,  $M = k$ -mfld in  $\mathbb{R}^n$

$m$ -tensor field:  $\omega: M \rightarrow \bigcup_{q \in M} \mathcal{L}^m(T_q(M)) \cong M \times \mathbb{R}$

$$p \mapsto \omega(p) \in \mathcal{L}^m(T_p(M))$$



•  $m$ -differential form ( $m$ -form ( $m$ -covector))

$$\omega: M \rightarrow \bigcup_{q \in M} \mathcal{A}^m(\mathcal{J}_q(M)) \cong M \rightarrow \mathbb{R}^{\binom{M}{m}}$$

$$M \ni p \mapsto \omega(p) \in \mathcal{A}^m(\mathcal{J}_p(M))$$

WLOG: assume  $\omega = \text{restriction to } M \text{ of } \Omega = m\text{-form on } V \subseteq \mathbb{R}^n$

$$\text{with } V \supseteq M: \quad \Omega: V \subseteq \mathbb{R}^n \rightarrow \bigcup_{x \in V} \mathcal{A}^m(\mathcal{J}_x(\mathbb{R}^n))$$

Notation:  $\Lambda^m(V)$  or  $\mathcal{A}^m(V) = \{m\text{-forms on } V\}$

$$\text{is a v.s. over } \mathbb{R}: \quad \forall x \in V, \quad (a\omega(x) + b\eta(x)) \langle x, \vec{v} \rangle = a\omega(x) \langle x, \vec{v} \rangle + b\eta(x) \langle x, \vec{v} \rangle$$

Basis for  $\Lambda^m(V)$ :

•  $\{\vec{e}_{i_1}, \dots, \vec{e}_{i_m}\} = \text{canonical basis for } \mathbb{R}^n; x \in \mathbb{R}^n (x \in V)$

Canonical 1-forms ( $m=1$ ):  $\underbrace{\varphi_j(x) \langle x, \vec{e}_j \rangle}_{\in \mathcal{A}^1(\mathcal{J}_x(\mathbb{R}^n))} = \delta_{ij}$

Canonical  $m$ -forms: ( $m \geq 1$ )

( $I = \text{ascending } m\text{-tuple } m(1, \dots, n)$ )

$$\varphi_I(x) = \varphi_{i_1}(x) \wedge \varphi_{i_2}(x) \wedge \dots \wedge \varphi_{i_m}(x) \quad \text{if } I = (i_1, \dots, i_m)$$

any ascending  $m$ -tuple  $m(1, \dots, n)$ .

recall:  $\varphi_I(x) \langle x, \vec{v} \rangle = \det X_I$

$$\underbrace{\langle \underbrace{\vec{v}_{i_1}, \dots, \vec{v}_{i_m}}_x \rangle}_{\in \mathbb{R}^{n \times m}} = \underbrace{\det}_{m \times m \text{ minor of } x \text{ with rows } (i_1, \dots, i_m)}$$

General  $m$ -form  $\omega(x) = \sum_{[I]} b_I(x) \varphi_I(x)$

↑ all ascending  $m$ -tuples  $m(1, \dots, n)$

where  $b_I: V \rightarrow \mathbb{R}$  is a scalar function.

$$\omega \text{ class } C^r \iff b_I \text{ class } C^r, \quad r=0, 1, \dots, \infty$$

We call  $\{b_I\}_{[I]}$  the components of  $\omega$  relative to canonical basis for  $\mathbb{R}^n$ .

Def: 0-forms:  $\Lambda^0(V)$  : scalar functions:  $V \rightarrow \mathbb{R}$

$$f, g \in \Lambda^0(V), \quad (f \wedge g)(x) := f(x)g(x) \in \Lambda^0(V)$$

pointwise product

$$\left( \begin{matrix} f \wedge \omega \\ \in \Lambda^0 \quad \in \Lambda^m \end{matrix} \right) (x) := \frac{f(x)\omega(x)}{\sum_{[I]} f(x)b_I(x)\psi_I(x)}$$

consistent w/ all the axiomatic prop's of  $\wedge$

Exterior Derivative (aka differential operator)

We are going to define a linear operator:

$$d: \Lambda^m(V) \rightarrow \Lambda^{m+1}(V) \quad \forall 0 \leq m \leq n$$

-  $m=0$ ,  $f \in \Lambda^0(V)$ ,  $df \in \Lambda^1(V)$  & is defined as follows:

$$(df)(x)(x; \vec{v}) = (Df)(x) \cdot \vec{v} \in \mathbb{R}$$

$(1 \times n) \quad (n \times 1)$

Lemma:  $d: \Lambda^0(V) \rightarrow \Lambda^1(V)$  is linear:

$$d(af+bg)(x) = a df(x) + b dg(x) \quad \text{check!!}$$

Representation of canonical 1-forms via d:

Lemma: (H)  $\pi_i: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $\pi_i(x) = x_i$ ,  $x = (x_1, \dots, x_n)$

$\varphi_i =$  canonical 1-form, i.e.  $\varphi_i(x; \vec{v}) = v_i$

(C)  $\varphi_i = d\pi_i$

Pf: Check  $d\pi_i(x; \vec{v}) = v_i \quad \forall v_i, \forall x$

$= \varphi_i(x; \vec{v})$

$$[D\pi_i(x) = (0, \dots, 0, 1, 0, \dots, 0) \quad \cdot \quad D\pi_i(x)(x; \vec{v}) = (0, \dots, 0, 1, 0, \dots, 0) \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix} = v_i]$$

It follows that (since:  $\gamma_I = \varphi_{i_1} \wedge \dots \wedge \varphi_{i_m}$ )

$$\gamma_I = d\pi_{i_1} \wedge \dots \wedge d\pi_{i_m}$$

Notation:  $x_i = \pi_i$  &  $\varphi_i = dx_i$  &  $\gamma_I = dx_{i_1} \wedge \dots \wedge dx_{i_m}$   $\forall$  canonical  $m$ -forms

So:  $\forall w \in \wedge^m(V)$ :  $w(x) = \sum_{[I]} b_I(x) \underbrace{dx_{i_1} \wedge \dots \wedge dx_{i_m}}_{\substack{\text{notation: } = dx_I = dx_{i_1} \wedge \dots \wedge dx_{i_m} \\ \uparrow}}$

note:  $dx_I$  is not a differential

In particular:  $f \in \wedge^0(V)$ ,  $df = (D_1 f) dx_1 + \dots + (D_n f) dx_n$ .

$d: \wedge^m(V) \rightarrow \wedge^{m+1}(V) \quad \forall m \geq 0$

Thm: ( $\exists!$  of exterior derivative op.)

(A)  $V \subseteq \mathbb{R}^n$  open

(C)  $\forall 0 \leq m \leq n \quad \exists!$  linear transf.  $d: \wedge^m(V) \rightarrow \wedge^{m+1}(V)$  s.t.

(1) If  $f \in \wedge^0(V)$ ,  $(df)(x)(x, \vec{v}) = (Df)(x) \cdot \vec{v} \quad \forall x \in V, \forall \vec{v} \in \mathbb{R}^n$ .

(2) If  $\omega \in \wedge^m(V)$ ,  $\eta \in \wedge^l(V)$  then

$$d(\omega \wedge \eta) = (d\omega) \wedge \eta + (-1)^m \omega \wedge (d\eta).$$

("Leibniz rule for  $\wedge$ ")

(3)  $\forall w \in \wedge^m(V)$ ,  $d(dw) = 0$  ("d<sup>2</sup>=0")

Proof: "final exam assignment".

Fact:  $w(x) = \sum_{[I]} \underbrace{b_I(x)}_{\in \wedge^m(V)} dx_I$

$$dw(x) = \sum_{[I]} (db_I)(x) \wedge dx_I = \sum_{[I]} \sum_{j=1}^n (D_j b_I) \underbrace{dx_j \wedge dx_I}_{\substack{J = (j, I) \\ (m+1)\text{-tuple}}}$$

Def: Let  $0 \leq m \leq n, \omega \in \Lambda^m(V)$

- $\omega$  is closed if  $d\omega = 0$
- $\omega$  is exact if  $\exists \eta \in \Lambda^{m-1}(V)$  s.t.  $\omega = d\eta$

(note:  $\omega$  exact  $\Rightarrow d\omega = 0$  b/c  $d^2 = 0$ )

so: exact  $\Rightarrow$  closed

but  $\Leftarrow$  in general, unless  $V$  is "star-shaped"

Connection with multivariable calculus:

~~Def:~~  $V \subseteq \mathbb{R}^3$  open ( $n=3$ )

Def:  $\vec{\nabla}: \{\text{functions: } V \rightarrow \mathbb{R}\} \rightarrow \{\text{vector fields: } V \rightarrow \mathbb{R}^3\}$

$$f \mapsto \vec{\nabla} f(x) = (x; (D_1 f)(x)\vec{e}_1 + \dots + (D_n f)(x)\vec{e}_n)$$

div:  $\{\text{vector fields: } V \rightarrow \mathbb{R}^3\} \rightarrow \{\text{functions: } V \rightarrow \mathbb{R}\}$

$$G \mapsto \text{div } \vec{a} = (D_1 g_1)(x) + (D_2 g_2)(x) + (D_3 g_3)(x)$$

$(g_1, g_2, g_3)$

$\vec{\text{Curl}}: \{\text{vector fields: } V \rightarrow \mathbb{R}^3\} \rightarrow$

$$\vec{F} = (f_1, f_2, f_3) \mapsto \vec{\text{Curl}} \vec{F}(x) = \begin{pmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ D_1 & D_2 & D_3 \\ f_1 & f_2 & f_3 \end{pmatrix}$$

Thm: (H)  $V \subseteq \mathbb{R}^3$ , open set.

(C)  $\exists$  v.s. isomorphism  $\alpha_j; \beta_j:$

$$\{\text{scalar fields: } V \rightarrow \mathbb{R}\} \xrightarrow{\alpha_0} \Lambda^0(V)$$

$$\downarrow \vec{\nabla} \qquad \qquad \qquad \downarrow d$$

$$\{\text{vector fields: } V \rightarrow \mathbb{R}^3\} \xrightarrow{\alpha_1} \Lambda^1(V)$$

$$\downarrow \vec{\text{Curl}} \qquad \qquad \qquad \downarrow d$$

$$\{\text{vector fields: } V \rightarrow \mathbb{R}^3\} \xrightarrow{\beta_2} \Lambda^2(V)$$

$$\downarrow \text{div} \qquad \qquad \qquad \downarrow d$$

$$\{\text{scalar fields: } V \rightarrow \mathbb{R}\} \xrightarrow{\beta_3} \Lambda^3(V)$$

s.t. above diagrams commute, i.e.

$$d \circ \alpha_n = \alpha_{n+1} \circ \vec{\nabla}; \quad d \circ \beta_n = \beta_{n+1} \circ \vec{\text{Curl}}; \quad d \circ \beta_3 = \beta_3 \circ \text{div}$$

Pf: part of "final exam assignment" . 0

## Action of a differential map

Recall, given:

•  $U \subset \mathbb{R}^k$  open set;  $\alpha: U \subset \mathbb{R}^k \rightarrow \mathbb{R}^n$ , class  $C^r$

$$d_x: T_x(\mathbb{R}^k) \rightarrow T_{\alpha(x)}(\mathbb{R}^n) \quad \forall x \in U$$

$$(x; \vec{v}) \mapsto d_x(x; \vec{v}) = (d\alpha)_x \cdot \vec{v} \quad \vec{v} \in \mathbb{R}^k$$

•  $T: V \rightarrow W$ , lin. transf. of v.s. ( $V$  &  $W$ )

$$T^*: \mathcal{A}^L(W) \rightarrow \mathcal{A}^L(V)$$

$$\uparrow \quad \begin{matrix} \psi \\ w \end{matrix} \quad (T^*w)(\vec{v}_1, \dots, \vec{v}_L) = w(T\vec{v}_1, \dots, T\vec{v}_L)$$

dual transf. of  $T$

Def: Given: •  $U \subset \mathbb{R}^k$  open

•  $\alpha: U \rightarrow \mathbb{R}^n$ , class  $C^r$

•  $V \subset \mathbb{R}^n$  open s.t.  $\alpha(U) \subset V$ .

$$0 \leq L \leq \min\{k, n\}$$

Pullback by  $\alpha$ :  $\alpha^*: \mathcal{A}^L(V) \rightarrow \mathcal{A}^L(U)$

•  $L=0$ ,  $f \in \mathcal{A}^0(V)$ ,  $(\alpha^*f)(x) = (f \circ \alpha)(x)$ ,  $x \in U$

•  $L \geq 1$ ,  $w \in \mathcal{A}^L(V)$ ,  $(\alpha^*w)(x) = w(x; \vec{v}_1, \dots, \vec{v}_L)$

$$:= w(\alpha(x)) (d_x(x; \vec{v}_1), \dots, d_x(x; \vec{v}_L)).$$

In practice:

Thm: (1)  $U \subset \mathbb{R}^k$  open;  $k \leq n$

$\alpha: U \rightarrow \mathbb{R}^n$ , class  $C^r$

$x \mapsto \alpha(x) = y$ , ie.  $\alpha(x) = (y_1, \dots, y_n)$

$dx_i =$  canonical 1-form in  $\mathbb{R}^k$

$dy_i =$  " " " " in  $\mathbb{R}^n$

Recall from last time:

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$U \subset \mathbb{R}^k$  open;  $m \in \{0, 1, \dots, k\}$ .

•  $\exists!$   $d: \Lambda^m(U) \rightarrow \Lambda^{m+1}(U)$  s.t.

•  $\omega \in \Lambda^m, \eta \in \Lambda^l$ :

$$d(\omega \wedge \eta) = (d\omega) \wedge \eta + (-1)^m \omega \wedge d\eta$$

•  $d^2 \equiv 0$  ( $d(d\omega) = 0 \forall \omega$ )

in practice:  $\omega(x) := \sum_{[I]_m} b_I(x) dx_I$

$$\Rightarrow d\omega(x) = \sum_{[I]_m} (db_I(x)) \wedge dx_I = \sum_{\substack{[I]_m \\ j=1, \dots, n}} \frac{\partial b_I(x)}{\partial x_j} dx_j \wedge dx_I$$

Note:  $\omega$  class  $C^k$  (i.e.  $b_I$  class  $C^k$  all  $I$ )  
 $d\omega$  class  $C^{k-1}$

For sake of simplicity, we assume: class  $C^\infty$

•  $\omega$  closed :=  $d\omega = 0$ .

•  $\omega$  exact := ~~then~~  $\omega = d\eta \exists \eta \in \Lambda^{m-1}$

Note: exact  $\implies$  closed (b/c  $d^2 = 0$ )

in general  $\Leftarrow$

Poincaré's lemma sa:  $U$  convex or more generally,  $\star$ -shaped  
then " $\Leftarrow$ " true.

• given  $\alpha: \mathbb{R}^k \rightarrow \mathbb{R}^n$  class  $C^\infty$

$$U \rightarrow \mathbb{R}^n$$

$$x \rightarrow y = \alpha(x) = (\alpha_1(x), \dots, \alpha_n(x))$$

$$\alpha^*: \Lambda^m(\mathbb{R}^n) \rightarrow \Lambda^m(\mathbb{R}^k) \quad \forall m = 0, 1, \dots, \min\{k, n\}$$

$U$

$$\alpha^*(dy_{\Gamma})(x) = \sum_{\substack{[J]_m \\ \subset \{1, \dots, k\}}} \left( \det \frac{\partial \alpha_{\Gamma}}{\partial x_j} (x) \right) dx_J$$

$$D\alpha(x) = \begin{matrix} \frac{\partial \alpha_1}{\partial x_1} & \dots & \frac{\partial \alpha_n}{\partial x_1} \\ \vdots & & \vdots \\ \frac{\partial \alpha_1}{\partial x_k} & & \frac{\partial \alpha_n}{\partial x_k} \end{matrix} \quad \left. \vphantom{\begin{matrix} \frac{\partial \alpha_1}{\partial x_1} \\ \vdots \\ \frac{\partial \alpha_1}{\partial x_k} \end{matrix}} \right\} \text{pick "J" rows}$$

$\left\{ \vphantom{\begin{matrix} \frac{\partial \alpha_1}{\partial x_1} \\ \vdots \\ \frac{\partial \alpha_1}{\partial x_k} \end{matrix}} \right\} \Gamma$  columns

Notes  $m=1 \Rightarrow dy_{\Gamma} = dy_i, i=1, \dots, n$  &  $J=j, j=1, \dots, k$

$$\frac{\partial \alpha_{\Gamma}}{\partial x_j} = \frac{\partial \alpha_i}{\partial x_j}(x) \Rightarrow \alpha^*(dy_i) = \sum_{j=1}^k \frac{\partial \alpha_i}{\partial x_j}(x) dx_j = d\alpha_{ji}$$



by linearity:

$$\text{if } \omega(y) = \sum_{\substack{[I]_m \\ \subseteq \{1, \dots, n\}}} b_I(y) \underbrace{dy_I}_{A^0} = \sum_{[I]_m} b_I(y) \wedge dy_I$$

$$\Rightarrow \alpha^* \omega(x) = \sum_{[I]_m} \alpha^* b_I(y) \wedge \alpha^* dy_I$$

$$\boxed{\begin{aligned} \alpha^*(\mu \wedge \eta) &= \\ \alpha^* \mu \wedge \alpha^* \eta \end{aligned}}$$

$$\underbrace{\alpha^* b_I(y)}_{\parallel} = (b_I \circ \alpha)(x) \quad (m=0)$$

$$y = \alpha(x)$$

$$= \sum_{[I]_m} b_I(\alpha(x)) (\alpha^* dy_I)$$

$$\alpha^* \omega(x) = \sum_{\substack{[I]_m \\ \subseteq \{1, \dots, n\}}} \left( b_I(\alpha(x)) \det \frac{\partial \alpha_I(x)}{\partial x_J} \right) dx_J$$

$$\sum_{[J]_m} c_J(x) dx_J$$

$$= \sum_{[J]_m} \underbrace{\left( \sum_{[I]_m} b_I(\alpha(x)) \det \frac{\partial \alpha_I(x)}{\partial x_J} \right)}_{c_J(x)} dx_J$$

# Thm (properties of pull-back)

-5-

⊕  $U \subset \mathbb{R}^k$  open

$\alpha: U \rightarrow \mathbb{R}^m$ , class  $C^\infty$

$V \subset \mathbb{R}^n$  open;  $\alpha(U) \subset V$

$\beta: V \rightarrow \mathbb{R}^h$ , class  $C^\infty$ .

$\omega; \eta$  the ~~two~~ 1-forms (same order)

⊙ (1)  $\beta^*(a\omega + b\eta) = a\beta^*\omega + b\beta^*\eta$

(2)  $\beta^*(\omega \wedge \theta) = \beta^*\omega \wedge \beta^*\theta \quad \forall \theta$

(3)  $(\beta \circ \alpha)^*\omega = \alpha^*(\beta^*\omega)$ .

Pf argument.

Thm ( $d$  commutes with pull-back) :

-6-

(H)  $U \subset \mathbb{R}^k$  open ;  $\alpha: U \xrightarrow{x \mapsto y = \alpha(x)} \mathbb{R}^n$  class  $C^\infty$   
 $V \subset \mathbb{R}^n$  open,  $\alpha(U) \subset V$   
 $w \in \Lambda^l(V)$

(C)  $d(\alpha^*w) = \alpha^*(dw)$  i.e.

$$\begin{array}{ccc} \Lambda^l(U) & \xrightarrow{d} & \Lambda^{l+1}(U) \\ \alpha^* \uparrow & \nearrow & \uparrow \alpha^* \\ \Lambda^l(V) & \xrightarrow{d} & \Lambda^{l+1}(V) \end{array}$$

~~the~~ pf: dual annihilation!

Importance of last thm ( $d\alpha^* = \alpha^*d$ )

-7-

•  $\omega \in \Lambda^m(\mathbb{R}^n)$  ~~closed~~ (closed)

$\omega$  closed  $\iff \alpha^*\omega$  closed

$$0 = d\omega \implies 0 = \alpha^*(d\omega) \implies d(\alpha^*\omega) = 0 = 1$$

$\alpha^*\omega$  closed.

$\Leftarrow$  true (same proof).

•  $\omega \in \Lambda^m(\mathbb{R}^n)$  exact i.e.  $\omega = dy$   $\exists y \in \Lambda^{m-1}(\mathbb{R}^n)$

$\implies \alpha^*\omega$  also exact:

then

$$\omega = dy \implies \alpha^*\omega = \alpha^*dy = d(\alpha^*y)$$

• if  $\alpha$  diffeomorphism:  $\mathbb{R}^n \rightarrow \mathbb{R}^n$  then:  
 $\omega$  exact  $\iff \alpha^*\omega$  exact.

pt:  $\implies \checkmark$

$\Leftarrow$  Suppose  $\alpha^*\omega = d\mu$  ( $\alpha^*\omega$  exact)

$$\implies (\alpha^{-1})^* \alpha^*\omega = (\alpha^{-1})^* d\mu$$

// (3) in thm on properties of pull-back

$$(\alpha \circ \alpha^{-1})^* \omega$$

$$(\text{Id})^* \omega$$

$$\omega$$

$$= (\alpha^{-1})^* d\mu \stackrel{\text{thm}}{=} d((\alpha^{-1})^* \mu)$$

Exa Aside:  $U \subset \mathbb{C}^n = \mathbb{R}^{2n}$  -8-

$$\bar{\partial} : \Lambda^m \rightarrow \Lambda^{m+1}$$

$$(\bar{\partial})^2 = 0$$

$$\left( \begin{array}{l} dz_1 \wedge dz_2 \wedge \dots \wedge dz_m \\ d\bar{z}_1 \wedge d\bar{z}_2 \wedge \dots \wedge d\bar{z}_m \end{array} \right)$$

$$d\bar{z}_1 \wedge d\bar{z}_2 \wedge \dots \wedge d\bar{z}_k$$

$$\bar{\partial} (f dz_1 \wedge \dots \wedge dz_m)$$

$$= \bar{\partial} f \wedge (dz_1 \wedge \dots \wedge dz_m)$$

$$= \sum_{j=1}^m \frac{\partial f}{\partial \bar{z}_j} dz_1 \wedge \dots \wedge dz_j \wedge \dots \wedge dz_m$$

$\bar{\partial}$

$$\alpha^* \bar{\partial} \neq \bar{\partial} \alpha^*$$

ex/  $n=3; k=2$   $\alpha: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  -9-  
 $U = \mathbb{R}^2;$   $(u, v) \rightarrow (x, y, z) := \begin{pmatrix} uv \\ u^2 \\ 3u+v \end{pmatrix}$   
 $\alpha^*: \Lambda^m(\mathbb{R}^3) \rightarrow \Lambda^m(\mathbb{R}^2), m=0, 1, 2.$

$m=1, w = xy dx + 2z dy - y dz \in \Lambda^1(\mathbb{R}^3)$   
 Compute directly:  $dw$ ;  $\alpha^*w$ ;  $\alpha^*(dw)$ ;  $d(\alpha^*w)$ .

$$dw = \underbrace{d(xy)} \wedge dx + \underbrace{2dz \wedge dy}_{-2dy \wedge dz} - dy \wedge dz$$

$$0 + x dy \wedge dx$$

$$dw = - \left\{ \underbrace{x dx \wedge dy}_{b_1} + \underbrace{3 dy \wedge dz}_{b_2} \right\}$$

$$\alpha^*w =$$

we:  
 $\alpha^*dy_i = d\alpha_i$

$$w = \underbrace{xy dx}_{b_1} + \underbrace{2z dy}_{b_2} - \underbrace{y dz}_{b_3}$$

$$\alpha^*w(u, v) = \sum_j (b_j \circ \alpha) d\alpha_j = \underbrace{(uv)u^2}_{b_1(\alpha)} d(\underbrace{uv}_{\alpha_1}) +$$

$$+ \underbrace{2(3u+v)}_{b_2 \circ \alpha} d(\underbrace{u^2}_{\alpha_2}) - \underbrace{u^2}_{b_3 \circ \alpha} d(3u+v) =$$

-10-

$$\alpha^* \omega(u,v) = u^3 (v \underline{du} + u \underline{dv}) + 4u(3u+v) \underline{du} +$$

$$-u^2(3 \underline{du} + \underline{dv}) =$$

$$= (vu^3 + 12u^2 - 3u^2) \underline{du} + (u^4v - u^2) \underline{dv}$$

4uv

$$\boxed{\alpha^* \omega(u,v) = (vu^3 + 9u^2 + 4uv) du + (u^4v - u^2) dv}$$

$$d(\alpha^* \omega) = d(vu^3 + 9u^2 + 4uv) \wedge du + d(u^4v - u^2) \wedge dv$$

$$= (2vu^3 + 4u) dv \wedge du + (4u^3v - 2u) du \wedge dv$$

$$= (4u^3v - 2u - 4u - 2vu^3) du \wedge dv$$

$$\boxed{d(\alpha^* \omega) = (2u^3v - 6u) du \wedge dv}$$

•  $\alpha^*(d\omega)$ . recall:  $d\omega = -\{x dx \wedge dy - 3 dy \wedge dz\}$

$$\alpha(u,v) = \left( \underset{\alpha_1}{uv}, \underset{\alpha_2}{u^2}, \underset{\alpha_3}{3u+v} \right)$$

$$D\alpha(u, v) = \begin{pmatrix} \frac{\partial \alpha_1}{\partial u} & \text{etc.} \\ \frac{\partial \alpha_1}{\partial v} \end{pmatrix} = \begin{pmatrix} v & 2u & 3 \\ u & 0 & 1 \end{pmatrix}^{-1} \quad \text{---(1)} \quad \begin{matrix} \swarrow & \searrow \\ (1,2) & (1,3) \end{matrix}$$

$$\cdot d^*(dx \wedge dy) = -2u^2 du \wedge dv$$

I=12

$$\cdot d^*(dy \wedge dz) = 2u du \wedge dv$$

I=23

$$d^*d\omega = (-uv)(-2u^2 du \wedge dv) - 3(2u du \wedge dv)$$

$$d^*d\omega = (2u^3v - 6u) du \wedge dv \quad \text{☺}$$



# Stokes' Thm

-12-

Recall from last time:

- $m$ -forms in  $\mathbb{R}^n$  are a generalization to  $\mathbb{R}^n$  of scalar fields } in  $\mathbb{R}^3$   
vector fields }
- exterior derivative  $d$  is a generalization to  $\mathbb{R}^n$  of  $\vec{D}$ ; curl; div } in  $\mathbb{R}^3$

Next:

- integral of an  $m$ -form over a (cpt)  $k$ -mfd in  $\mathbb{R}^n$ :

this will be a generalization of to  $\mathbb{R}^n$  of

- line integrals } in  $\mathbb{R}^3$ .
- surface integrals }

Standing assumptions:

- $k$ -mfd in  $\mathbb{R}^n$ ,  $M$ , is cpt &  $C^\infty$

- $m$ -form  $\omega$  is defined on  $V$  open set in  $\mathbb{R}^n$  with  $M \subset V$

- $m$ -form  $\omega$  class  $C^\infty$

$$\omega(x) = \sum_{I \in \binom{\{1, \dots, n\}}{m}} b_I(x) dx_I$$

$b_I$  class  $C^\infty$   
 $b_I$  defined on open set  $V \supset M$ .

- integral of  $\eta \in \Lambda^k(U)$ ,  $U \subset \mathbb{R}^k$  open, over  $U$ : <sup>-13-</sup>

Then  $[I]_k = (1, 2, \dots, k)$  a single ascending  $k$ -tuple in  $\mathbb{R}^k$

$$\eta(x) = \underbrace{a(x)}_{a: U \rightarrow \mathbb{R}} dx_1 \wedge \dots \wedge dx_k$$

Def:  $\int_U \eta = \int_U \underbrace{a(x)}_{\text{Euclidean vol. meas. in } \mathbb{R}^k} dV(x)$

provided the latter exists.

- Integral over a parametrized  $k$ -submanifold  $M$ , in  $\mathbb{R}^n$  of  $\omega \in \Lambda^k(V)$ , with  $V \subset \mathbb{R}^n$  open,  $M \subset V$

(a)  $L=1, \alpha^*(dy_i) = dx_i$

(b)  $L=k \quad \forall I=(i_1, \dots, i_k) = \text{ascending } k\text{-tuple in } \{1, \dots, n\}$

$\alpha^*(dy_I) = \left( \det \frac{\partial x_I}{\partial x} \right) dx_{i_1} \wedge \dots \wedge dx_{i_k}$

$(D\alpha(x)) \in \mathbb{R}^{n \times k}, D\alpha_I \in \mathbb{R}^{k \times k}$

(c) General  $L: I=(i_1, \dots, i_L) \text{ ascending } L\text{-tuple in } \{1, \dots, n\}$

$\alpha^*(dy_I) = \sum_{[J]} \left( \det \frac{\partial x_I}{\partial x_J} \right) dx_J$

$[J]=(j_1, \dots, j_L) = \text{ascending } L\text{-tuple in } \{1, \dots, k\}$

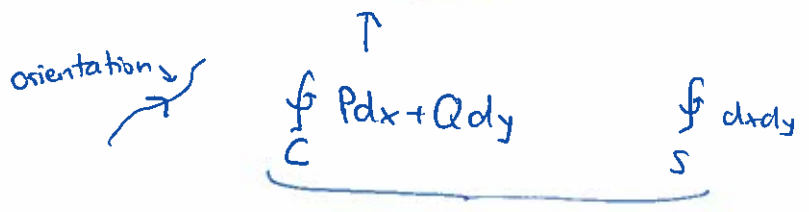
Oct 24

Oct 19: see printed sheets

Recall from last time: Stoke's thm

Next: • integral of  $k$ -form  $\omega$  over (cpct)  $k$ -mfd in  $\mathbb{R}^n$ :

• generalization of line integrals in  $\mathbb{R}^3$ ; surface integrals in  $\mathbb{R}^3$



need "orientation" for  $C$  or  $S$ .

Orientable mfds

Def: Let  $M$  be a  $k$ -mfd in  $\mathbb{R}^n$ , let  $\alpha_j: U_j \rightarrow V_j \subset \mathbb{R}^n$ ,  $j=1,2$  be two coord. charts for  $M$  s.t.  $V_1 \cap V_2 \neq \emptyset$  ("overlapping charts") Assume  $V_1 \subset \alpha_2(U_2)$

• We say that the charts  $\alpha_1$  &  $\alpha_2$  overlap positively if transition

funct.  $\alpha_2^{-1} \circ \alpha_1: U_{1'} \rightarrow U_{2'} \subset \mathbb{R}^n$  has:  $\det (D(\alpha_2^{-1} \circ \alpha_1)(x)) > 0 \quad \forall x \in U_1$

• We say that  $M$  is orientable if  $M$  has an atlas  $\mathcal{A} = \{(U_j, \alpha_j)\}_j$  s.t. any two overlapping coord charts in  $\mathcal{A}$  overlap positively.

Otherwise,  $M$  is not orientable

- If  $M$  is orientable, then an orientation for  $M$  is a collection of charts that cover  $M$  & overlap positively.

Orientable  $k$ -mfds in  $\mathbb{R}^n$ : three special cases:

$$k=1; k=n-1; k=n \quad (\text{class } C^\infty)$$

- $k=1$ :  $M$  orientable 1-mfd in  $\mathbb{R}^n \Rightarrow M$  admits a unit tangent field of class  $C^\infty$ :

$$T: M \rightarrow T(M) \quad \text{class } C^\infty$$

given  $p \in M$  let  $(U_1, \alpha)$  be any coord. chart about  $p$  in the orientation of  $M$  s.t.  $p = \alpha(t_1) \exists t_1 \in U_1$ , def.  $T(p) := (p, \frac{D\alpha(t_1)}{\|D\alpha(t_1)\|})$

To show: this def indep. of choice of  $\alpha$ .

Let  $(U_2, \beta)$  be another coord. chart about  $p$  in orientation

for  $M$  s.t.  $p = \beta(t_2) \exists t_2 \in U_2$  then

$$g: \beta^{-1} \circ \alpha: U_1 \rightarrow U_2 \quad \& \quad Dg(t) \text{ is } 1 \times 1 \text{ matrix}$$

with  $\det Dg(t) > 0$  (b/c  $\alpha$  and  $\beta$  overlap positively  $\forall t \in U_1$ )

$$D\alpha(t_1) = D(\beta \circ g)(t_1) = \underbrace{D\beta(t_2)}_{M_2} \underbrace{Dg(t_1)}_{M_1 > 0}$$

$$g(t_1) = \beta^{-1}(p) = t_2$$

$$\Rightarrow D\alpha(t_1) = M_1 D\beta(t_2)$$

$$\Rightarrow \frac{D\alpha(t_1)}{\|D\alpha(t_1)\|} \stackrel{(\alpha)}{=} \frac{M_1 D\beta(t_2)}{\|M_1 D\beta(t_2)\|} = \frac{M_1 D\beta(t_2)}{|M_1| \|D\beta(t_2)\|} \stackrel{M_1 > 0}{=} \frac{D\beta(t_2)}{\|D\beta(t_2)\|}$$

- $k=n-1$ :  $\forall p \in M$ ,  $T_p(M)$  has  $\dim = n-1$  & a basis  $T_p(M)$  is

$$\left\{ \left( p, \frac{\partial \alpha}{\partial x_1}(x_0) \right); \dots; \left( p, \frac{\partial \alpha}{\partial x_{n-1}}(x_0) \right) \right\} \text{ if } (U, \alpha) \text{ is a coord. chart}$$

about  $p$  orientation of  $M$  with  $p = \alpha(x_0)$ .

Complete to a basis for  $T_p(\mathbb{R}^n)$ :

$$\left\{ \underbrace{(p; \tilde{n}(p))}_{\uparrow \text{unit vector s.t.}}; (p; \frac{\partial \alpha}{\partial x_1}(x_0)); \dots; (p; \frac{\partial \alpha}{\partial x_n}(x_0)) \right\}$$

$$\det \underbrace{\left[ n, D\alpha(x_0) \right]}_{n \times n \text{ matrix}} > 0$$

This defines a unit vector field & one may show that:

$M$  orientable & class  $C^\infty \Rightarrow p \rightarrow (p; \tilde{n}(p))$  is well-def'd

(indep. of choice of  $\alpha$  chart) & class  $C^\infty$ .

"The unit normal field to  $M$  corresponding to orientation of  $M$ "

$n=3$   
 $k=2$  Möbius band



•  $k=n$ :  $M$   $n$ -mfd in  $\mathbb{R}^n$ . is always orientable:

$$\forall \text{ atlas } \mathcal{A} = \{ (U_j; \alpha_j) \} \quad \alpha: U \rightarrow V \begin{matrix} \subset \mathbb{R}^n \\ \subset \mathbb{R}^n \end{matrix} \quad \text{has } \det \underbrace{D\alpha(x)}_{n \times n} \neq 0 \quad \forall x \in U$$

Def. Natural orientation of  $M = \{ (U, \alpha) \mid \det \alpha(x) > 0 \quad \forall x \in U \}$

Let  $(U_j; \alpha_j)$  be an atlas for  $M$ .

Assume w.l.o.g. that each  $U_j$  is connected (either  $U_j = B_{\epsilon_j}(p)$

$$\exists p \in M, \text{ or } U_j = B_{\epsilon_j}(p) \cap \mathbb{H}^n$$

$$\text{then: either } \left. \begin{array}{l} \det D\alpha_j(x) > 0 \\ \det D\alpha_j(x) < 0 \end{array} \right\} \forall x \in U_j$$

if  $\det D\alpha_j(x) > 0 \quad \forall x \in U_j$ , save  $(U_j; \alpha_j)$

if  $\det D\alpha_j(x) < 0 \quad \forall x \in U_j$ , replace  $(U_j; \alpha_j)$  with  $(\tilde{U}_j; \tilde{\alpha}_j)$ ,  $\tilde{\alpha}_j := \alpha_j \circ r$  or

where  $r: \mathbb{R}^n \rightarrow \mathbb{R}^n$ ;  $(x_1, \dots, x_n) \rightarrow r(x_1, \dots, x_n) = (-x_1, x_2, \dots, x_n)$

then:  $\det(D\tilde{\alpha}_j|_x) > 0$ ;  $\tilde{U}_j = \{(-x_1, x_2, \dots, x_n) \mid (x_1, \dots, x_n) \in U_j\}$

So:  $\tilde{\mathcal{A}} = \{\det D\alpha_j > 0\} \cup \{\alpha_j \circ r, \det D\alpha_j > 0\}$  is an atlas

for  $M$  made of positively overlapping charts:  $M$  orientable.

Reversing orientation of an orientable  $k$ -mfd in  $\mathbb{R}^n$

Suppose  $M$  is orientable  $k$ -mfd in  $\mathbb{R}^n$ .

Def:  $r: \mathbb{R}^k \rightarrow \mathbb{R}^k$

$$(x_1, \dots, x_k) \rightarrow (-x_1, x_2, \dots, x_k) = r(x_1, \dots, x_k)$$

Suppose  $(U, \alpha)$  is coord. patch belonging to orientation of  $M$ .

Def:  $(\tilde{U}, \tilde{\alpha})$ , with  $\tilde{\alpha}(\tilde{x}) = \alpha \circ r(\tilde{x})$ ,  $\tilde{x} \in \tilde{U}$ ,  $\tilde{U} = \{(-x_1, \dots, x_k) \mid (x_1, \dots, x_k) \in U\}$ .

Then:  $(U, \alpha)$  &  $(\tilde{U}, \tilde{\alpha})$  overlap negatively

But:  $(\tilde{U}_1, \tilde{\alpha}_1)$  &  $(\tilde{U}_2, \tilde{\alpha}_2)$  overlap positively (if  $(U_1, \alpha_1)$  &  $(U_2, \alpha_2)$  do)

So,  $\{(U, \alpha) \mid (U, \alpha) \in \text{orientation}\}$  is another orientation of  $M$ .

So: every orientable mfd has at least two orientations

(if  $M$  connected, then  $M$  has exactly two orientations)

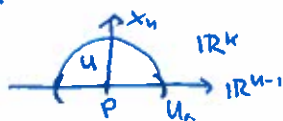
Induced orientation on boundary of orientable mfd (with boundary!)

Thm: (F)  $M$  orientable  $k$ -mfd in  $\mathbb{R}^n$  with  $bM \neq \emptyset$  ( $k \geq 1$ )

(C)  $bM$  is orientable.

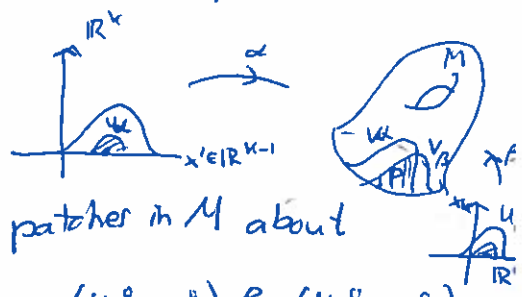
Pf: Let  $p \in bM$ . Let  $(U, \alpha)$  be a coord. chart for  $p$  in  $M$ .

Then  $(p \in bM)$   $U$  open in  $\mathbb{H}^k$ . set:  $U_\partial^0 := U \cap \mathbb{R}^{k-1}$ .



def  $\alpha^{\circ}(\underbrace{x_1, \dots, x_{k-1}}_{\in U_0}) = \alpha(x_1, \dots, x_{k-1}, 0)$  is a coord. patch

for  $p$  in  $bM$ . ("restriction of  $\alpha$ ")



Fact: if  $(U_i, \alpha_i)$  &  $(U_j, \alpha_j)$  are two coord. patches in  $M$  about  $p \in bM$  that overlap positively then so do:  $(U_i^{\circ}, \alpha_i^{\circ})$  &  $(U_j^{\circ}, \alpha_j^{\circ})$

So, if  $\{(U_i, \alpha_i, p) \mid p \in M\}$  is an orientation for  $M$ , then

$\{(U_i^{\circ}, \alpha_i^{\circ}, p) \mid p \in bM\}$  is an orientation for  $bM$ . □

Recall from last time:

$M = k$ -mfd in  $\mathbb{R}^n$ .

$M$  orientable if  $M$  admits an atlas  $\{(U_{\alpha}, \alpha, V_{\alpha})\}_{\alpha}$  s.t. any two overlapping charts in atlas overlap positively, i.e.

if  $V_{\alpha} \cap V_{\beta} \neq \emptyset$  then  $g := \beta^{-1} \circ \alpha : \alpha^{-1}(V_{\alpha} \cap V_{\beta}) \rightarrow \beta^{-1}(V_{\alpha} \cap V_{\beta})$  has  $\det Dg(x) > 0 \quad \forall x \in \alpha^{-1}(V_{\alpha} \cap V_{\beta})$ .

We call such an atlas "an orientation for  $M$ ".

M orientable  $\Rightarrow M$  has (at least) two orientations:  $\rightarrow (U_{\alpha}, \alpha, V_{\alpha})$  &  $(U_{\alpha}, \tilde{\alpha}, \tilde{V}_{\alpha})$

Let  $f: U \rightarrow V$

- Any  $n$ -mfd  $M$  in  $\mathbb{R}^n$  ( $k=n$ ) is orientable with a "natural" orientation induced by  $\mathbb{R}^n$ :  $(U_{\alpha}, \alpha)$  s.t.  $\det D\alpha(x) > 0 \quad \forall x \in U_{\alpha}$ .
- Orientable  $1$ -mfds &  $(n-1)$ -mfds ( $k=1, n-1$ ) have "intrinsic" orientations (via tangent vector fields ( $k=1$ ) or normal vector field ( $k=n-1$ )).

Induced orientation on bM

- Thm: (A)  $M$  is orientable  $k$ -mfd in  $\mathbb{R}^n$ ,  $bM \neq \emptyset$   
 (C)  $bM$  is orientable  $(k-1)$ -mfd in  $\mathbb{R}^n$

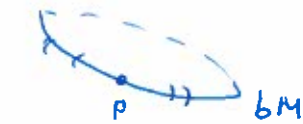
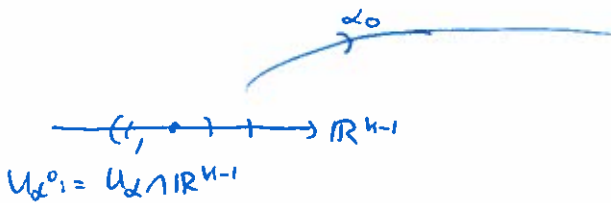
Pf.  $p \in bM$ ,  $\alpha, \beta$  two coord charts for  $M$  about  $p$  that overlap positively.

$g: \beta^{-1} \circ \alpha: \alpha^{-1}(V_\alpha \cap V_\beta) \rightarrow \beta^{-1}(V_\alpha \cap V_\beta)$  has  $\det Dg(x) > 0$   
 $\forall x \in \alpha^{-1}(V_\alpha \cap V_\beta) \cap \beta^{-1}(V_\alpha \cap V_\beta)$

Let  $\alpha_0$  &  $\beta_0$  be the coord charts for  $bM$  about  $p$  obtained by

restricting  $\alpha$  &  $\beta$  to  $bM$ :

$\alpha_0(x') := \alpha(x', 0) : \beta_0(x') = \beta(x', 0)$   
 $(x', 0) \in U_\alpha \quad (x', 0) \in U_\beta$



$\uparrow \beta_0$

$W_\alpha^0 := \alpha^{-1}(V_\alpha \cap V_\beta) \cap \mathbb{R}^{n-1}$



$W_\beta^0 := \beta^{-1}(V_\alpha \cap V_\beta) \cap \mathbb{R}^{n-1}$

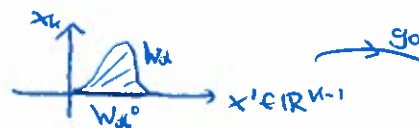
def.  $g^0 := \beta_0^{-1} \circ \alpha_0: W_\alpha^0 \rightarrow W_\beta^0$

Claim:  $\det Dg^0(x') > 0 \forall x' \in W_\alpha^0$

This will show that  $\alpha_0$  &  $\beta_0$  overlap positively.

$Dg^T(x) = \begin{pmatrix} \frac{\partial g_1}{\partial x_1} & \dots & \frac{\partial g_{k-1}}{\partial x_1} & \frac{\partial g_k}{\partial x_1} \\ \vdots & & \vdots & \vdots \\ \frac{\partial g_1}{\partial x_{k-1}} & \dots & \frac{\partial g_{k-1}}{\partial x_{k-1}} & \frac{\partial g_k}{\partial x_{k-1}} \\ \frac{\partial g_1}{\partial x_k} & \dots & \frac{\partial g_{k-1}}{\partial x_k} & \frac{\partial g_k}{\partial x_k} \end{pmatrix}, x \in W_\alpha$

Focus on  $W_\alpha^0$ :





We know :  $g: (x':0) \mapsto (y':0) \quad \forall x' \in W_x^0 \quad (*)$

Claim:  $\frac{\partial g_k}{\partial x_j}(x':0) = 0 \quad \forall j=1, \dots, k-1, \quad \forall x' \in W_x^0$

pf: i.e.  $j=1$ :  $\frac{\partial g_k}{\partial x_1}(x':0) = \lim_{\substack{h \rightarrow 0 \\ h > 0}} \frac{g_k(x_1+h, x_2, \dots, x_n, 0) - g_k(x':0)}{h}$   
 $\stackrel{(*)}{=} \lim_{h \rightarrow 0} \frac{0-0}{h} = 0$ . Same all  $j=1, \dots, k-1$ .

Claim:  $\frac{\partial g_k}{\partial x_k}(x':0) \geq 0 \quad \forall x' \in W_x^0$

$$\frac{\partial g_k}{\partial x_k}(x':0) = \lim_{h \downarrow 0} \frac{g_k(x':h) - g_k(x':0)}{h} \stackrel{(*)}{=} \lim_{h > 0} \frac{g_k(x':h) - 0}{h} \geq 0$$

0 b/c  $g(x':h) \in \mathbb{H}^n$

$$Dg^T(x':0) = \begin{pmatrix} \frac{\partial g_1}{\partial x_1}(x':0) & \dots & \frac{\partial g_{k-1}}{\partial x_k}(x':0) & 0 \\ \vdots & & \vdots & \vdots \\ \frac{\partial g_1}{\partial x_k}(x':0) & \dots & \frac{\partial g_{k-1}}{\partial x_{k-1}}(x':0) & \frac{\partial g_k}{\partial x_k}(x':0) \end{pmatrix}$$

$(Dg)_\Gamma \rightarrow$

$$\det Dg(x':0) = \frac{\partial g_k}{\partial x_k}(x':0) \cdot \det (Dg)_\Gamma(x':0)$$

Fact:  $(Dg)_\Gamma(x':0) = (Dg^0)(x')$  check!

Thus:  $\underbrace{\det Dg(x':0)}_{>0} = \underbrace{\frac{\partial g_k}{\partial x_k}(x':0)}_{>0} \cdot \det (Dg^0)(x')$

$$\Rightarrow \det (Dg^0)(x') > 0 \quad \text{all } x' \in W_x^0$$

Q: Does that work for any  $(k-1)$ -submfld? Probably not.

### Integrations of $k$ -forms over $k$ -mflds in $\mathbb{R}^n$

Case k:  $k=n$  &  $M = \text{open subset, } U, \text{ of } \mathbb{R}^n, \quad \omega \in \mathcal{A}^n(U)$ .

•  $\omega(x) = a(x) dx_1 \wedge dx_2 \wedge \dots \wedge dx_n, \quad \exists a: U \rightarrow \mathbb{R}$

•  $\int_M \omega \stackrel{\text{def}}{=} \int_U a(x) dx_1 dx_2 \dots dx_n$ , provided this exists as a Riemann integral in  $\mathbb{R}^n$

Case 2:  $k \leq n$  &  $M =$  "parametrized  $n$ -mfd in  $\mathbb{R}^n$ " i.e.

$M$  covered by a single chart  $\alpha: U \subset \mathbb{R}^n \rightarrow \alpha(U) = V \supset M$ .  
 $U$  open, connected

Let  $\omega \in \Lambda^k(V)$  Def:  $\int_M \omega = \int_U \underbrace{\alpha^* \omega}_{\in \Lambda^k(U)} \rightarrow$  Case 1 provided latter exists

Recall that:  $\omega \in \Lambda^k(V) \rightarrow \alpha^* \omega \in \Lambda^k(U)$   
 $\alpha: U \subset \mathbb{R}^n \rightarrow V \subset \mathbb{R}^n$   
 $\alpha^*: \Lambda^k(V) \rightarrow \Lambda^k(U)$

$$\alpha^* \omega(x) = \sum_{\substack{[I] \\ \in \binom{[1, n]}{k}}} (b_I | \alpha |)(x) \underbrace{\alpha^* dy_I}_{= \det \left( \frac{\partial x_I}{\partial x} \right)(x) dx_{1,1} \dots dx_{k,n}} \stackrel{k=n}{=} |b \circ \alpha|(x) |\det D\alpha(x)| dx_{1,1} \dots dx_n$$

$$\alpha^* \omega(x) = b(\alpha(x)) \det D\alpha(x) dx_{1,1} \dots dx_n$$

Lemma:  
Thm: [(independence of choice of parametrization)]

(H)  $M$  parametrized  $k$ -mfd in  $\mathbb{R}^n$

$$M = \alpha(U) = \beta(\tilde{U}), \quad U, \tilde{U} \subset \mathbb{R}^n \text{ open}$$

$$\omega \in \Lambda^k(M)$$

$$g := \beta^{-1} \circ \alpha$$

$\alpha: U \rightarrow \alpha(U) = M, U$  open in  $\mathbb{R}^k$   
 $\beta: \tilde{U} \rightarrow \beta(\tilde{U}) = M, \tilde{U}$  " " " " " "

are two param. of  $M$ , i.e.

$\alpha: | \cdot |, D\alpha(x)$  has rank  $k$   $\forall x \in U$   
 $\beta: | \cdot |, D\beta(y)$  " " " "  $\forall y \in \tilde{U}$

(C)  $\int_U \alpha^* \omega = \varepsilon \int_{\tilde{U}} \beta^* \omega$ , where  $\varepsilon = \text{sign } \det Dg(x) \forall x \in U$

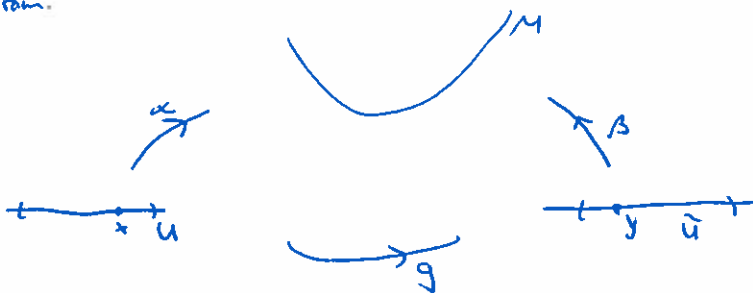
$k=n$ : Check! (CVF for integrals in  $\mathbb{R}^n$ )

$\Rightarrow$  (Thm indep. of choice of param.)

$$\varepsilon = 1$$

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Pf.



(H)  $\Rightarrow \det Dg(x) \neq 0 \forall x \in U \therefore \text{sign } |\det Dg(x)| = +1 \text{ or } -1 \text{ all } x \in U$  "ε"

Now  $g := \beta^{-1} \circ \alpha \Rightarrow \alpha = \beta \circ g$ . Set  $\eta := \beta^* \omega$ .

Then  $g^* \eta = g^* \beta^* \omega = (\beta^{-1} \circ \alpha)^* \beta^* \omega = [\beta \circ (\beta^{-1} \circ \alpha)]^* \omega = \alpha^* \omega$

≠ So:  $\eta = \beta^* \omega \Rightarrow g^* \eta = \alpha^* \omega$

Thus:  $\int_U \alpha^* \omega \stackrel{?}{=} \int_a^b \beta^* \omega \Leftrightarrow \int_U g^* \eta \stackrel{?}{=} \int_a^b \eta$

Now:  $\eta = f dy_1 \wedge \dots \wedge dy_k \Rightarrow g^* \eta = (f \circ g) g^*(dy_1 \wedge \dots \wedge dy_k)$   
 $= (f \circ g) \det Dg(x) dx_1 \wedge \dots \wedge dx_k$

Thus:  $\int_U g^* \eta \stackrel{?}{=} \int_a^b \eta \Leftrightarrow \int_U (f \circ g)(x) \det Dg(x) dx_1 \dots dx_k$   
 $\stackrel{?}{=} \int_a^b f(y) dy_1 \dots dy_k$

$\Leftrightarrow \int_U (f \circ g)(x) \underbrace{\det Dg(x)}_{= |\det Dg(x)|} dx_1 \dots dx_k \stackrel{?}{=} \int_a^b f(y) dy_1 \dots dy_k$

↑  
 which is true by C.V.F.  
 (change of var. form.)  
 for Riemann integrals in  $\mathbb{R}^k$  □

Case 3: •  $M$  cpct oriented  $k$ -mfd in  $\mathbb{R}^n$

•  $\omega \in \mathcal{L}^k(W)$   $\exists W$  open in  $\mathbb{R}^n$ , s.t.  $M \subset W$  i.e.

$$|\omega| = \sum_{\substack{[I]_k \\ \text{cl}(I) \rightarrow M}} a_I(y) dy_I \quad \exists a_I: W \rightarrow \mathbb{R}$$

Def:  $\text{supp } \omega := \bigcup_{[I]_k} \text{supp } a_I$ ;  $C = M \cap \text{supp } \omega$  (cpct subset of  $\mathbb{R}^n$ )

• Suppose  $\exists$  single coord. chart:  $(U, \alpha, V)$  belonging  
 (connected)  
 to the orientation of  $M$  s.t.  $C \subset V$

Def:  $\int_M \omega \& := \int_{\text{Int } U} \alpha^* \omega$  provided latter exists as Riemannian  
 integral in  $\mathbb{R}^k$   
 (recall:  $U$  is open in  $\mathbb{R}^k$  or in  $\mathbb{H}^k$ )

Remarks: • Def of  $\int_M \omega$  is indep. of choice of coord. chart  
 in orientation of  $M$  (previous lemma with  $\varepsilon = \pm 1$ )

• Def of  $\int_M \omega$  is linear: if  $\omega$  &  $\eta$  are supported in single coord. chart

$(U, \alpha, V)$ , then  $\int_M aw + b\eta = a \int_M w + b \int_M \eta$  (linearity of  $\alpha^*$   
linearity of Riem. integral)

• if  $-M := M$  with reversed orient., then  $\int_{-M} w = - \int_M w$ .

Case 4:

- $M$  cpct oriented  $k$ -mfd in  $\mathbb{R}^n$
- $w \in \mathcal{L}^k(W) \exists W \subset \mathbb{R}^n$  open,  $M \subset W$
- cover  $M$  by coord. charts  $\{U_\alpha, \alpha, V_\alpha\}$ ,  $V_\alpha = \alpha(U_\alpha) = W_\alpha \cap M$ ,  
 $\exists W_\alpha$  open in  $\mathbb{R}^n$
- ie.  $\det D(\beta^{-1} \circ \alpha)(x) > 0 \quad \forall x \in U_\alpha$
- choose partition of unity  $\varphi_1, \dots, \varphi_k$  on  $M$  that is dominated by  $\{U_\alpha\}$

Recall:  $\varphi_i : \mathbb{R}^n \rightarrow \mathbb{R}$  s.t. (1)  $\varphi_i(x) \geq 0 \quad \forall x \in \mathbb{R}^n$   
(2)  $(\text{Supp } \varphi_i) \cap M \subset V_i$   
(3)  $\sum_{i=1}^k \varphi_i(x) = 1 \quad \forall x \in M$

Def:  $\int_M w := \sum_{i=1}^k \int_M (\varphi_i w)$  (\*)

Remarks:

- $w_i := \varphi_i w$  is supported in single coord. chart:  $(U_i, \alpha_i, V_i)$ ,  
so rhs of (\*) is defined as in Case 3.
- def of  $\int_M w$  is indep. of choice of partition of unity
- $\int_M aw + b\eta = a \int_M w + b \int_M \eta$
- $\int_{-M} w = - \int_M w$

Thm: (Computation of  $\int_M w$  via tiling)

- Ⓐ  $M$  cpct oriented  $k$ -mfd in  $\mathbb{R}^n \quad \{V_1, \dots, V_N, K\}$  is a tiling of  
 $M$  by coord. charts that belong to orientation for  $M$ , ie.
- $\{U_i, \alpha_i, V_i\}_{i=1, \dots, N}$  are coord. charts belong. to orient. of  $M$

- $V_i \cap V_j = \emptyset \quad V_i \neq j$
- $M = V_1 \cup \dots \cup V_N \cup K$
- $K$  has zero meas. in  $M$  (ie,  $\alpha^{-1}(K)$  has zero meas. in  $\mathbb{R}^n \quad \forall$  coord charts  $\alpha$ )

©  $\int_M \omega = \sum_{i=1}^N \int_{U_i} \alpha_i^* \omega$   
 Case 2

Stokes Thm

• a thm about integrals of  $k$ -forms over cpct, orientable  $k$ -mfolds  $M$  in  $\mathbb{R}^n$ , that includes all thms of vector calculus ( $n=2$  or  $n=3$ ) as special case.

• We begin with a special case:  $M = \underbrace{[0,1]^k}_{=I^k}$  in  $\mathbb{R}^k$

$I^k = \underbrace{[0,1]}_{I_1} \times \dots \times \underbrace{[0,1]}_{I_k}$   $k$  times

$\text{Int}(I^k) = (0,1)^k = (0,1) \times \dots \times (0,1)$

$b(I^k) = I^k \setminus \text{Int}(I^k) = \bigcup_{j=1}^k I_1 \times \dots \times I_{j-1} \times \underbrace{b I_j}_{[0,1]} \times I_{j+1} \times \dots \times I_k$



Lemma: (Stokes' for  $M=I^k$ )

©  $\eta \in \Lambda^{k-1}(\mathbb{R}^k) \exists W$  open subset of  $\mathbb{R}^k$  s.t.  $I^k \subset W$  s.t.  $\eta|_A = 0$   
 $\forall x \in b(I^k)$  except possibly in  $(0,1)^{k-1} \times \{0\}$



©  $\int_{(0,1)^k} d\eta = (-1)^k \int_{(0,1)^{k-1}} i^* \eta$ , where  $i$  is the inclusion map:  $i: (0,1)^{k-1} \rightarrow (0,1)^k$

via  $i(u_1, \dots, u_{k-1}) = (u_1, \dots, u_{k-1}, 0)$ .



Notation: •  $u$  is general pt in  $\mathbb{R}^{k-1}$

•  $x_1, \dots, x_k \in \mathbb{R}^k$

•  $\forall j \in \{1, \dots, k\}$  let  $j' = (1, 2, \dots, j-1, j+1, \dots, k)$   
 $= (1, 2, \dots, \hat{j}, \dots, k)$

• elementary  $(k-1)$ -forms in  $\mathbb{R}^k$ :  $dx_{j'} = dx_1 \wedge \dots \wedge dx_{j-1} \wedge dx_{j+1} \wedge \dots \wedge dx_k$

Pf: by linearity of  $\int_W \cdot$ ;  $d$ ;  $i^*$ ; enough to consider case

when  $\eta = f dx_{j'}$ ,  $j' \in \{1, \dots, k\}$ ,  $f: W \rightarrow \mathbb{R}$ .

Step 1a: • Compute  $d\eta$ :

$$d\eta = d(f dx_{j'}) = df \wedge dx_{j'} = \sum_{l=1}^k \frac{\partial f}{\partial x_l} dx_l \wedge dx_{j'}$$

$$= \frac{\partial f}{\partial x_j} \underbrace{dx_{j'} \wedge dx_1 \wedge dx_2 \wedge \dots \wedge dx_{j-1} \wedge dx_{j+1} \wedge \dots \wedge dx_k}_{(j-1)\text{-many "jumps"}}$$

$$\Rightarrow d(f dx_{j'}) = (-1)^{j-1} \frac{\partial f}{\partial x_j} dx_1 \wedge \dots \wedge dx_k$$

Step 1b: Compute  $\int_{(0,1)^k} d\eta = (-1)^{j-1} \int_{(0,1)^k} \frac{\partial f}{\partial x_j} dx_1 \wedge \dots \wedge dx_k$

Case 1 in def  $\int_W$

$$(-1)^{j-1} \int_{(0,1)^k} \frac{\partial f}{\partial x_j} dx_1 \wedge \dots \wedge dx_k = (-1)^{j-1} \int_{(0,1)^{k-1}} \left( \int_0^1 \frac{\partial f}{\partial x_j} dx_j \right) dx_1 \wedge \dots \wedge dx_{j-1} \wedge dx_{j+1} \wedge \dots \wedge dx_k$$

// FTC fund. thm. Calc

$$= \begin{cases} 0 & \text{if } j < k \\ (-1)^k \int_{(0,1)^{k-1}} (f \circ i) dx_1 \wedge \dots \wedge dx_{k-1} & \text{if } j = k \end{cases}$$

(H)  $\neq 0 \Leftrightarrow j = k$

Thus: for  $f = \eta dx_{j'}$   $\forall j' \in \{1, \dots, k\}$  we have:

$$\int_{(0,1)^k} d\eta = \begin{cases} 0 & \text{if } j < k \\ (-1)^k \int_{(0,1)^{k-1}} (f \circ i) dx_1 \wedge \dots \wedge dx_{k-1} & \text{if } j = k \end{cases} \quad (1)$$

Step 2a: Compute  $i^*(f dx_{j'}) = (f \circ i) i^*(dx_{j'})$

recall.  $i: \mathbb{R}^{k-1} \rightarrow \mathbb{R}^k$ ,  $(u_1, \dots, u_{k-1}) \rightarrow (u_1, \dots, u_{k-1}, 0)$  has

Jacobian  $\underbrace{D_i(u)}_{\in \mathbb{R}^{k \times (k-1)}} = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & 0 \end{pmatrix}$  so:  $i^*(dx_j) = \det(D_i)_{j, \cdot} du_1 \wedge \dots \wedge du_{k-1}$

&  $\det(D_i)_{j, \cdot} = \begin{cases} 0 & j \neq k \\ 1 & j = k \end{cases}$  (picks  $(k-1)$ -minor that have a zero row)

So:  $i^*(\eta) = i^*(f dx_j) = \begin{cases} 0 & j \neq k \\ (f_i(u) du_1 \wedge \dots \wedge du_{k-1}) & j = k \end{cases}$

$\int_{(0,1)^{k-1}} i^* \eta = \begin{cases} 0 & \text{if } j \neq k \\ \int_{(0,1)^{k-1}} (f_i) & \text{if } j = k. \end{cases} \quad (2)$

Conclusion: Comparing (1) & (2) we obtain for  $\eta = f dx_j$ ,  $\forall j=1 \rightarrow k$ :

$\int_{(0,1)^k} d\eta \stackrel{(1)}{=} 0 \stackrel{(2)}{=} (-1)^k \int_{(0,1)^{k-1}} i^* \eta$  if  $j \neq k$

$\int_{(0,1)^k} d\eta \stackrel{(1)}{=} (-1)^k \int_{(0,1)^{k-1}} (f_i) \stackrel{(2)}{=} (-1)^k \int_{(0,1)^{k-1}} i^* \eta$  if  $j = k$ .

Thus:  $\int_{(0,1)^k} d\eta = (-1)^k \int_{(0,1)^{k-1}} i^* \eta.$  □

Nov 2

Stokes Thm

Ⓐ  $k \geq 2$ ,  $M$  is a cpt oriented  $k$ -mfld in  $\mathbb{R}^n$ . If  $bM \neq \emptyset$ , give  $bM$  orientation induced by  $M$  (induced orient.)

$w \in \wedge^{k-1}(\mathbb{R}^n)$ ,  $W$  open set in  $\mathbb{R}^n$  s.t.  $M \subset W$ .

ⓐ  $\int_M dw = \begin{cases} \int_{bM} w & \text{if } bM \neq \emptyset \\ 0 & \text{if } bM = \emptyset \end{cases}$

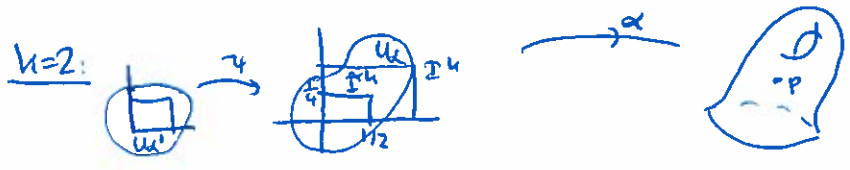
Pf: Let  $\{U_\alpha, \alpha, V_\alpha\}$  be an atlas for  $M$  in orient of  $M$

Step 1: Augment atlas by including suitably built coord. charts, which overlap positively.

Let  $p \in M = (M \setminus bM) \cup bM$ .

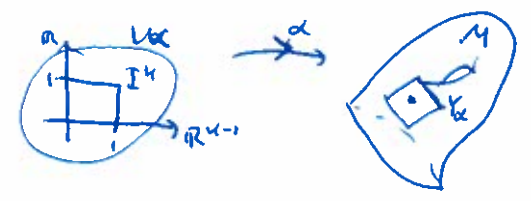
Case 1:  $p \in M \setminus bM$  (this will be only case if  $bM = \emptyset$ )

Choose  $(U_\alpha, \alpha, V_\alpha)$  coord chart about  $p$  s.t.  $U_\alpha$  open in  $\mathbb{R}^k$ , and contains  $I^k = [0,1]^k$  & s.t.  $\alpha^{-1}(p) \in (0,1)^k = \text{int}(I^k)$   
 (always achievable via translation & rescaling in  $\mathbb{R}^k$ )  
 See picture



Def  $\gamma: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  rescaling fitted to  $I^2$   
 $(v_1, v_2) \rightarrow (\frac{1}{2}v_1, \frac{1}{4}v_2)$  ("rescaling")  
 $U_\alpha' = \gamma^{-1}(U_\alpha)$   
 & consider  $\tilde{\alpha} := \alpha \circ \gamma$  instead.

Set:  $Y_\alpha := \alpha([0,1]^k) = \alpha(\text{int}(I^k))$ .



Then: restriction of  $\alpha$  to  $(0,1)^k$ , that is:

$\{(0,1)^k, \alpha, Y_\alpha\}$  is also a coord chart in the orient. of  $M$ .

with  $\tilde{U}_\alpha := (0,1)^k$  open in  $\mathbb{R}^k$ , & by construction  $\alpha$  extends to an open nbhd of  $(0,1)^k$  (namely  $U_\alpha$ ).

Case 2:  $p \in bM$ . Choose  $\{U_\alpha, \alpha, V_\alpha\}$  from atlas belonging to orientation of  $M$

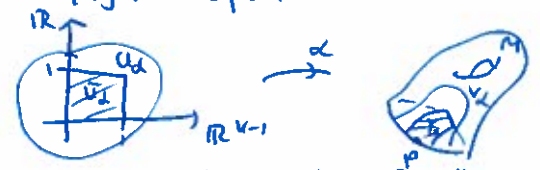
s.t.  $U_\alpha$  is open in  $\mathbb{H}^k$  ( $\therefore U_\alpha = \mathbb{H}^k \cap (\text{open set } \tilde{U}$  in  $\mathbb{R}^k$ )

contains  $I^k = [0,1]^k$  (again: achievable via transl. & rescaling)

& s.t.  $\alpha^{-1}(p) \in (0,1)^{k-1} \times \{0\}$ .

Def:  $\tilde{U}_\alpha = (0,1)^k \cup ((0,1)^{k-1} \times \{0\})$  open in  $\mathbb{H}^k$  (not in  $\mathbb{R}^k$ ),  $Y_\alpha = \alpha(\tilde{U}_\alpha)$

See picture:



Then restriction of  $\alpha$  to  $\tilde{U}_\alpha$  is a coord chart for  $M$  about  $p \in bM$  that belongs to orient. of  $M$  with  $\tilde{U}_\alpha$  open in  $\mathbb{H}^k$  but not in  $\mathbb{R}^k$ .



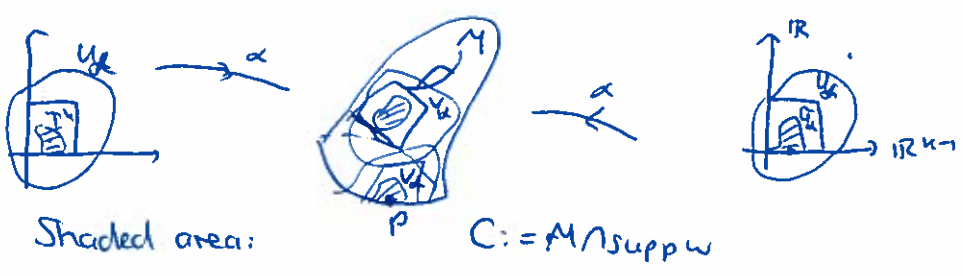
In the sequel, we will <sup>work</sup> exclusively with these special charts

$$\{(0,1)^k, \alpha, Y_\alpha\}, p \in \text{Int } M \quad \& \quad \{(0,1)^{k-1} \times \{0\}, \alpha, Y_\alpha\} \text{ if } p \in bM.$$

Step 2: by linearity of "d" & of  $\int dw$  enough to prove ③ in case when  
 $C := M \cap \text{Supp } w \subset Y_\alpha = \begin{cases} \alpha(I^k) & , p \in \text{Int } M \\ \alpha((0,1)^{k-1} \times \{0\}) \cup ((0,1)^{k-1} \times \{0\}) & , p \in bM \end{cases}$

(image of a single chart  $\alpha$ )

(Say not,  $C \subset Y_\alpha \cup Y_\beta$ , say. Then  $w = \frac{\rho_\alpha w}{w_\alpha} + \frac{\rho_\beta w}{w_\beta}$  for a part of unity  $\{\rho_\alpha, \rho_\beta\}$  dominated by  $\{Y_\alpha, Y_\beta\}$   
 $Y_\alpha \cap Y_\beta \neq \emptyset$   
 $C_\alpha := M \cap \text{Supp } w_\alpha$   
 $C_\beta := M \cap \text{Supp } w_\beta$   
 $\& dw = dw_\alpha + dw_\beta$  so  $\int_M dw = \int_M dw_\alpha + \int_M dw_\beta$ )



Def:  $\eta := \alpha^* w \in \mathcal{L}^{k-1}(\mathbb{R}^k)$  Then:

- $\eta$  extends to  $U_\alpha$  open in  $\mathbb{R}^k \cong I^k = [0,1]^k$
- $\eta(x) = 0 \forall x \in b(I^k)$  except possibly for points in  $(0,1)^{k-1} \times \{0\}$ .

Thus  $\eta$  satisfies all hypotheses of lemma.

Step 3: Let  $w$  &  $\eta$  as in Step 2. We prove ③

Case 1:  $bM \neq \emptyset$ . Then ③ needs  $\int_M dw = 0$ .

Note that if  $bM = \emptyset$ ,  $M$  is covered by charts of type Case 1 in Step 1.

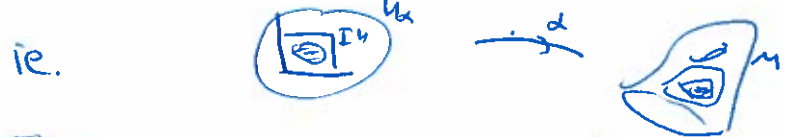
Then: 
$$\int_M dw = \int_{(0,1)^k} \alpha^*(dw) \stackrel{\alpha^*d = d\alpha^*}{=} \int_{(0,1)^k} d(\alpha^*w) \stackrel{\eta = \alpha^*w}{=} \int_{(0,1)^k} d(\eta)$$

Lemma = 
$$(-1)^k \int_{(0,1)^{k-1}} i^* \eta = 0$$

Case 1:  $i^* \eta = 0$  on  $(0,1)^{k-1}$ . Thus:  $\int_M dw = 0$  done.

Case 2:  $bM \neq \emptyset$ . Then ③ needs:  $\int_M dw = \int_{bM} w$ .

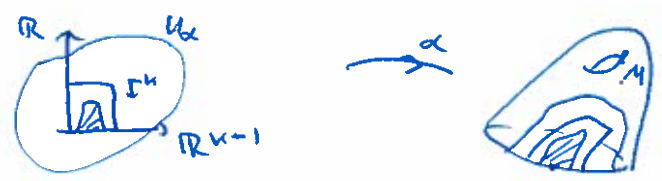
Case 2a:  $w$  supported in a chart  $\alpha$  st.  $Y_\alpha \subset \text{Int } M$ .



Then, proceeding as in Case 1 we get  $\int_M dw = 0$ . But also

$\int_{bM} dw = 0$  as well, b/c in Case 2a:  $\text{Supp } w \cap bM = \emptyset \therefore w|_p = 0 \forall p \in bM$

Case 2b:  $w$  supported in a chart  $\alpha$  as in Case 2 of Step 1



Recall:  $\tilde{U}_\alpha = (0,1)^k \cup ((0,1)^{k-1} \times \{0\})$   
open in  $\mathbb{R}^k$ , but not open in  $\mathbb{R}^k$

Computing as before,  $\int_M dw = \int_{(0,1)^k} \alpha^* dw = \int_{(0,1)^k} d(\alpha^* w) = \int_{(0,1)^k} dz$

Lemma  $= (-1)^k \int_{(0,1)^{k-1}} i^{\otimes k} z$

Thus:  $\int_M dw = (-1)^k \int_{(0,1)^{k-1}} i^{\otimes k} z, z = \alpha^* w$  (1)

Next: Compute  $\int_{bM} w$ . Now:  $\text{Supp } w \cap bM$  is covered by the following chart for  $bM$ :  $\beta := \alpha \circ i: (0,1)^{k-1} \rightarrow Y_\alpha \cap bM$   
& recall that if  $k$  even then  $\beta$  belongs to induced orient. of  $bM$ , or else if  $k$  odd,  $\beta$  belongs to opposite of induced orient. of  $M$ .

Thus:  $\int_{bM} w \alpha = \begin{cases} \int_{(0,1)^{k-1}} \beta^* w & \text{if } k \text{ is even} \\ - \int_{(0,1)^{k-1}} \beta^* w & \text{if } k \text{ odd} \end{cases}$  That is:  $\int_{bM} w = (-1)^k \int_{(0,1)^{k-1}} \beta^* w$

But:  $\beta^* w = (\alpha \circ i)^* w \stackrel{\text{prop of pullback}}{=} i^* \alpha^* w = i^* z$ . So:

$\int_{bM} w = (-1)^k \int_{(0,1)^{k-1}} i^* z$  all  $k$  (2) & recall:  $\int_M dw = (-1)^k \int_{(0,1)^{k-1}} i^* z$  (1)

Comparing (1) & (2) get:  $\int_M dw = \int_{bM} w$ . □

Complex Manifolds

Let  $N = 2k, n \geq k$ .

Def  $M$  is a complex  $k$ -mfd in  $\mathbb{C}^n$  if it is a

$2k$ -mfd in  $\mathbb{R}^{2k}$  s.t.  $\forall$  atlas  $\{U_i, \alpha_i, V_i\}$ , then coord.

charts "overlap holomorphically" i.e.:

if  $\alpha_1: U_1 \subset \mathbb{R}^{2k} \rightarrow V_1$  &  $\alpha_2: U_2 \subset \mathbb{R}^{2k} \rightarrow V_2$  are two charts with  $V_1 \cap V_2 \neq \emptyset$

then the transition map:  $\varphi: \alpha_2^{-1} \circ \alpha_1: \alpha_1^{-1}(V_1 \cap V_2) \rightarrow \alpha_2^{-1}(V_1 \cap V_2)$   
!!  $D$  open set in  $U_1 \subset \mathbb{R}^{2k}$       !!  $W$  open in  $U_2 \subset \mathbb{R}^{2k}$

is a holomorphic map of open sets  $\mathbb{C}^k$  under the natural identification of  $\mathbb{R}^{2k}$  with  $\mathbb{C}^k$ .

$$(x_1, y_1, x_2, y_2, \dots, x_k, y_k) \rightarrow (z_1, \dots, z_k), z_j = x_j + iy_j$$

$$\varphi: D \subset \mathbb{C}^k \rightarrow W \subset \mathbb{C}^k$$

$$(z_1, \dots, z_k) \mapsto (w_1, \dots, w_k), w_j = \varphi_j(z_1, \dots, z_k)$$

holomorphic map means:  $\forall j=1, \dots, k$   $\varphi_j$  holomorphic fct:  $D \rightarrow \mathbb{C}$

That is,  $\varphi_j = u_j + iv_j$ ;  $\forall j=1, \dots, k$  & we require that  $u_j$  &  $v_j$  satisfy

the Cauchy-Riemann eqn's:  $(CR) \begin{cases} \frac{\partial u_j}{\partial x_l} = \frac{\partial v_j}{\partial y_l} \\ \frac{\partial u_j}{\partial y_l} = -\frac{\partial v_j}{\partial x_l} \end{cases} \quad \forall l=1, \dots, k, \forall j=1, \dots, k$

Alternate formulation of CR:

Def:  $\frac{\partial}{\partial z_l} := \frac{1}{2} \left( \frac{\partial}{\partial x_l} + i \frac{\partial}{\partial y_l} \right)$   
 $\frac{\partial}{\partial \bar{z}_l} := \frac{1}{2} \left( \frac{\partial}{\partial x_l} - i \frac{\partial}{\partial y_l} \right)$

Lemma 0:

- (H)  $\varphi_j = u_j + iv_j$
- (C)  $\varphi_j$  satisfies (CR)  $\Leftrightarrow \frac{\partial \varphi_j}{\partial \bar{z}_l} \equiv 0 \quad \forall l=1, \dots, k.$

Pf:  $\frac{\partial \varphi_j}{\partial \bar{z}_l} = \frac{\partial u_j}{\partial x_l} + i \frac{\partial v_j}{\partial x_l} = \frac{1}{2} \left\{ \left( \frac{\partial u_j}{\partial x_l} + \frac{\partial u_j}{\partial x_l} \right) + i \left( \frac{\partial v_j}{\partial x_l} - \frac{\partial v_j}{\partial x_l} \right) \right\}$

$$= \frac{1}{2} \left\{ \left( \frac{\partial u_j}{\partial x_L} - \frac{\partial v_j}{\partial y_L} \right) + i \left( \frac{\partial v_j}{\partial x_L} + \frac{\partial u_j}{\partial y_L} \right) \right\} = \frac{\partial \psi_j}{\partial \bar{z}_L}$$

So:  $\frac{\partial \psi_j}{\partial \bar{z}_L} = 0 \Leftrightarrow \operatorname{Re} \left( \frac{\partial \psi_j}{\partial \bar{z}_L} \right) = 0 \Leftrightarrow \text{CR1}$   
 $\operatorname{Im} \left( \frac{\partial \psi_j}{\partial \bar{z}_L} \right) = 0$  □

Lemma 1:  $\frac{\partial \psi_j}{\partial \bar{z}_L} = 0 \Leftrightarrow \frac{\partial \psi_j}{\partial z_L} = \frac{\partial \psi_j}{\partial x_L}$ .

Pf: 
$$\begin{cases} \frac{\partial \psi_j}{\partial \bar{z}_L} = \frac{1}{2} \left( \frac{\partial \psi_j}{\partial x_L} - i \frac{\partial \psi_j}{\partial y_L} \right) \\ + \frac{\partial \psi_j}{\partial z_L} = \frac{1}{2} \left( \frac{\partial \psi_j}{\partial x_L} + i \frac{\partial \psi_j}{\partial y_L} \right) \end{cases}$$

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$$\frac{\partial \psi_j}{\partial \bar{z}_L} + \frac{\partial \psi_j}{\partial z_L} = \frac{\partial \psi_j}{\partial x_L}, \text{ so } \frac{\partial \psi_j}{\partial \bar{z}_L} = 0 \Leftrightarrow \frac{\partial \psi_j}{\partial z_L} = \frac{\partial \psi_j}{\partial x_L}. \quad \square$$

Lemma 2: For any  $\psi_j = u_j + i v_j$ ,

(a)  $\frac{\partial \overline{\psi_j}}{\partial z_L} = \overline{\frac{\partial \psi_j}{\partial \bar{z}_L}}$ ; (b)  $\frac{\partial \psi_j}{\partial \bar{z}_L} = \overline{\left( \frac{\partial \overline{\psi_j}}{\partial z_L} \right)}$

Pf: (a) Note that (b) is (a) applied to  $\overline{\psi_j}$ .

(a) 
$$\frac{\partial \psi_j}{\partial z_L} = \frac{\partial u_j}{\partial x_L} + i \frac{\partial v_j}{\partial x_L} = \frac{1}{2} \left[ \frac{\partial u_j}{\partial x_L} + i \frac{\partial u_j}{\partial y_L} \right] + \frac{i}{2} \left[ \frac{\partial v_j}{\partial x_L} + i \frac{\partial v_j}{\partial y_L} \right]$$

$$= \frac{1}{2} \left[ \left( \frac{\partial u_j}{\partial x_L} + \frac{\partial v_j}{\partial y_L} \right) - i \left( \frac{\partial u_j}{\partial y_L} - \frac{\partial v_j}{\partial x_L} \right) \right].$$

Thus: 
$$\frac{\partial \overline{\psi_j}}{\partial z_L} = \frac{1}{2} \left[ \left( \frac{\partial u_j}{\partial x_L} + \frac{\partial v_j}{\partial y_L} \right) + i \left( \frac{\partial u_j}{\partial y_L} - \frac{\partial v_j}{\partial x_L} \right) \right]. \quad (*)$$

Next: 
$$\frac{\partial \overline{\psi_j}}{\partial \bar{z}_L} = \frac{\partial u_j}{\partial \bar{z}_L} - i \frac{\partial v_j}{\partial \bar{z}_L} = \frac{1}{2} \left[ \frac{\partial u_j}{\partial x_L} - i \frac{\partial u_j}{\partial y_L} \right] - \frac{i}{2} \left[ \frac{\partial v_j}{\partial x_L} - i \frac{\partial v_j}{\partial y_L} \right]$$

$$= \frac{1}{2} \left[ \left( \frac{\partial u_j}{\partial x_L} + \frac{\partial v_j}{\partial y_L} \right) + i \left( \frac{\partial u_j}{\partial y_L} - \frac{\partial v_j}{\partial x_L} \right) \right] \quad (**)$$

Compare (\*) and (\*\*). □

Lemma 3: (H)  $\frac{\partial \psi_j}{\partial \bar{z}_L} = 0$   
 (C)  $\frac{\partial \overline{\psi_j}}{\partial x_L} = \overline{\frac{\partial \psi_j}{\partial \bar{z}_L}}$

Pf:  $\overline{\frac{\partial \varphi_j}{\partial z_k}} \stackrel{\text{Lemma 1}}{=} \frac{\partial \varphi_j}{\partial \bar{z}_k} \quad (*)$

But  $\frac{\partial \varphi_j}{\partial x_k} = \frac{\partial u_j}{\partial x_k} + i \frac{\partial v_j}{\partial x_k} = \frac{\partial u_j}{\partial x_k} - i \frac{\partial v_j}{\partial x_k} = \frac{\partial \varphi_j}{\partial x_k} \quad (**)$

All together:  $\frac{\partial \varphi_j}{\partial x_k} = \frac{\partial \varphi_j}{\partial x_k} = \frac{\partial \varphi_j}{\partial \bar{z}_k} \quad \square$

Def: Complex Jacobian matrix of  $\varphi$  at  $a \in D$ :

$$D^c \varphi(a) := \begin{bmatrix} \frac{\partial \varphi_1}{\partial z_1}(a), & \dots, & \frac{\partial \varphi_1}{\partial z_n}(a) \\ \vdots & & \vdots \\ \frac{\partial \varphi_n}{\partial z_1}(a), & \dots, & \frac{\partial \varphi_n}{\partial z_n}(a) \end{bmatrix} \in \mathbb{C}^{k \times k}$$

Lemma 4: (H)  $\varphi = (\varphi_1, \dots, \varphi_n) : D \subseteq \mathbb{C}^n \rightarrow W \subseteq \mathbb{C}^k$  is a holom. map

Let  $D\varphi(a)$  be the (real) Jacobian matrix of  $\varphi$  at  $a \in D$ .

(C)  $\det D\varphi(a) = |\det D^c \varphi(a)|^2 \quad !!$

Pf: Writing  $\varphi_j = u_j + i v_j$  (omit  $(a)$ ):

$$D\varphi = \begin{bmatrix} \frac{\partial u_1}{\partial x_1}, \frac{\partial u_1}{\partial x_2}, \dots, \frac{\partial u_1}{\partial x_n} \\ \frac{\partial v_1}{\partial x_1}, \frac{\partial v_1}{\partial x_2}, \dots, \frac{\partial v_1}{\partial x_n} \\ \vdots \\ \frac{\partial u_n}{\partial x_1}, \frac{\partial u_n}{\partial x_2}, \dots, \frac{\partial u_n}{\partial x_n} \\ \frac{\partial v_n}{\partial x_1}, \frac{\partial v_n}{\partial x_2}, \dots, \frac{\partial v_n}{\partial x_n} \end{bmatrix}$$

After a permutation of rows <sup>columns</sup> we may re-write:

$$\det D\varphi = \det \begin{bmatrix} \frac{\partial u_j}{\partial x_1} & \frac{\partial u_j}{\partial x_k} \\ \vdots & \vdots \\ \frac{\partial v_i}{\partial x_1} & \frac{\partial v_i}{\partial x_k} \end{bmatrix} \stackrel{\text{CR}}{=} \det \begin{bmatrix} \frac{\partial u_j}{\partial x_1} + i \frac{\partial v_i}{\partial x_1} & \frac{\partial u_j}{\partial x_k} + i \frac{\partial v_i}{\partial x_k} \\ \vdots & \vdots \\ \frac{\partial v_i}{\partial x_1} & \frac{\partial v_i}{\partial x_k} \end{bmatrix} \stackrel{\text{CR}}{=} \det \begin{bmatrix} \frac{\partial u_j}{\partial x_1} + i \frac{\partial v_i}{\partial x_1} & \frac{\partial u_j}{\partial x_k} + i \frac{\partial v_i}{\partial x_k} \\ \vdots & \vdots \\ \frac{\partial v_i}{\partial x_1} & \frac{\partial v_i}{\partial x_k} \end{bmatrix}$$

$\frac{\partial u_j}{\partial x_k} + i \frac{\partial v_i}{\partial x_k} = \frac{\partial u_j + i v_i}{\partial x_k}$   
 $\frac{\partial v_i}{\partial x_k} = \frac{\partial v_i + i \frac{\partial u_j}{\partial x_k}}{\partial x_k}$

subtract  
 (left rows)  
 from corresp.  
 right  
 columns

$$\det \left[ \begin{array}{c|c} \frac{\partial \varphi_j}{\partial z_i} + i \frac{\partial \varphi_j}{\partial \bar{z}_i} & 0 \\ \hline \frac{\partial \varphi_j}{\partial z_i} & \frac{\partial \varphi_j}{\partial z_i} - i \frac{\partial \varphi_j}{\partial \bar{z}_i} \end{array} \right] = \det \left[ \begin{array}{c|c} \frac{\partial \varphi_j}{\partial z_i} & 0 \\ \hline \frac{\partial \varphi_j}{\partial z_i} & \frac{\partial \varphi_j}{\partial z_i} \end{array} \right]$$

Lemma 12.3

=

$$\det \left[ \begin{array}{c|c} \frac{\partial \varphi_j}{\partial z_i} & 0 \\ \hline \frac{\partial \varphi_j}{\partial z_i} & \frac{\partial \varphi_j}{\partial z_i} \end{array} \right]$$

$$\text{So: } \det D\varphi = \det \left[ \begin{array}{c|c} D^{\mathbb{R}}\varphi & 0 \\ \hline \frac{\partial \varphi_j}{\partial z_i} & \overline{D^{\mathbb{R}}\varphi} \end{array} \right] = \det(D^{\mathbb{R}}\varphi) \det(\overline{D^{\mathbb{R}}\varphi})$$

$$= \det(D^{\mathbb{R}}\varphi) \overline{\det(D^{\mathbb{R}}\varphi)} = |\det D^{\mathbb{R}}\varphi|^2$$

□

We have proved that  $\det D\varphi = |\det D^{\mathbb{R}}\varphi|^2$  (if  $\varphi$  has holom.

components)

Coroll. 1:

- (H)  $M$  is a complex  $k$ -mfd in  $\mathbb{C}^n$
- (C)  $M$  is orientable.

Coroll. 2:

- (H)  $M$  is a cplx  $k$ -mfd in  $\mathbb{C}^n$
- (C)  $\forall$  transition map  $\varphi$  we have:

$$\det D^{\mathbb{R}}\varphi(a) \neq 0 \quad \forall a \in \text{domain of } \varphi$$

Corollary 3:

- (H)  $M$  is a complex  $k$ -mfd in  $\mathbb{C}^n$
- (C) any trans. map  $\varphi$  is a biholomorphism of open sets in  $\mathbb{C}^n$ .

Pf: Coroll. 2 + Complex implicit funct. thm

Stokes' Thm in 1 cplx variable

Recall:  $f(x+iy) = \underset{\text{Re } f}{u(x,y)} + i \underset{\text{Im } f}{v(x,y)}$ ,  $(x,y) \in D \subseteq \mathbb{C}$   
← domain

Def:  $f$  analytic at  $z \in D$  if following lim exists:

$$\lim_{h \rightarrow 0} \frac{f(z+h) - f(z)}{h} = f'(z)$$

" $f \in A(D)$ "



Thm 1:  $f \in A(D) \Leftrightarrow \begin{cases} u_x = v_y \\ u_y = -v_x \end{cases} \quad \forall (x,y) \in D$  &  $f'(z) = u_x + i v_x$

Def:  $z := x+iy$ ,  $\bar{z} := x-iy$ . then:  $T: (x,y) \rightarrow (z, \bar{z})$  is a coord. change in sense that  $T$  invertible & inverse is:

$$U: (z, \bar{z}) \rightarrow \left( \frac{z+\bar{z}}{2}, \frac{z-\bar{z}}{2i} \right) =: (x,y)$$

By Chain Rule:

$$\frac{\partial f}{\partial z} = f_x \cdot \frac{\partial x}{\partial z} + f_y \frac{\partial y}{\partial z} = \frac{1}{2}(f_x + i f_y)$$

$$\frac{\partial f}{\partial \bar{z}} = f_x \frac{\partial x}{\partial \bar{z}} + f_y \frac{\partial y}{\partial \bar{z}} = \frac{1}{2}(f_x - i f_y)$$

Thm 2:  $f \in A(D) \Leftrightarrow \frac{\partial f}{\partial \bar{z}}(z, \bar{z}) = 0$  in  $D$ .

Pf:  $\frac{\partial f}{\partial \bar{z}} = \frac{\partial u}{\partial \bar{z}} + i \frac{\partial v}{\partial \bar{z}} = \frac{1}{2} \{ [u_x + i u_y] + i [v_x + i v_y] \} = \frac{1}{2} \{ (u_x - v_y) + i(u_y + v_x) \}$

$$\text{So: } \begin{cases} \text{Re } \frac{\partial f}{\partial \bar{z}} = 0 \Leftrightarrow \text{CR I} = 0 \\ \text{Im } \frac{\partial f}{\partial \bar{z}} = 0 \Leftrightarrow \text{CR II} = 0 \end{cases} \Leftrightarrow \text{Thm 1} \Leftrightarrow f \in A(D)$$

Def:  $\frac{\partial f}{\partial \bar{z}} = 0$  "CR eqn's in complex form"

Thm 3: (H)  $f \in A(D)$   
 (C)  $f'(z) = \frac{\partial f}{\partial z}(z)$  in  $D$ .

Pf:  $\frac{\partial f}{\partial z} = \frac{\partial u}{\partial z} + i \frac{\partial v}{\partial z} = \frac{1}{2} [ (u_x - i u_y) + i (v_x - i v_y) ] \stackrel{\text{CR}}{=} \frac{1}{2} [ (u_x + i v_x) + (v_y - i u_y) ]$   
 $\stackrel{\text{Thm 1}}{=} u_x + i v_x = f'(z)$

Thm: (properties of  $\frac{\partial}{\partial z}$  &  $\frac{\partial}{\partial \bar{z}}$ ):

• linearity:  $\frac{\partial}{\partial z} (af + bg) = a \frac{\partial f}{\partial z} + b \frac{\partial g}{\partial z}$

$\frac{\partial}{\partial \bar{z}} ( \quad ) = \dots$

• Leibniz:  $\frac{\partial}{\partial z} (fg) = g \frac{\partial f}{\partial z} + f \frac{\partial g}{\partial z}$

$\frac{\partial}{\partial \bar{z}} ( \dots ) = \dots$

•  $\frac{\partial f}{\partial \bar{z}} = \overline{\frac{\partial f}{\partial z}}$  ;  $\frac{\partial f}{\partial z} = \overline{\frac{\partial f}{\partial \bar{z}}}$

Differential forms in  $\mathbb{C}$  cplx notation

$\mathbb{R}^2$ : Elementary 1-forms :  $dx, dy$   
                  - 2-forms :  $dx \wedge dy$

$\mathbb{C}$ : Elementary 1-forms :  $dz = dx + idy =: \text{"type (1,0)"}$   
                                   $d\bar{z} = dx - idy =: \text{"type (0,1)"}$

2-forms:  $dz \wedge d\bar{z} = (dx + idy) \wedge (dx - idy)$   
 $= i dy \wedge dx - i dx \wedge dy$   
 $= -2i dx \wedge dy$

Notes:  $dz \wedge dz = 0$  (check!)  
 $d\bar{z} \wedge d\bar{z} = 0$      -  
 $d\bar{z} \wedge dz = -dz \wedge d\bar{z}$  (check!)

Forms of type (0,0) = forms of degree 0 =  $f(z, \bar{z})$ .

type (1,0):  $\omega = f(z, \bar{z}) dz$   
type (0,1):  $\omega = f(z, \bar{z}) d\bar{z}$   
type (1,1):  $\omega = f(z, \bar{z}) dz \wedge d\bar{z}$ .

Exterior derivative in cplx form

Recall: (d for  $\mathbb{R}^2$ ):  $\Lambda^0(V) \xrightarrow{d} \Lambda^1(V) \xrightarrow{d} \Lambda^2(V) \xrightarrow{d} \{0\}$ .

Def:  $\partial: \Lambda^{(p,0)}(V) \xrightarrow{\partial} \Lambda^{(p+1,0)}(V) \xrightarrow{\partial} \{0\}$ ;  $\bar{\partial}: \Lambda^{(0,q)}(V) \xrightarrow{\bar{\partial}} \Lambda^{(0,q+1)}(V)$   
 $\bar{\partial}: \Lambda^{(p,0)}(V) \xrightarrow{\bar{\partial}} \Lambda^{(p,1)}(V) \xrightarrow{\bar{\partial}} \{0\}$ ;  $\partial: \Lambda^{(0,q)}(V) \xrightarrow{\partial} \Lambda^{(1,q)}(V)$ .



via:

$$(0,0): \partial f = \frac{\partial f}{\partial z} dz$$

$$(1,0): \partial(f dz) := \partial f \wedge dz = \frac{\partial f}{\partial z} \underbrace{dz \wedge dz}_{=0} = 0$$

$$(0,1): \partial(f d\bar{z}) := \partial f \wedge d\bar{z} = \frac{\partial f}{\partial z} dz \wedge d\bar{z}$$

$$(1,1): \partial(f dz \wedge d\bar{z}) := \partial f \wedge dz \wedge d\bar{z} = 0 \wedge dz = 0$$

$$(0,0): \bar{\partial} f := \frac{\partial f}{\partial \bar{z}} d\bar{z}$$

$$(1,0): \bar{\partial}(f dz) := \bar{\partial} f \wedge dz = \frac{\partial f}{\partial \bar{z}} d\bar{z} \wedge dz$$

$$(0,1): \bar{\partial}(f d\bar{z}) := \bar{\partial} f \wedge d\bar{z} = 0$$

$$(1,1):$$

Corollary:  $f \in A(n) \Leftrightarrow \bar{\partial} f = 0.$

Coroll:  $\partial^2 = 0, \bar{\partial}^2 = 0$

Pf: (0,0):  $f \quad \partial f = \frac{\partial f}{\partial z} dz, \quad \partial(\partial f) = \left(\partial\left(\frac{\partial f}{\partial z}\right)\right) \wedge dz$   
 $= f_{zz} \underbrace{dz \wedge dz}_{=0}$

So:  $\partial^2 f = 0$  if  $f \in \mathcal{L}^{0,0}$

(1,0):  $f dz, \quad \partial(f dz) = 0, \quad \partial^2(f dz) = \partial(0) = 0.$

etc. ... □

Thm:  $d = \partial + \bar{\partial}$  (any degree / type)

Aside:  $f \in \mathcal{L}^{(0,0)}$

$$\frac{\partial f}{\partial z} = f_z = \frac{1}{2}(f_x - i f_y)$$

$$\frac{\partial f}{\partial \bar{z}} = f_{\bar{z}} = \frac{1}{2}(f_x + i f_y)$$

Thus:  $f_x = f_z + f_{\bar{z}} \tag{1}$

$-i f_y = f_z - f_{\bar{z}} \rightarrow f_y = i(f_z - f_{\bar{z}}) \tag{2}$

Pf of Thm: degree zero:  $df = f_x dx + f_y dy \stackrel{(1),(2)}{=} (f_z + f_{\bar{z}}) \frac{1}{2}(dz + d\bar{z}) + i(f_z - f_{\bar{z}}) \frac{1}{2i}(dz - d\bar{z})$

$$= \frac{1}{2} \left\{ (f_z dz + f_{\bar{z}} d\bar{z} + \cancel{f_z d\bar{z}} + \cancel{f_{\bar{z}} dz}) + (f_z dz + f_{\bar{z}} d\bar{z} - \cancel{f_{\bar{z}} dz} - \cancel{f_z d\bar{z}}) \right\}$$

$$= \partial f + \bar{\partial} f.$$

• degree 1:  $w = f dx + g dy$

$$dw = df \wedge dx + dg \wedge dy \stackrel{f, g \text{ have degree } 0}{=} (\partial f + \bar{\partial} f) \wedge \frac{1}{2}(dz + d\bar{z}) + (\partial g + \bar{\partial} g) \wedge \frac{1}{2i}(dz - d\bar{z})$$

$$(1) \quad dw = \frac{1}{2} \{ f_z + ig_z \} dz \wedge d\bar{z} + \frac{1}{2} \{ -f_{\bar{z}} + ig_{\bar{z}} \} d\bar{z} \wedge dz$$

On the other hand:

$$w = f dx + g dy = f \cdot \frac{1}{2}(dz + d\bar{z}) + g \frac{1}{2i}(dz - d\bar{z})$$

$$\Rightarrow \partial w = \frac{1}{2} \{ \partial f \wedge (dz + d\bar{z}) - i \partial g \wedge (dz - d\bar{z}) \}$$

$$\stackrel{\text{degree } 0}{=} \frac{1}{2} \{ f_z dz \wedge d\bar{z} + ig_z d\bar{z} \wedge dz \} = \frac{1}{2} \{ f_z + ig_z \} dz \wedge d\bar{z} \quad (2)$$

$$\text{Similarly: } \bar{\partial} w = \dots \Rightarrow \bar{\partial} w = \frac{1}{2} \{ -f_{\bar{z}} + ig_{\bar{z}} \} d\bar{z} \wedge dz \quad (3)$$

$$\text{Notice that: } \begin{matrix} (1) = (2) + (3) \\ dw = \partial w + \bar{\partial} w \end{matrix} \quad \therefore dw = \partial w + \bar{\partial} w. \quad \#$$

• degree 2: ...

### Stokes in one cplx vble

(\*)  $\int_{\partial D} w = \int_D dw$   $\forall w \in \mathcal{A}$  with coeff. of class  $C^1(D) \cap C(\bar{D})$   
 $\& \mathcal{A}$  sufficiently regular bounded open set  $D$ .

(a) type (1,0):  $w = f dz$  for  $f \in C^1(D) \cap C(\bar{D})$

$$(*) \text{ reads: } \int_{\partial D} f dz = \int_D \bar{\partial} f \wedge dz = \int_D f_{\bar{z}} d\bar{z} \wedge dz.$$

$\uparrow$   
 $d = \partial + \bar{\partial}, \bar{\partial}(f dz) = 0$

(b) type (0,1):  $w = f d\bar{z}$ ,  $f \in C^1(D) \cap C(\bar{D})$  &

$$(*) \Rightarrow \int_{\partial D} f d\bar{z} = \int_D \partial f \wedge d\bar{z} = - \int_D f_z d\bar{z} \wedge dz.$$

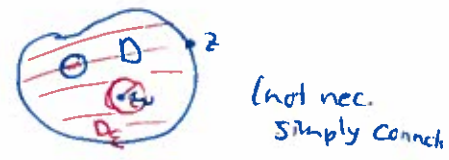
Corollary: Cauchy-Thm: (H)  $f \in A(D) \cap C(\bar{D})$   
 (C)  $\int_{\partial D} f dz = 0$

Pf: Stokes formulation (a):  $\omega = f dz$  [(1,0)-form]

$\hookrightarrow d\omega = \underbrace{\bar{\partial} f}_{=0} \wedge dz$  b/c  $f \in A(D)$ .

Corollary: Cauchy formula for analytic functs.

(H)  $g \in A(D) \cap C(\bar{D})$   
 (C)  $\forall w \in D, g(w) = \frac{1}{2\pi i} \int_{\partial D} \frac{g(z)}{z-w} dz$



Pf: Let  $\epsilon_0 > 0$  s.t.  $\overline{D_\epsilon(w)} \subset D \forall 0 < \epsilon < \epsilon_0$

Def:  $D_\epsilon := D \setminus \overline{D_\epsilon(w)}$

def:  $f(z) := \frac{1}{2\pi i} \frac{g(z)}{z-w} \in A(D_\epsilon) \forall \epsilon > 0$

By Cauchy Thm (applied to  $f$  on  $D_\epsilon$ ) get:

$0 = \frac{1}{2\pi i} \int_{\partial D_\epsilon} \frac{g(z)}{z-w} dz = \frac{1}{2\pi i} \int_{\partial D} \frac{g(z)}{z-w} dz - \frac{1}{2\pi i} \int_{\partial D_\epsilon(w)} \frac{g(z)}{z-w} dz$

So:  $\frac{1}{2\pi i} \int_{\partial D} \frac{g(z)}{z-w} dz = \underbrace{\frac{1}{2\pi i} \int_{\partial D_\epsilon(w)} \frac{g(z)}{z-w} dz}_{I_\epsilon(w)} \forall \epsilon > 0.$

Now:

$I_\epsilon(w) = \int_{z=w+\epsilon e^{i\theta}} \frac{g(z)}{z-w} dz = \int_{\theta=0}^{2\pi} \frac{g(w+\epsilon e^{i\theta})}{\epsilon e^{i\theta}} i\epsilon e^{i\theta} d\theta$

$= \frac{1}{2\pi} \int_0^{2\pi} g(w+\epsilon e^{i\theta}) d\theta = \frac{1}{2\pi} \int_0^{2\pi} (g(w+\epsilon e^{i\theta}) - g(w)) d\theta + g(w)$

But  $g \in A(D) \Rightarrow g \in C(\overline{D_\epsilon(w)})$  & we conclude that

$$\lim_{\epsilon \rightarrow 0} I_{\epsilon}(w) = g(w) + \frac{1}{2\pi i} \int_0^{2\pi} \underbrace{\lim_{\epsilon \rightarrow 0} (g(w) + \epsilon e^{i\theta} - g(w))}_{=0} d\theta$$


All together:  $\frac{1}{2\pi i} \int_{\partial D} \frac{g(z)}{z-w} dz = g(w)$ .  $\square$

Remark: in proving that  $\lim_{\epsilon \rightarrow 0} I_{\epsilon} = g(w)$  we only used the fact that  $g \in C(\overline{D_{\epsilon}(w)})$  (we did not use  $g \in A(D)$ ).

Corollary: Pompeiu (also generalized Cauchy) formula for  $C'(D) \cap C(\bar{D})$ .

(H)  $g \in C'(D) \cap C(\bar{D})$

(C)  $\forall w \in D, g(w) = \frac{1}{2\pi i} \int_{\partial D} \frac{g(z)}{z-w} dz - \frac{1}{\pi^2} \int_D \frac{g_{\bar{z}}(z, \bar{z})}{z-w} dx dy$

Pf:   $w = \frac{1}{2\pi i} \int_{\partial D_{\epsilon}} \frac{g(z)}{z-w} dz \in A'(D_{\epsilon}) \quad \forall \epsilon > 0$

Stokes  $\Rightarrow \frac{1}{2\pi i} \int_{\partial D_{\epsilon}} \frac{g(z)}{z-w} dz = \frac{1}{2\pi i} \int_{D_{\epsilon}} dz \left( \frac{g(z)}{z-w} \right) \wedge dz$

$d = \partial + \bar{\partial}$  ok...  $\frac{1}{2\pi i} \int_{D_{\epsilon}} \bar{\partial}_z \left( \frac{g(z)}{z-w} \right) \wedge dz = \text{Leibniz} \wedge \frac{1}{z-w} \in A(D_{\epsilon})$

$= \frac{1}{2\pi i} \int_{D_{\epsilon}} \frac{1}{z-w} \partial_{\bar{z}} g(z) \wedge dz = \frac{1}{2\pi i} \int_{D_{\epsilon}} \frac{1}{z-w} g_{\bar{z}}(z, \bar{z}) \frac{d\bar{z} \wedge dz}{z dx + i dy}$

So:  $\frac{1}{2\pi i} \int_{\partial D_{\epsilon}} \frac{g(z)}{z-w} dz = \frac{1}{\pi} \int_{D_{\epsilon}} \frac{1}{z-w} g_{\bar{z}}(z, \bar{z}) dx dy$

But  $\frac{1}{z-w}$  is absolutely integrable at  $w$  in  $D$

$\int_{D, (w)} \frac{1}{|z-w|} dx dy = \text{Polar coord's} \int_0^{2\pi} \int_0^1 \frac{1}{r} r dr d\theta < \infty$

So:  $\int_{D_{\epsilon}} \frac{g_{\bar{z}}}{z-w} dx dy \xrightarrow{\epsilon \rightarrow 0} \int_{z \in D} \frac{g_{\bar{z}}}{z-w} dx dy$

All together:  $\int_{\partial D} \frac{g(z)}{z-w} dz = \int_{D} \frac{g_{\bar{z}}}{z-w} dx dy$

$$\int_{\partial D} \equiv \left( \underbrace{-\int_{\partial D_\varepsilon(w)} \frac{g(z)}{z-w} dz}_{\Gamma_\varepsilon(w)} = \right) \downarrow$$

$$\int_{\partial D} \frac{g(z)}{z-w} dz \quad -g(w) = \int_D \frac{g_z}{z-w} dx dy$$

D

Nov 14

### Stokes' Thm in SCV

several cplx variables

#### Preliminaries:

$$\mathbb{R}^{2n} = \{ (x_1, y_1, x_2, y_2, \dots, x_n, y_n) \} = \{ (x_1, x_2, \dots, x_{2n}) \}$$

$$\mathbb{C}^n: z_j := x_j + iy_j, \quad j=1, \dots, n$$

$$\text{alt.: } z_j := x_{2j-1} + ix_{2j}, \quad j=1, \dots, n$$

$$z_j := x_j + ix_{j+n}, \quad j=1, \dots, n$$

Consequently,  $x_j := \frac{1}{2}(z_j + \bar{z}_j)$  (alt.:  $x_{2j-1} = \frac{1}{2}(z_j + \bar{z}_j)$ )  
 $y_j := \frac{1}{2i}(z_j - \bar{z}_j)$   $x_{2j} = \frac{1}{2i}(z_j - \bar{z}_j)$

Given  $f: D \rightarrow \mathbb{C}$ ,

$$\text{def.: } \frac{\partial f}{\partial z_j} = \frac{1}{2} \left( \frac{\partial f}{\partial x_j} - i \frac{\partial f}{\partial y_j} \right)$$

$$\frac{\partial f}{\partial \bar{z}_j} = \frac{1}{2} \left( \frac{\partial f}{\partial x_j} + i \frac{\partial f}{\partial y_j} \right)$$

Def:  $f$  is holomorphic in  $D$  ("analytic" :  $n=1$ ) iff  $\frac{\partial f}{\partial \bar{z}_j} \equiv 0$  in  $D \forall j=1, \dots, n$

Notation:  $f \in \mathcal{O}(D)$

- Differential forms in cplx notation: "degree"
- Elementary 1-forms in  $\mathbb{R}^{2n}$ :  $dx_j, dy_j, \quad j=1, \dots, n$

In  $\mathbb{C}^{2n}$ :  $dz_j = dx_j + i dy_j$  ;  $d\bar{z}_j = dx_j - i dy_j$  ,  $j=1 \rightarrow n$   
 $\uparrow$   $\uparrow$   
 type (1,0) type (0,1)

- Elementary 2-forms in  $\mathbb{R}^{2n}$  :  $dx_j \wedge dx_l$  ;  $dx_j \wedge dy_l$  ;  $dy_j \wedge dy_l$   
 in  $\mathbb{C}^{2n}$ :  $dz_j \wedge dz_l$  ,  $dz_j \wedge d\bar{z}_l$  ,  $d\bar{z}_j \wedge d\bar{z}_l$   
 type 2,0                      1,1                      0,2

Given  $p, q \in \{0, 1, 2, \dots, n\}$ :  

$$\begin{matrix} I = (i_1, i_2, \dots, i_p) \\ J = (j_1, j_2, \dots, j_q) \end{matrix} \left. \vphantom{\begin{matrix} I \\ J \end{matrix}} \right\} \begin{matrix} \text{ascending labels} \\ \text{in } \{1, \dots, n\} \end{matrix}$$

Elem. (p,0) - forms:  $dz_I = dz_{i_1} \wedge dz_{i_2} \wedge \dots \wedge dz_{i_p}$

Fact:  $dz_i \wedge dz_i = 0$

Elem. (0,q) - forms:  $d\bar{z}_J = d\bar{z}_{j_1} \wedge d\bar{z}_{j_2} \wedge \dots \wedge d\bar{z}_{j_q}$

(again:  $d\bar{z}_j \wedge d\bar{z}_j = 0$  all  $j$ )

Elem. (p,q) - forms:  $dz_I \wedge d\bar{z}_J = dz_{i_1} \wedge \dots \wedge dz_{i_p} \wedge d\bar{z}_{j_1} \wedge \dots \wedge d\bar{z}_{j_q}$   
 degree  $r = p+q$

General form type (p,q):  $\omega = \sum_{\substack{[I]_p \\ [J]_q}} a_{IJ} dz_I d\bar{z}_J$

$a_{IJ} : \mathbb{C} \rightarrow \mathbb{C}$

Notation:  $\mathcal{L}^{p,q}(\mathbb{C}^n)$  ;  $\mathcal{L}^r(\mathbb{R}^{2n})$  ,  $p, q \in \{0, \dots, n\}$  ,  $r \in \{0, \dots, 2n\}$

Fact:  $\mathcal{L}^r(\mathbb{C}^n) = \bigoplus_{p+q=r} \mathcal{L}^{p,q}(\mathbb{C}^n)$   
 $\uparrow$   $\uparrow$   
 $\mathbb{R}^{2n}$   $\mathbb{C}^n$   
 $z_j = x_j + i y_j$   
 $\uparrow$   
 $\vec{c} \in \mathbb{R}^{2n}$

Functions:  $f : \mathbb{C}^n \rightarrow \mathbb{C} : \mathcal{L}^{0,0}(\mathbb{C}^n)$

Def:  $\omega \in \mathcal{L}^{p,q} \rightsquigarrow \bar{\omega} \in \mathcal{L}^{p,q}$ ,

$$\begin{aligned} & \downarrow \\ & \sum_{\substack{[I]_p \\ [J]_q}} a_{I\bar{J}} dz_I \wedge d\bar{z}_J \quad \rightsquigarrow \bar{\omega} = \sum_{\substack{[I]_p \\ [J]_q}} \bar{a}_{I\bar{J}} d\bar{z}_I \wedge dz_J \end{aligned}$$

Extend derivative in cplx form:

•  $r=0, f \in \mathcal{L}^{0,0}$

$$\partial f := \sum_{i=1}^n \frac{\partial f}{\partial z_i} dz_i \in \mathcal{L}^{1,0}$$

$$\bar{\partial} f := \sum_{j=1}^n \frac{\partial f}{\partial \bar{z}_j} d\bar{z}_j \in \mathcal{L}^{0,1}$$

Note:  $f \in \mathcal{O}(D) \Leftrightarrow \bar{\partial} f = 0$ .

•  $r \in \{1, \dots, 2n\}$

•  $q \in \{0, \dots, n\}$

$$\partial: \{0\} \hookrightarrow \mathcal{L}^{0,q}(D) \rightarrow \mathcal{L}^{1,q}(D) \rightarrow \dots \rightarrow \mathcal{L}^{p,q}(D) \rightarrow \mathcal{L}^{p+1,q} \rightarrow \dots \rightarrow \mathcal{L}^{n,q} \rightarrow \{0\}$$

$$\partial \left( \sum a_{I\bar{J}} dz_I \wedge d\bar{z}_J \right) = \sum \left( \partial a_{I\bar{J}} \right) \wedge dz_I \wedge d\bar{z}_J$$

↑  
def for  $r=0$

•  $p \in \{0, \dots, n\}$

$$\bar{\partial}: \{0\} \hookrightarrow \mathcal{L}^{p,0}(D) \xrightarrow{\bar{\partial}} \mathcal{L}^{p,1} \rightarrow \dots \rightarrow \mathcal{L}^{p,q} \rightarrow \mathcal{L}^{p,q+1} \rightarrow \dots \rightarrow \mathcal{L}^{p,n} \rightarrow \{0\}$$

$$\bar{\partial} \left( \sum a_{I\bar{J}} dz_I \wedge d\bar{z}_J \right) = \sum \left( \bar{\partial} a_{I\bar{J}} \right) \wedge dz_I \wedge d\bar{z}_J$$

Thm: (H)  $d = \text{exterior derivative for } \mathbb{R}^{2n}$

(C)  $d = \partial + \bar{\partial}$   $\left( d \left( \sum a_{I\bar{J}} dz_I \wedge d\bar{z}_J \right) = \sum \left( \partial a_{I\bar{J}} + \bar{\partial} a_{I\bar{J}} \right) \wedge dz_I \wedge d\bar{z}_J \right)$

$$\partial \circ \partial = 0; \quad \bar{\partial} \circ \bar{\partial} = 0; \quad (\partial \circ \bar{\partial} + \bar{\partial} \circ \partial) = 0$$

Furthermore,  $\partial$  &  $\bar{\partial}$  commute with pull-back under holomorphic

maps  $F: \mathbb{C}^n \rightarrow \mathbb{C}^n$ .

• Volume form for  $\mathbb{R}^{2n}$

$$dV = dx_1 \wedge dy_1 \wedge \dots \wedge dx_n \wedge dy_n$$

$$= \left(\frac{i}{2}\right)^n dz_1 \wedge d\bar{z}_1 \wedge \dots \wedge dz_n \wedge d\bar{z}_n$$

$$= \frac{1}{n!} \left(\frac{i}{2}\right)^n \sum_{j=1}^n dz_j \wedge d\bar{z}_j \wedge \dots$$

$$= \frac{(-1)^{\frac{n(n-1)}{2}}}{(2i)^n} dz_1 \wedge \dots \wedge d\bar{z}_n \wedge dz_1 \wedge \dots \wedge dz_n$$

• Inner product of forms:  $\omega = \sum a_{IJ} dz_I \wedge d\bar{z}_J$

(same type (p,q))

$$\eta = \sum b_{IJ} dz_I \wedge d\bar{z}_J$$

$$\langle \omega, \eta \rangle_{\mathbb{C}^n} = \sum_{\substack{[I]_p \\ [J]_q}} a_{IJ} \overline{b_{IJ}} / |I|, |J| \in \mathbb{N}$$

$$(\omega, \eta)_0 = \int_{\mathbb{C}^n} \langle \omega, \eta \rangle_{\mathbb{C}^n} dV$$

provided this integral makes sense

Thm (Hodge \* operator for  $\mathbb{R}^{2n} \cong \mathbb{C}^n$ ): There is a !  $\mathbb{C}$ -linear map  $*$ ,

s.t.  $\forall r \in \{0, \dots, 2n\}$ :

$$*: \Lambda^r(\mathbb{C}^n) \rightarrow \Lambda^{2n-r}(\mathbb{C}^n)$$

$$*(\bar{\varphi}) = \overline{* \varphi}$$

$$** \varphi = (-1)^{2n-r} \varphi$$

$$*1 = dV, \quad *dV = 1$$

$$(\varphi, * \bar{\varphi})_{\mathbb{C}^n} = \langle \varphi, \varphi \rangle dV \quad \forall \varphi, \bar{\varphi} \in \Lambda^r$$

Furthermore, in  $\mathbb{C}^n \cong \mathbb{R}^{2n}$ :

$$*: \Lambda^{p,q} \rightarrow \Lambda^{n-q, n-p}$$

$$** \varphi = (-1)^{p+q} \varphi \quad \forall \varphi \in \Lambda^{p,q}$$

$$* \underbrace{dz_j}_{\in \Lambda^{1,0}} = \frac{(-1)^{\frac{q(q-1)}{2}}}{2^{n-q} i^n} dz_j \wedge \left( \bigwedge_{\substack{J' \in J \\ J' \neq \{j\}}} d\bar{z}_{J'} \wedge dz_{J'} \right)$$



e.g. in  $\mathbb{C}^3$ ,  $q=2$ ,  $J=(1,3)$   
 $J'=(2)$

$q=1$ ,  $J=(2)$ ,  $J'=(1,3)$

Stokes' Thm for  $D \subseteq \mathbb{C}^n$

Recall from last time (Stokes' Thm for  $D \subseteq \mathbb{C}$ ):

Stokes' Thm: (H)  $D \subseteq \mathbb{C}$  (bdd, smooth)  
 $j: \partial D \hookrightarrow \mathbb{C}$   
 $f \in C^1(\partial D) \cap C(\bar{D})$

(C) (a)  $\int_{\partial D} j^*(f dz) = \int_D \bar{\partial} f \lrcorner dz$

(b)  $\int_{\partial D} j^*(f d\bar{z}) = \int_D \partial f \lrcorner d\bar{z}$

Corollary: (Cauchy-Riemann formula):

(H)  $g \in C^1(\partial D) \cap C(\bar{D})$



(C)  $g(w) = \frac{1}{2\pi i} \int_{\partial D} j^*(g(z) j^*(\frac{dz}{z-w})) - \frac{1}{2\pi i} \int_D \bar{\partial} g \lrcorner \frac{dz}{z-w}$

In particular, if  $g \in A(D) \cap C(\bar{D})$ , then:

$g(w) = \frac{1}{2\pi i} \int_{z \in \partial D} j^*(g(z) j^*(\frac{dz}{z-w})) \quad \forall w \in D$

Def:  $\frac{1}{2\pi i} j^*(\frac{dz}{z-w}) =: \text{Cauchy kernel for } D \text{ at } w \in D$

Q: Is there an analog of Cauchy-Riemann & Cauchy formula for  $D \subseteq \mathbb{C}^n$ ,  $n \geq 1$ ?

Stokes in  $\mathbb{R}^{2n}$ :  $\int_{\partial D} j^* \omega = \int_D d\omega \quad \forall \omega \in \mathcal{L}^{2n-1}(\mathbb{R}^{2n})$

Now:  $\mathcal{L}^{2n-1} = \bigoplus_{p+q=2n-1} \mathcal{L}^{p,q} = \mathcal{L}^{n,n-1} \oplus \mathcal{L}^{n-1,n}$   
 $p, q \in \{0, 1, \dots, n\}$

Short hand:  $dz_N = dz, \wedge \dots \wedge dt_n$

$$d\bar{z}_N = d\bar{z}, \wedge \dots \wedge d\bar{t}_n$$

$$\omega = \sum_{j=1}^n a_j dz_N \wedge d\bar{z}_j, \quad \omega = \sum_{j=1}^n b_j dz_j \wedge d\bar{z}_N$$

(a) (b)

$$a_j, b_j: \mathbb{R}^{2n} (\text{or } \mathbb{C}^n) \rightarrow \mathbb{C}$$

$$(a) d\omega = (\partial + \bar{\partial})\omega = \bar{\partial}\omega = \sum_j \bar{\partial} a_j \wedge dz_N \wedge d\bar{z}_j$$

$$(b) d\omega = (\partial + \bar{\partial})\omega = \partial\omega = \sum_j \partial b_j \wedge dz_j \wedge d\bar{z}_N$$

Stokes in cplx form for  $D \subseteq \mathbb{C}^n$ :

$$(H) \quad \omega \in \mathcal{L}^{2n-1}(D)$$

$$(a) \quad (\omega \in \mathcal{L}^{n,n-1}): \quad \int_{\partial D} j^{\mathbb{R}} \omega = \sum_j \int_D \bar{\partial} a_j \wedge dz_N \wedge d\bar{z}_j$$

$$\omega = \sum_j a_j dz_N \wedge d\bar{z}_j$$

$$(b) \quad (\omega \in \mathcal{L}^{n+1,n}): \quad \int_{\partial D} j^{\mathbb{R}} \omega = \sum_i \int_D \partial b_i \wedge dz_i \wedge d\bar{z}_N$$

$$\omega = \sum_i b_i dz_i \wedge d\bar{z}_N$$

Q: Cauchy-Pompeiu for  $D \subseteq \mathbb{C}^n$ ?

Back to  $n=1$ : Cauchy kernel:  $j^{\mathbb{R}} \left( \frac{dz}{z-w} \right)$

Now, if  $z \in \mathbb{C}^n$  then  $\frac{1}{z} = ??$

However, note that if  $z, w \in \mathbb{C} (n=1)$ : rewrite:  $\frac{1}{z-w} = \frac{\bar{z}-\bar{w}}{|w-z|^2}$

meaningful in any dimension!

$n \geq 2$ : Def:  $\beta(z, w) := |w-z|^2 = |z_1-w_1|^2 + \dots + |z_n-w_n|^2$   
 $= (z_1-w_1)(\overline{z_1-w_1}) + \dots + (z_n-w_n)(\overline{z_n-w_n})$ .

Def: Bochner-Martinelli kernel  $K_0(z, w)$   
 1943, Ann. Math      1938, Mem. R. Accad. Italia

$K_0(z, w) := \frac{(n-2)!}{2\pi^n} \left( - * \underbrace{\partial_z \beta^{1-n}}_{\mathcal{L}^{1,0}} \right) \quad \forall w \in \mathbb{C}^n, z \in \mathbb{C}^n \setminus \{w\}$   
 $\mathcal{L}^{n, n-1}$

Lemma:  $K_0(z, w) = \frac{1}{(2\pi i)^n} \underbrace{\frac{\partial \beta}{\beta}}_{\mathcal{L}^{1,0}} \wedge \left[ \bar{\partial} \left( \frac{\partial \beta}{\beta} \right) \right]^{n-1}$   
 $\mathcal{L}^{1,0} \wedge (\mathcal{L}^{1,1})^{n-1} = \mathcal{L}^{n-1, n-1}$

Pf: omitted.

Remark:  $n=1$ :  $K_0(z, w) = \frac{1}{2\pi i} \frac{\partial \beta}{\beta} = \frac{1}{2\pi i} \frac{\partial(|w-z|^2)}{|w-z|^2}$   
 $= \frac{1}{2\pi i} \frac{\partial(|z-w|(\overline{z-w}))}{|w-z|^2} = \frac{1}{2\pi i} \frac{dz(\overline{z-w}) + (z-w)0}{|z-w|^2}$   
 $= \frac{1}{2\pi i} \frac{(\overline{z-w})}{|z-w|^2} dz = \frac{1}{2\pi i} \frac{dz}{z-w} \quad \checkmark$

So:  $n=1$  BM = Cauchy  $\checkmark$

too lazy and late to write sth down :P